

1. (24 points) Note that parts c and d of this problem are on the next page.  
Consider the second-order equation

$$\frac{d^2y}{dt^2} + 4\frac{dy}{dt} + 20y = -5 \cos 5t.$$

- (a) What can you say about the long-term behavior of solutions without solving for the general solution? Be as specific as possible.

The equation is damped and sinusoidally forced  $\Rightarrow$  all solutions tend to the steady-state solution. That solution has angular frequency  $= 5 \Rightarrow$  period  $= \frac{2\pi}{5}$ .

- (b) Determine a particular solution to this differential equation.

Complexify:  $\frac{d^2y}{dt^2} + 4\frac{dy}{dt} + 20y = -5e^{(5i)t}$

Guess  $y_c(t) = a e^{(5i)t}$

We get

$$a((5i)^2 + 4(5i) + 20)e^{(5i)t} \stackrel{(5i)t}{=} -5e^{(5i)t}$$

$$a(-25 + 20i + 20)e^{(5i)t} \stackrel{(5i)t}{=} -5e^{(5i)t}$$

$$\Rightarrow a = \frac{-5}{-5 + 20i} = \frac{1}{1-4i} \frac{(1+4i)}{(1+4i)} = \frac{1+4i}{17}$$

For a solution to the original equation,

we take

$$y_p(t) = \operatorname{Re}(ae^{(5i)t})$$

$$= \operatorname{Re}\left(\frac{1+4i}{17}(cos 5t + i sin 5t)\right)$$

$$= \left(\frac{1}{17}\right) cos 5t - \left(\frac{4}{17}\right) sin 5t$$

1. (continued) Here is the differential equation from the previous page:

$$\frac{d^2y}{dt^2} + 4\frac{dy}{dt} + 20y = -5 \cos 5t.$$

- (c) Find the general solution to this differential equation.

The characteristic polynomial is  $\lambda^2 + 4\lambda + 20$ .

$$\text{We get } \lambda = \frac{-4 \pm \sqrt{16 - 80}}{2} = -2 \pm 4i$$

The general solution to the equation is

$$y(t) = c_1 e^{-2t} \cos 4t + c_2 e^{-2t} \sin 4t \\ + \left(\frac{1}{17}\right) \cos 5t - \left(\frac{4}{17}\right) \sin 5t$$

- (d) What can you say about the long-term behavior of the solutions given your results from parts b and c? Be as specific as possible.

The amplitude of the steady-state is

$$|a| = \frac{1}{17} |1+4i| = \frac{\sqrt{17}}{17} = \frac{1}{\sqrt{17}}$$

The phase angle of the steady-state

is given by  $\tan \theta = 4$ . It is

approximately  $104^\circ$ .

The exponential rate of approach to the

steady-state is determined by the real

part of the eigenvalue, which is  $-2$ .

2. (16 points) For what values of  $a, b, c$ , and  $d$  is the linear system

$$\frac{d\mathbf{Y}}{dt} = \begin{pmatrix} a & b \\ c & d \end{pmatrix} \mathbf{Y}$$

Hamiltonian? Calculate a Hamiltonian function for these values.

We want  $H(x, y)$  such that

$$\frac{dx}{dt} = ax + by = \frac{\partial H}{\partial y}$$

$$\frac{dy}{dt} = cx + dy = -\frac{\partial H}{\partial x}.$$

Therefore, we want

$$\frac{\partial(ax+by)}{\partial x} = -\frac{\partial(cx+dy)}{\partial y}$$

$$\Rightarrow a = -d.$$

In this case, our system becomes

$$\frac{dx}{dt} = ax + by$$

$$\frac{dy}{dt} = cx - ay.$$

$$\begin{aligned} \text{To compute } H(x, y) &= \int (ax+by) dy + \varphi(x) \\ &= axy + b \frac{y^2}{2} + \varphi(x). \end{aligned}$$

$$\begin{aligned} \text{Then } cx - ay &= -(ay + \varphi'(x)) \Rightarrow \varphi'(x) = -cx \\ &\Rightarrow \varphi(x) = -c \frac{x^2}{2} \end{aligned}$$

$$\text{We have } H(x, y) = \frac{by^2}{2} + axy - \frac{cx^2}{2}.$$

3. (20 points) Note that part c of this problem is on the next page.

(a) Calculate  $\mathcal{L}^{-1} \left[ \frac{2s+5}{s^2+2s+3} \right]$ .

$$\frac{2s+5}{(s+1)^2+2} = \frac{2(s+1)}{(s+1)^2+2} + \frac{3}{(s+1)^2+2}$$

$$\mathcal{L}^{-1} \left[ \frac{2s+5}{s^2+2s+3} \right] = 2e^{-t} \cos \sqrt{2}t + \frac{3}{\sqrt{2}} e^{-t} \sin \sqrt{2}t$$

(b) Calculate the Laplace transform  $\mathcal{L}[y]$  for the solution  $y(t)$  to the initial-value problem

$$\frac{d^2y}{dt^2} + 2\frac{dy}{dt} + 3y = \delta_4(t), \quad y(0) = 2, \quad y'(0) = 1.$$

DO NOT CALCULATE A FORMULA FOR  $y(t)$  HERE.

$$(s^2 \mathcal{L}[y] - 2s - 1) + 2(s \mathcal{L}[y] - 2) + 3 \mathcal{L}[y] = e^{-4s}$$

$$(s^2 + 2s + 3) \mathcal{L}[y] = 2s + 5 + e^{-4s}$$

$$\mathcal{L}[y] = \frac{2s+5}{s^2+2s+3} + \frac{e^{-4s}}{s^2+2s+3}$$

3. (continued)

(c) Calculate the solution  $y(t)$  to the initial-value problem in part b.

$$\mathcal{L}^{-1} \left[ \frac{1}{s^2 + 2s + 3} \right] = \mathcal{L}^{-1} \left[ \frac{1}{(s+1)^2 + 2} \right] = \frac{1}{\sqrt{2}} e^{-t} \sin \sqrt{2}t$$

$$\Rightarrow \mathcal{L}^{-1} \left[ \frac{e^{-4s}}{s^2 + 2s + 3} \right] = \frac{1}{\sqrt{2}} u_4(t) e^{-(t-4)} \sin \sqrt{2}(t-4)$$

We obtain the solution

$$y(t) = 2e^{-t} \cos \sqrt{2}t + \frac{3}{\sqrt{2}} e^{-t} \sin \sqrt{2}t \\ + \frac{1}{\sqrt{2}} u_4(t) e^{-(t-4)} \sin \sqrt{2}(t-4)$$

4. (16 points) Consider the one-parameter family of linear systems

$$\frac{d\mathbf{Y}}{dt} = \begin{pmatrix} a & 1 \\ a & a \end{pmatrix} \mathbf{Y}.$$

- (a) Sketch the curve in the trace-determinant plane that is obtained by varying the parameter  $a$ .

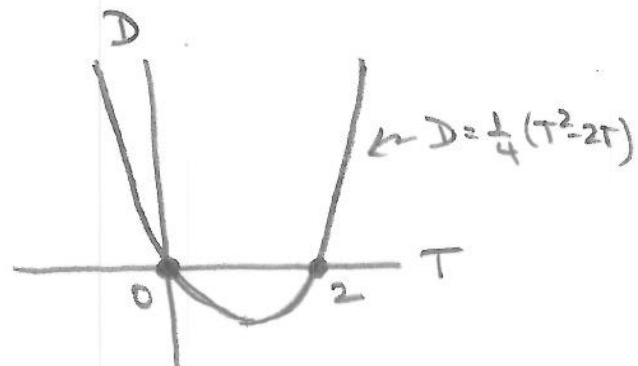
$$T = \text{trace} = 2a$$

$$D = \det = a^2 - a$$

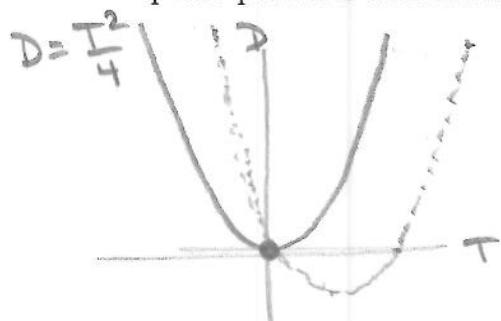
$$D = \left(\frac{T}{2}\right)^2 - \frac{T}{2}$$

$$= \frac{T^2}{4} - \frac{T}{2}$$

$$= \frac{1}{4}(T^2 - 2T) \text{ parabola}$$



- (b) Determine all bifurcation values of  $a$  and briefly discuss the different types of phase portraits that are exhibited in this one-parameter family.



Need to determine where the two parabolas intersect.

$$D = \frac{T^2}{4} = \frac{1}{4}(T^2 - 2T)$$

$$\Rightarrow T^2 = T^2 - 2T \Rightarrow 0 = -2T \Rightarrow T = 0$$

For  $T = 2a$  negative, the system

is a spiral sink.

For  $a = 0$ , we have a bifurcation value.

For  $0 < T < 2$  (equivalently  $0 < a < 1$ ),

the system is a saddle.

For  $T = 2$  ( $\Rightarrow a = 1$ ), we have another bifurcation value. For  $T > 2$  ( $a > 1$ ),

the system is a source with real eigenvalues.

5. (24 points) Note that part c of this problem is on the next page. Consider the system

$$\begin{aligned}\frac{dx}{dt} &= x - 3y^2 \\ \frac{dy}{dt} &= x - 3y - 6.\end{aligned}$$

- (a) Sketch the nullclines and indicate the directions in which solutions cross the nullclines.

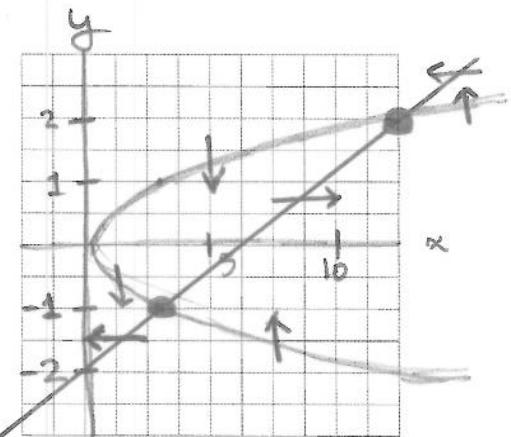
$$\begin{aligned}\frac{dx}{dt} = 0 &\Leftrightarrow x = 3y^2 \\ \frac{dy}{dt} = 0 &\Leftrightarrow 3y = x - 6 \\ &\Leftrightarrow y = \frac{1}{3}x - 2\end{aligned}$$

Nullclines intersect if

$$3y^2 = 3y + 6 \Rightarrow$$

$$3y^2 - 3y - 6 = 0 \Rightarrow y^2 - y - 2 = 0 \Rightarrow (y-2)(y+1) = 0 \Rightarrow y = 2 \text{ or } -1$$

- (b) Find and classify all equilibrium points.



$$J(x,y) = \begin{pmatrix} 1 & -6y \\ 1 & -3 \end{pmatrix}$$

$$(x,y) = (12,2) \text{ or } (3,-1)$$

$$J(12,2) = \begin{pmatrix} 1 & -12 \\ 1 & -3 \end{pmatrix} \Rightarrow \lambda^2 + 2\lambda + 9 = 0 \\ \lambda = \frac{-2 \pm \sqrt{4 - 36}}{2}$$

$\Rightarrow (12,2)$  is a spiral sink

$$J(3,-1) = \begin{pmatrix} 1 & 6 \\ 1 & -3 \end{pmatrix}$$

From the negative determinant, we know  
that  $(3,-1)$  is a saddle.

5. (continued)

(c) Sketch the phase portrait.

