

1. (10 points) Let

$$\mathbf{v} = \begin{bmatrix} 2 \\ 3 \\ -7 \end{bmatrix} \quad \text{and} \quad \mathbf{w} = \begin{bmatrix} 3 \\ 1 \\ 1 \end{bmatrix}.$$

(a) Write \mathbf{v} as the sum of a vector in the line spanned by \mathbf{w} and a vector orthogonal to \mathbf{w} .

$$\begin{aligned} \text{proj } \mathbf{v} &= \left(\frac{\mathbf{v} \cdot \mathbf{w}}{\mathbf{w} \cdot \mathbf{w}} \right) \mathbf{w} & \mathbf{v} \cdot \mathbf{w} &= 6 + 3 - 7 = 2 \\ & & \mathbf{w} \cdot \mathbf{w} &= 9 + 1 + 1 = 11 \\ &= \frac{2}{11} \begin{bmatrix} 3 \\ 1 \\ 1 \end{bmatrix} = \begin{bmatrix} \frac{6}{11} \\ \frac{2}{11} \\ \frac{2}{11} \end{bmatrix} \end{aligned}$$

$$\text{Let } \mathbf{u} = \mathbf{v} - \text{proj } \mathbf{v} = \begin{bmatrix} 2 \\ 3 \\ -7 \end{bmatrix} - \begin{bmatrix} \frac{6}{11} \\ \frac{2}{11} \\ \frac{2}{11} \end{bmatrix} = \begin{bmatrix} \frac{16}{11} \\ \frac{31}{11} \\ -\frac{79}{11} \end{bmatrix}$$

$$\mathbf{v} = \begin{bmatrix} \frac{6}{11} \\ \frac{2}{11} \\ \frac{2}{11} \end{bmatrix} + \begin{bmatrix} \frac{16}{11} \\ \frac{31}{11} \\ -\frac{79}{11} \end{bmatrix}$$

\swarrow in span \mathbf{w} \nwarrow orthogonal to \mathbf{w}

(b) Compute the distance of \mathbf{v} to the line spanned by \mathbf{w} .

$$\begin{aligned} \text{distance} &= \|\mathbf{u}\| = \sqrt{\mathbf{u} \cdot \mathbf{u}} = \frac{1}{11} \sqrt{16^2 + 31^2 + 79^2} \\ &= \frac{\sqrt{7458}}{11} \end{aligned}$$

2. (10 points) Let A and B be 4×4 matrices with $\det A = 2$ and $\det B = -3$. Compute:

$$(a) \det 3A = (3)^4 \det A = (81)(2) = 162$$

$$(b) \det B^3 = (\det B)(\det B)(\det B) = -27$$

$$(c) \det AB = (\det A)(\det B) = (2)(-3) = -6$$

$$(d) \det A^T A = (\det A^T)(\det A) = (\det A)(\det A) \\ = (2)(2) = 4$$

$$(e) \det B^{-1}AB = (\det B^{-1})(\det A)(\det B) \\ = \left(\frac{1}{\det B}\right)(\det A)(\det B) \\ = \det A = 2.$$

3. (14 points) Consider the set S of all vectors

$$\begin{bmatrix} a \\ b \\ c \\ d \end{bmatrix}$$

in \mathbb{R}^4 such that

$$\begin{aligned} a - 2b + 2c + d &= 0 \\ -3a + 6b - 5c - d &= 0 \\ 4a - 8b + 9c + 6d &= 0. \end{aligned}$$

(a) Why is S a subspace of \mathbb{R}^4 ?

$$S = \text{null } A \text{ where } A = \begin{bmatrix} 1 & -2 & 2 & 1 \\ -3 & 6 & -5 & -1 \\ 4 & -8 & 9 & 6 \end{bmatrix}$$

(b) Determine the dimension of S and find a basis.

$$A \sim \begin{bmatrix} 1 & -2 & 2 & 1 \\ 0 & 0 & 1 & 2 \\ 0 & 0 & 1 & 2 \end{bmatrix} \sim \begin{bmatrix} 1 & -2 & 2 & 1 \\ 0 & 0 & 1 & 2 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

two free variables (b and d) $\Rightarrow \dim S = 2$.

$$b=0 \text{ and } d=1 \Rightarrow \begin{aligned} c &= -2 \\ a &= 2b - 2c - d = 3 \end{aligned}$$

$$b=1 \text{ and } d=0 \Rightarrow \begin{aligned} c &= 0 \\ a &= 2b - 2c - d = 2 \end{aligned}$$

$$\text{basis: } \left\{ \begin{bmatrix} 2 \\ 1 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 3 \\ 0 \\ -2 \\ 1 \end{bmatrix} \right\}$$

4. (14 points) Consider the matrix

$$A = \begin{bmatrix} 4 & 0 & -2 \\ 2 & 5 & 4 \\ 0 & 0 & 5 \end{bmatrix}.$$

(a) Without doing any computation, explain why $\lambda = 5$ is an eigenvalue.

From the second column, we see that
 $Ae_2 = 5e_2$.

(b) What's the "easy" way to show that $v = \begin{bmatrix} -1 \\ 2 \\ 0 \end{bmatrix}$ is an eigenvector?

$$Av = \begin{bmatrix} -4 \\ 0 \\ 0 \end{bmatrix} = 4v \quad \text{eigenvalue} = 4$$

(c) Find an invertible matrix P and a diagonal matrix D such that $D = P^{-1}AP$.
 You do not need to calculate P^{-1} .

$$\begin{aligned} \text{char poly} = \det(A - \lambda I) &= \begin{vmatrix} 4-\lambda & 0 & -2 \\ 2 & 5-\lambda & 4 \\ 0 & 0 & 5-\lambda \end{vmatrix} \\ &= (5-\lambda) \begin{vmatrix} 4-\lambda & -2 \\ 0 & 5-\lambda \end{vmatrix} = (5-\lambda)^2(4-\lambda) \end{aligned}$$

$\lambda = 4, 5$

$$\text{nul}(A - 5I) = \text{nul} \begin{bmatrix} -1 & 0 & -2 \\ 2 & 0 & 4 \\ 0 & 0 & 0 \end{bmatrix} = \text{nul} \begin{bmatrix} -1 & 0 & -2 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

$$\lambda = 5 \text{ eigenspace} : x_1 + 2x_3 = 0$$

#4 (c) cont.

two free variables:

$$x_2 = 1 \text{ and } x_3 = 0 \Rightarrow x_1 = 0$$

eigenvector is e_2 (already known)

$$x_2 = 0 \text{ and } x_3 = 1 \Rightarrow x_1 = -2$$

eigenvector is $\begin{bmatrix} -2 \\ 0 \\ 1 \end{bmatrix}$.

matrix P of eigenvectors

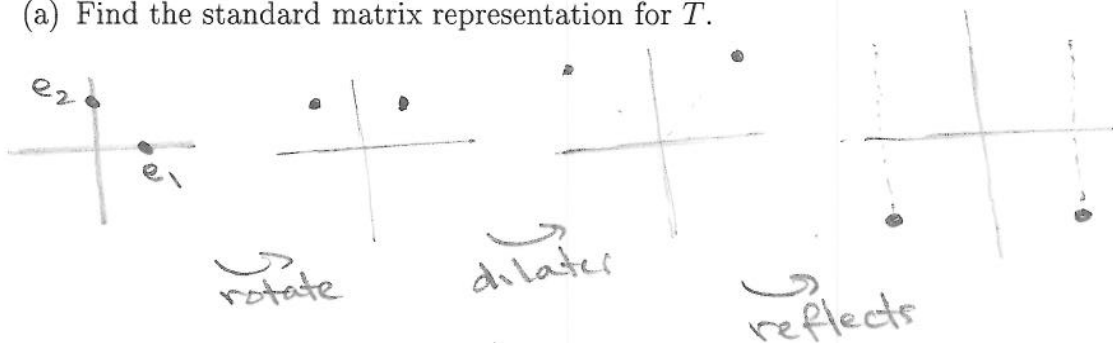
$$P = \begin{bmatrix} -1 & 0 & -2 \\ 2 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

In this case,

$$P^{-1}AP = \begin{bmatrix} 4 & 0 & 0 \\ 0 & 5 & 0 \\ 0 & 0 & 5 \end{bmatrix}.$$

5. (14 points) Let $T : \mathbb{R}^2 \rightarrow \mathbb{R}^2$ be the linear transformation that first rotates the plane by 45° in the counterclockwise direction, then dilates the plane by a factor of 2, and finally reflects the plane in the x_1 -axis.

(a) Find the standard matrix representation for T .



The left-hand point is $(-\sqrt{2}, -\sqrt{2})$ and the right-hand point is $(\sqrt{2}, -\sqrt{2})$

$$\text{matrix } A = \begin{bmatrix} \sqrt{2} & -\sqrt{2} \\ -\sqrt{2} & -\sqrt{2} \end{bmatrix}$$

(b) Let P be the parallelogram determined by the two vectors

$$v_1 = \begin{bmatrix} 1 \\ 1 \end{bmatrix} \quad \text{and} \quad v_2 = \begin{bmatrix} 1 \\ 3 \end{bmatrix}.$$

Calculate the area of $T(P)$.

$$\text{area } P = \begin{vmatrix} 1 & 1 \\ 1 & 3 \end{vmatrix} = 2$$

$$\begin{aligned} \text{area } T(P) &= |\det A| \text{ area}(P) \\ &= |-4| (2) = 8 \end{aligned}$$

6. (14 points) Note that there is a second part to this problem on the next page. Recall that a matrix is upper triangular if all of its entries below the diagonal are zero. For example, an upper-triangular 3×3 matrix A has the form

$$A = \begin{bmatrix} a_{1,1} & a_{1,2} & a_{1,3} \\ 0 & a_{2,2} & a_{2,3} \\ 0 & 0 & a_{3,3} \end{bmatrix}$$

where the entries $a_{1,1}$, $a_{1,2}$, $a_{1,3}$, $a_{2,2}$, $a_{2,3}$, and $a_{3,3}$ can be any real numbers.

- (a) Show that the subset S of all upper-triangular matrices in $M_{3 \times 3}$ is a vector subspace of $M_{3 \times 3}$.

① (not necessary) The zero vector is the zero matrix $\begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}$. This matrix is upper triangular.

② closed under vector addition:

Given A as above and

$$B = \begin{bmatrix} b_{11} & b_{12} & b_{13} \\ 0 & b_{22} & b_{23} \\ 0 & 0 & b_{33} \end{bmatrix}$$

then

$$A+B = \begin{bmatrix} a_{11}+b_{11} & a_{12}+b_{12} & a_{13}+b_{13} \\ 0 & a_{22}+b_{22} & a_{23}+b_{23} \\ 0 & 0 & a_{33}+b_{33} \end{bmatrix}$$

which is upper triangular.

③ closed under scalar multiplication:
Given A as above and r in \mathbb{R}

$$rA = \begin{bmatrix} ra_{11} & ra_{12} & ra_{13} \\ 0 & ra_{22} & ra_{23} \\ 0 & 0 & ra_{33} \end{bmatrix}$$

which is upper triangular.

Problem 6 (continued):

(b) Specify a basis for S and show that it is a basis. What is the dimension of S ?

basis consists of six upper triangular matrices:

$$\begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 0 & 1 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

$$\begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix}.$$

$$\Rightarrow \dim S = 6.$$

Need to verify that these six matrices form a basis of S .

① linearly independent: Given a dependence relation

$$r_1 \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} + r_2 \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} + r_3 \begin{bmatrix} 0 & 0 & 1 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} + r_4 \begin{bmatrix} 0 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

$$+ r_5 \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{bmatrix} + r_6 \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix} = \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix},$$

we see that $r_1 = r_2 = r_3 = r_4 = r_5 = r_6 = 0$.

② spans S . Given A on the previous page,

$$\text{then}$$

$$A = a_{11} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} + a_{12} \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} + a_{13} \begin{bmatrix} 0 & 0 & 1 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

$$+ a_{22} \begin{bmatrix} 0 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix} + a_{23} \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{bmatrix} + a_{33} \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix}.$$

7. (24 points) Are the following statements true or false? You must justify your answers to receive any credit.

- (a) Row operations on a matrix A can change the linear dependence relations among the rows of A .

True. Start with $A_1 = \begin{bmatrix} 1 & 0 \\ 2 & 0 \end{bmatrix}$.

Then $\text{row } 2 = 2 \text{ row } 1$. Then

$A_1 \sim A_2 = \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}$. Then

$\text{row } 2 = 0 \text{ row } 1$.

- (b) A square matrix is invertible if and only if it is the product of elementary matrices.

True. We know that a matrix A is invertible $\iff A$ is row equivalent to the identity matrix I . Each row operation corresponds to multiplication by an elementary matrix, so we have:

$$A \text{ is invertible} \iff E_n E_{n-1} \cdots E_2 E_1 A = I.$$

$$\iff A = E_1^{-1} E_2^{-1} \cdots E_{n-1}^{-1} E_n^{-1}.$$

Problem 7 (continued):

- (c) A basis is a spanning set that is as large as possible.

False. One basis for \mathbb{R}^2 is $\left\{ \begin{bmatrix} 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \end{bmatrix} \right\}$.

A bigger spanning set is

$$\left\{ \begin{bmatrix} 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \end{bmatrix}, \begin{bmatrix} 1 \\ 1 \end{bmatrix} \right\}.$$

In fact, one can always increase the number of vectors in a spanning set. So there is no such thing as a largest spanning set.

- (d) If λ is an eigenvalue for the $n \times n$ matrix A and μ is an eigenvalue for the $n \times n$ matrix B , then the product $\lambda\mu$ is an eigenvalue for the matrix AB .

False. For example, let $A = \begin{bmatrix} 3 & 1 \\ 1 & 3 \end{bmatrix}$

which has $\lambda = 2, 4$, and let $B = \begin{bmatrix} 1 & 0 \\ 0 & 3 \end{bmatrix}$

which has $\mu = 1, 3$. Then

$$AB = \begin{bmatrix} 3 & 3 \\ 1 & 9 \end{bmatrix}. \quad \det(AB - \lambda I) = \begin{vmatrix} 3-\lambda & 3 \\ 1 & 9-\lambda \end{vmatrix}$$

$$= (\lambda-3)(\lambda-9) - 3 =$$

$$= \lambda^2 - 12\lambda + 24.$$

$$\text{roots are } \frac{12 \pm \sqrt{144 - 96}}{2}$$

$$= 6 \pm \sqrt{12}.$$

Problem 7 (continued):

(e) Every projection matrix is orthogonal.

False. Projection onto the line $x_2 = x_1$ is $P = \begin{bmatrix} \frac{1}{2} & \frac{1}{2} \\ \frac{1}{2} & \frac{1}{2} \end{bmatrix}$. The columns are neither orthogonal nor unit length.

(f) Every projection matrix is diagonalizable.

True. Consider projection onto the subspace W of \mathbb{R}^n . If $\dim W = k$, then W is the k dimensional eigenspace corresponding to $\lambda = 1$, and W^\perp is the $n-k$ dimensional eigenspace corresponding to $\lambda = 0$. We can diagonalize a matrix if there is a basis of \mathbb{R}^n of eigenvectors. Pick a basis $\{u_1, \dots, u_k\}$ of W and a basis $\{v_1, \dots, v_{n-k}\}$ of W^\perp . Then $\{u_1, \dots, u_k, v_1, \dots, v_{n-k}\}$ is the required basis.