

Dynamical charts for irrationally indifferent fixed points of holomorphic functions

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Complex Dynamics

$f : \widehat{\mathbb{C}} \rightarrow \widehat{\mathbb{C}}$ Rational map or $f : \mathbb{C} \rightarrow \mathbb{C}$ Polynomial

$$z_0 \mapsto z_1 = f(z_0) \mapsto z_2 = f^2(z_0) \mapsto \dots \mapsto z_n = f^n(z_0) = \overbrace{f \circ \dots \circ f}^n(z_0)$$

Dichotomy in Phase space (z-plane)

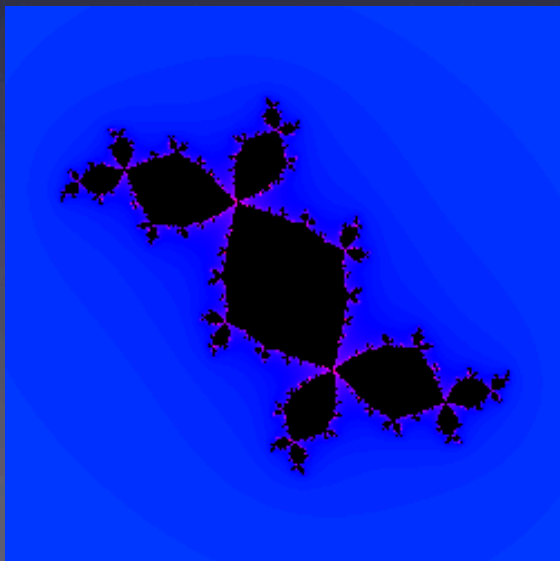
$$\widehat{\mathbb{C}} = F(f) \cup J(f)$$

where $F(f) =$ Fatou set (tame part), $J(f) =$ Julia set (chaotic part)

For f polynomial,

$K(f) := \{z \in \mathbb{C} : \{f^n(z)\}_{n=0}^{\infty} \text{ bounded}\}$ filled Julia set

$J(f) := \partial K(f) = \{z : \{f^n\}_{n=0}^{\infty} \text{ is not equicontinuous near } z\}$

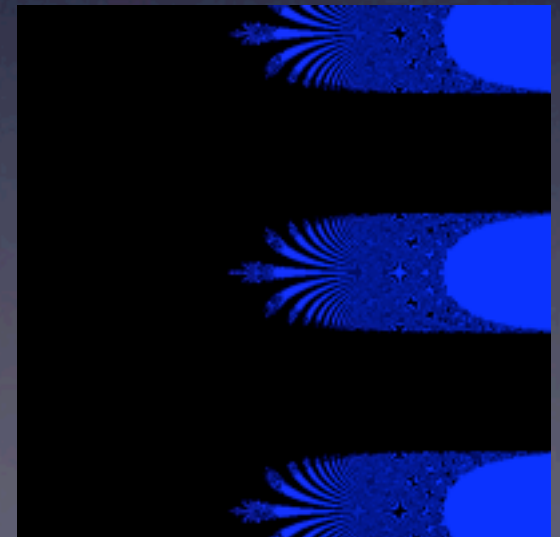


Other dynamics, e.g.

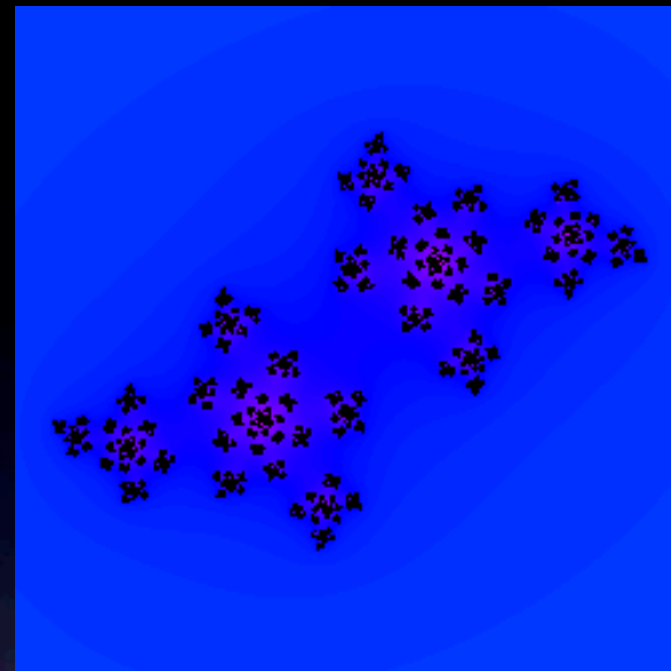
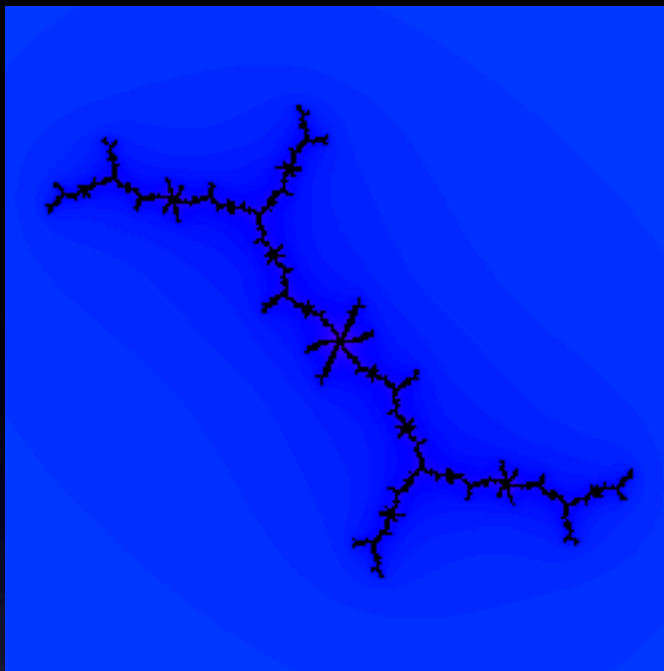
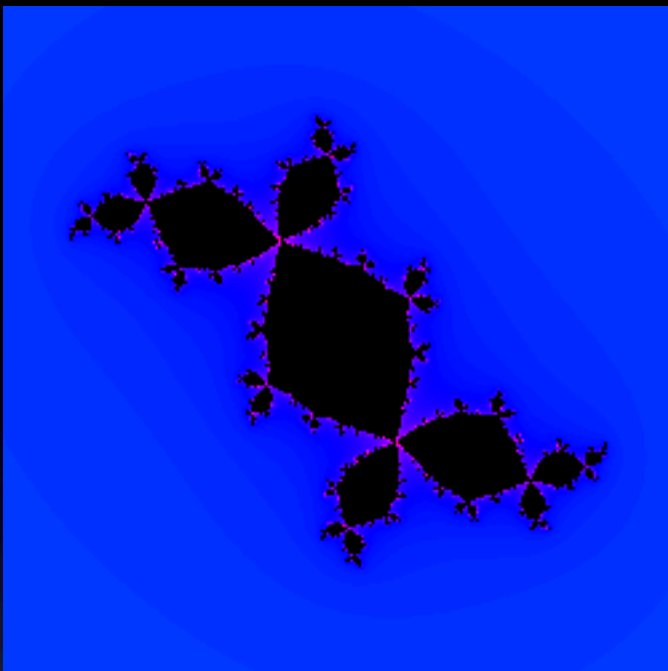
$$E_\lambda(z) = \lambda e^z$$

(cf. Devaney's talk:

Cantor Bouquet and hairs)



A few examples ($f_c(z) = z^2 + c$ with various c 's)



Well-understood if f is *hyperbolic*: all critical points are attracted to attracting periodic orbits, or equivalently f is expanding on $J(f)$. Then the Julia set is locally connected and the dynamics of $J(f)$ can be described as a quotient (factor) of $z \mapsto z^d$ on S^1 .

There are other cases where the topology of Julia sets (and other invariant sets) are not well-understood.

An example is the maps with non-linearizable irrationally indifferent fixed points.

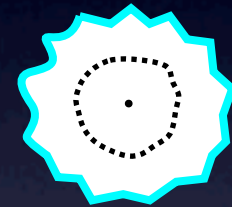
Goal of this talk is to understand the local dynamics of such a map via *renormalization*.

Local dynamics near irrationally indifferent fixed points

Irrationally indifferent fixed point of a holomorphic function

$$f(z) = e^{2\pi i\alpha} z + z^2 + \dots, \quad \alpha \in \mathbb{R} \setminus \mathbb{Q}$$

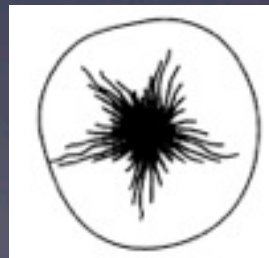
The fixed point is *linearizable* if and only if it is locally (holomorphically) conjugate to a rotation.



Problem: What is the local dynamics when the fixed pt is not linearizable?

Perez-Marco's *Hedgehog*: $0 \in U$ topological disk in \mathbb{C} , $f : \bar{U} \rightarrow f(\bar{U})$ homeo, holomorphic in U , $f(z) = e^{2\pi i\alpha} z + O(z^2)$, $\alpha \in \mathbb{R} \setminus \mathbb{Q}$
 $\exists K \subset U$ maximal connected invariant set.

He constructed some examples of germs of hedgehogs.

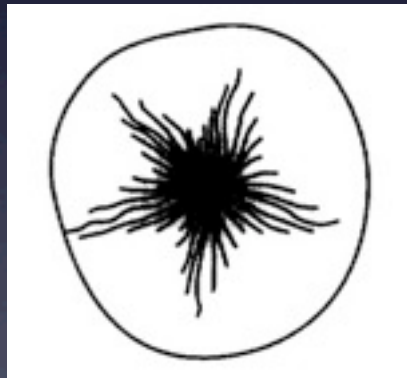


Problem: What are possible hedgehogs for quadratic polynomials?

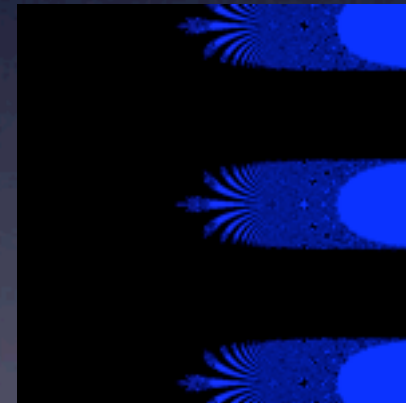
Theorem: If $f(z) = e^{2\pi i\alpha} z + z^2$ and the rotation number α is an irrational number of high type, i.e.

$$\alpha = \pm \frac{1}{a_1 \pm \frac{1}{a_2 \pm \frac{1}{\ddots}}} \quad (a_i \in \mathbb{N}, a_i \geq N \text{ large})$$

then the Julia set $J(f)$ contains an invariant subset Λ such that 0 , critical pt $\in \Lambda$ and $\Lambda \setminus \{0\}$ consists of (disjoint) continuous hairs (like the Julia set of exponential map).

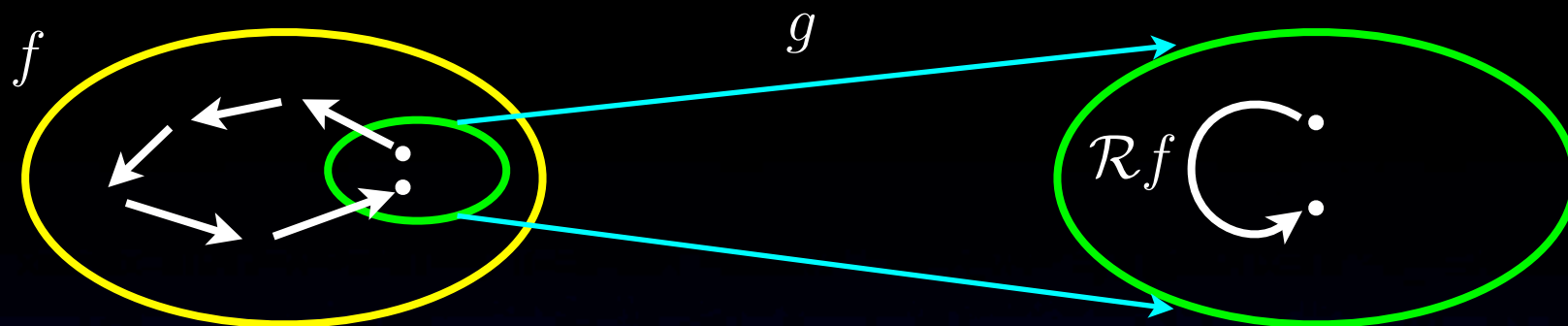


(maximal hedgehog)



The key idea is to use the *near-parabolic renormalization*, which is associated with the perturbation of parabolic fixed points (e.g. $z = 0$ for $z \mapsto z + z^2 + \dots$).

Return map and renormalization

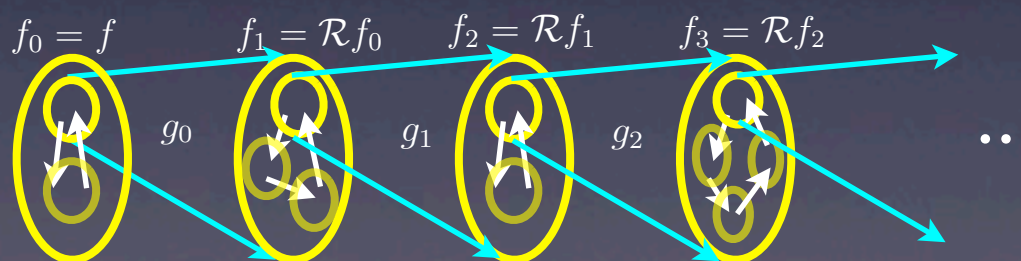


$$\begin{aligned} \mathcal{R}f &= (\text{first return map of } f) \text{ after rescaling} \\ &= g \circ f^k \circ g^{-1} \quad (\text{if return time } \equiv k) \end{aligned}$$

Renormalization

high iterates of f \longleftrightarrow fewer iterates of $\mathcal{R}f$
 fine orbit structure for f \longleftrightarrow large scale orbit structure for $\mathcal{R}f$

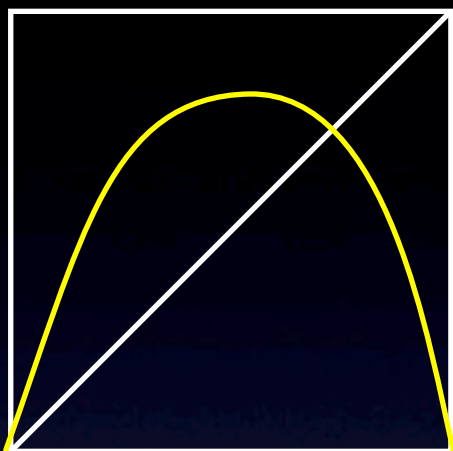
Successive construction of $\mathcal{R}f, \mathcal{R}^2f, \dots$, helps to understand the dynamics of f (orbits, invariant sets, rigidity, bifurcation, ...)



The renormalization $\mathcal{R} : f \mapsto \mathcal{R}f$ can be considered as a meta-dynamics on the space of dynamical systems of certain class.

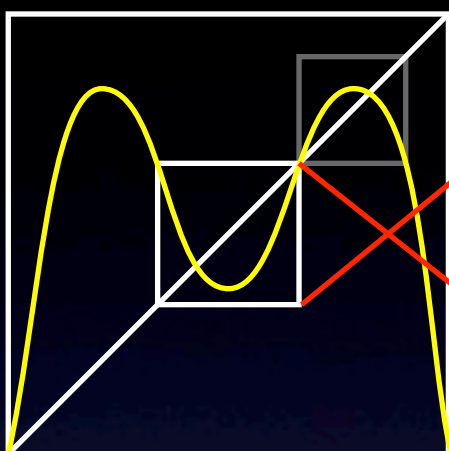
Feigenbaum-Coulet-Tresser for unimodal maps

f



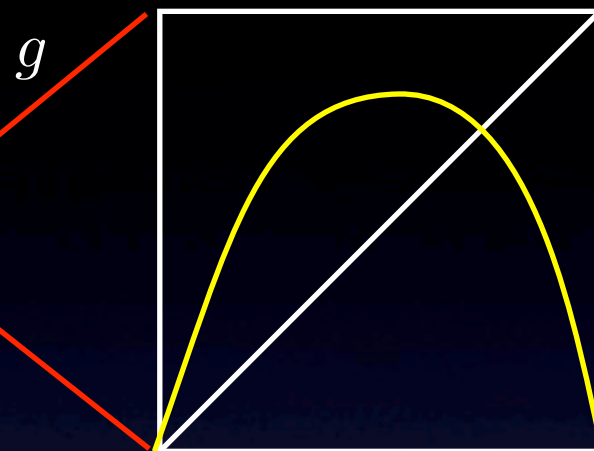
$I = [0, 1]$

f^2

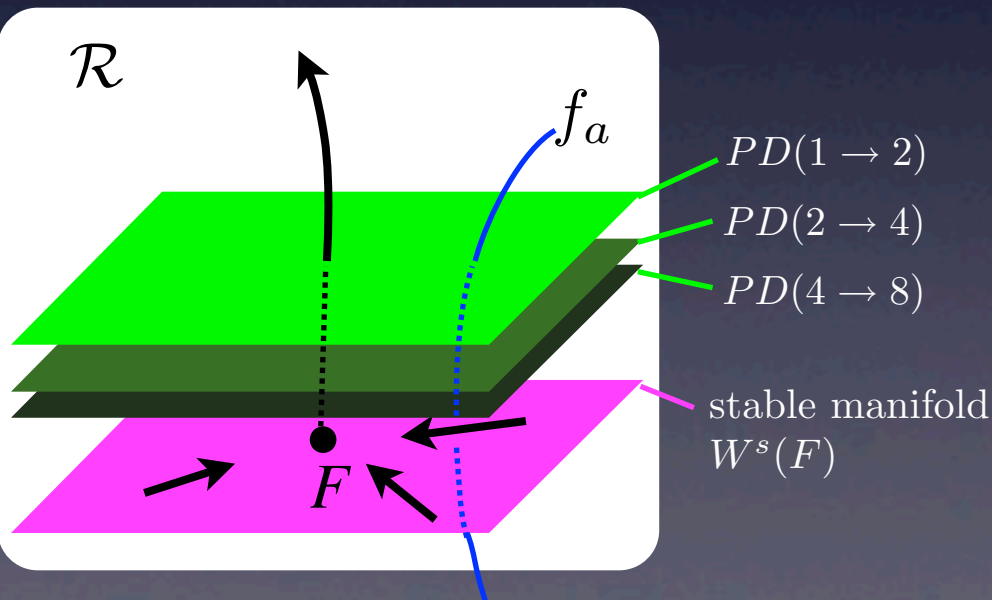


$J \subset I$ s.t. $f^2(J) \subset J$

$$\mathcal{R}f = g \circ (f^2|_J) \circ g^{-1}$$



\mathcal{R}



$PD(1 \rightarrow 2)$

$PD(2 \rightarrow 4)$

$PD(4 \rightarrow 8)$

stable manifold
 $W^s(F)$

Hyperbolic fixed point or hyperbolic horseshoe of the meta-dynamics imply conclusion on rigidity and structure of parameter space

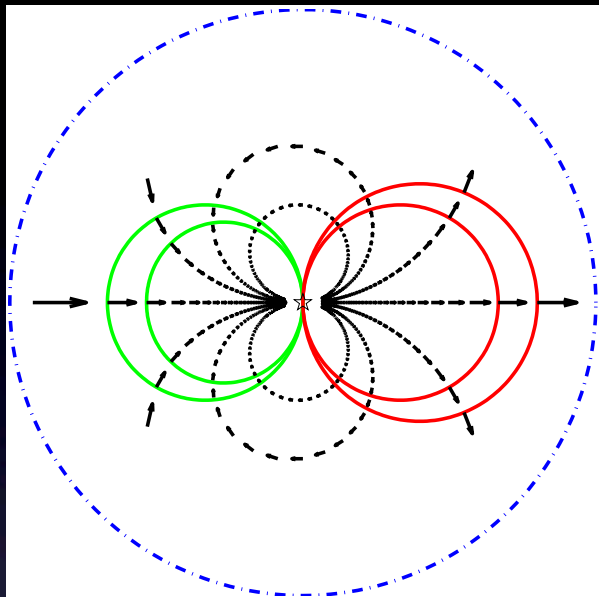
The universality of ratios of bifurcating parameters

Fatou coordinates $\Phi_{attr/rep}$ and the Horn map E_{f_0} for $f_0(z) = z + z^2 + \dots$

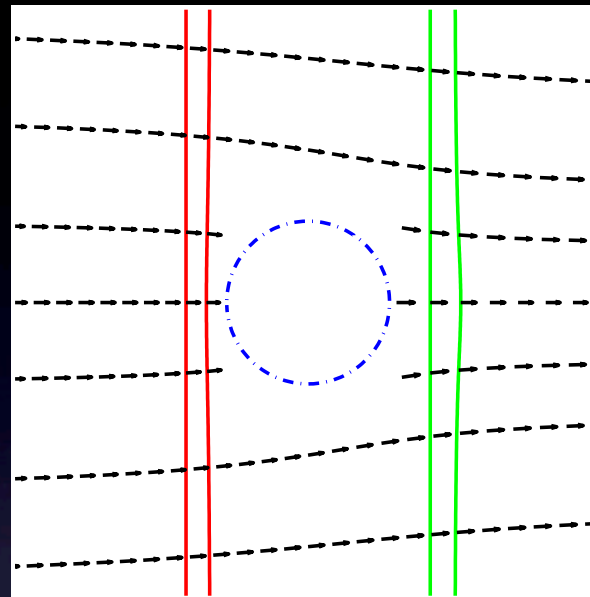
$$f_0(z) = z + a_2 z^2 + \dots$$

$$F_0(w) = w + 1 + o(1)$$

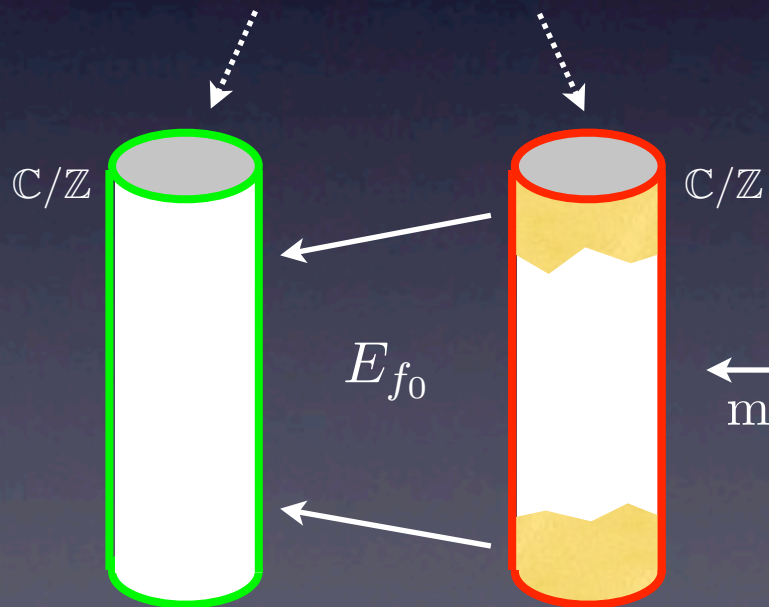
near 0



near ∞

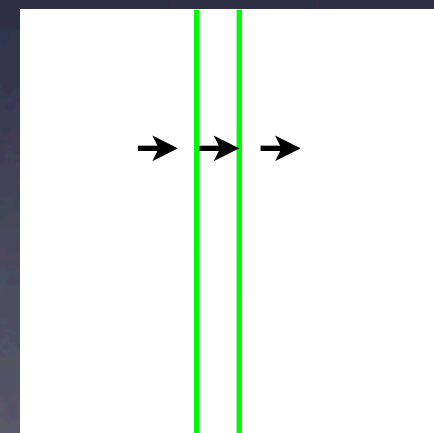
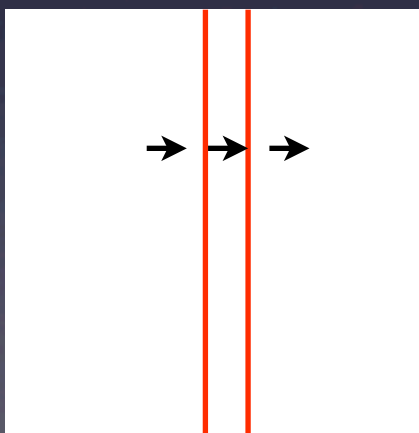


$$w = -\frac{c}{z}$$



$$\Phi_{rep}$$

$$\Phi_{attr}$$



$$T(w) = w + 1$$

$$T(w) = w + 1$$

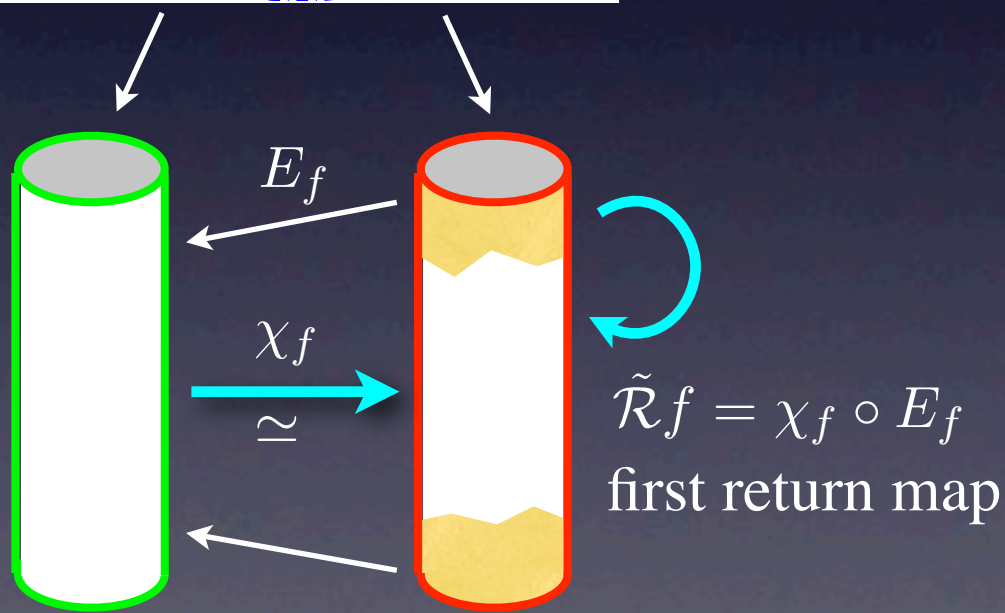
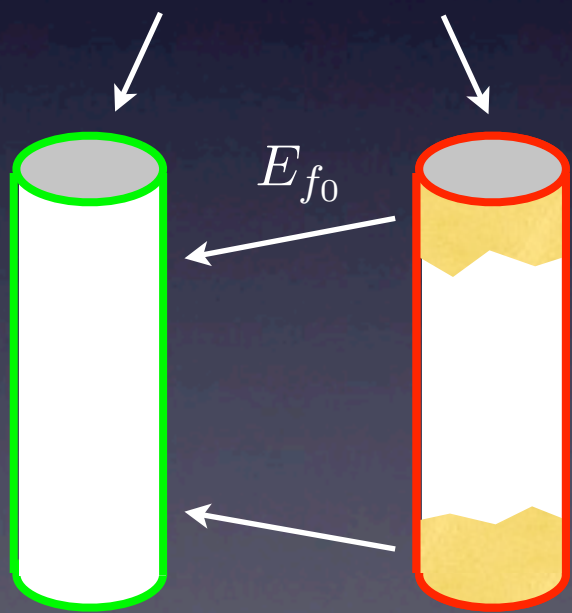
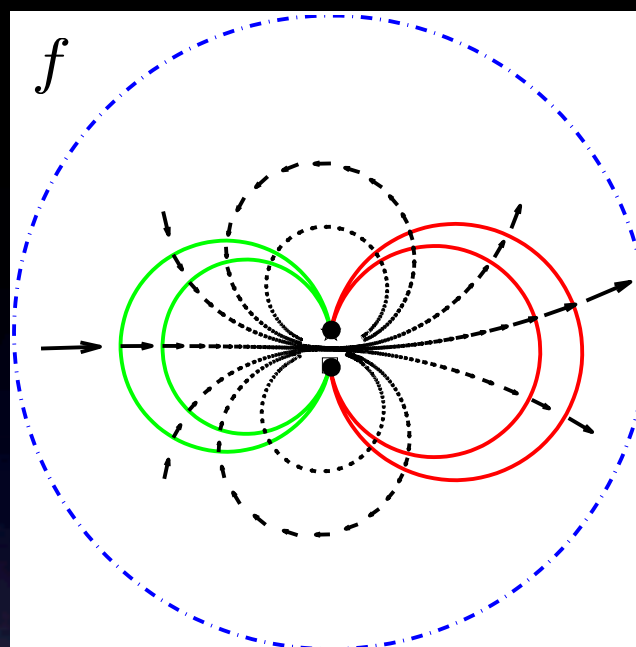
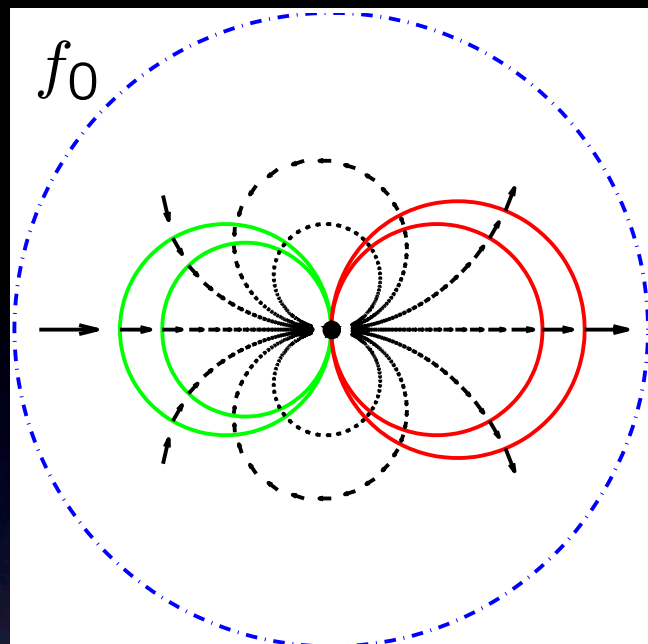
$$\text{mod } \mathbb{Z}$$

$$E_{f_0}(z) = \Phi_{attr} \circ \Phi_{rep}^{-1}$$

$$\Phi_{\dots}(f_0(z)) = \Phi_{\dots}(z) + 1$$

Perturbation

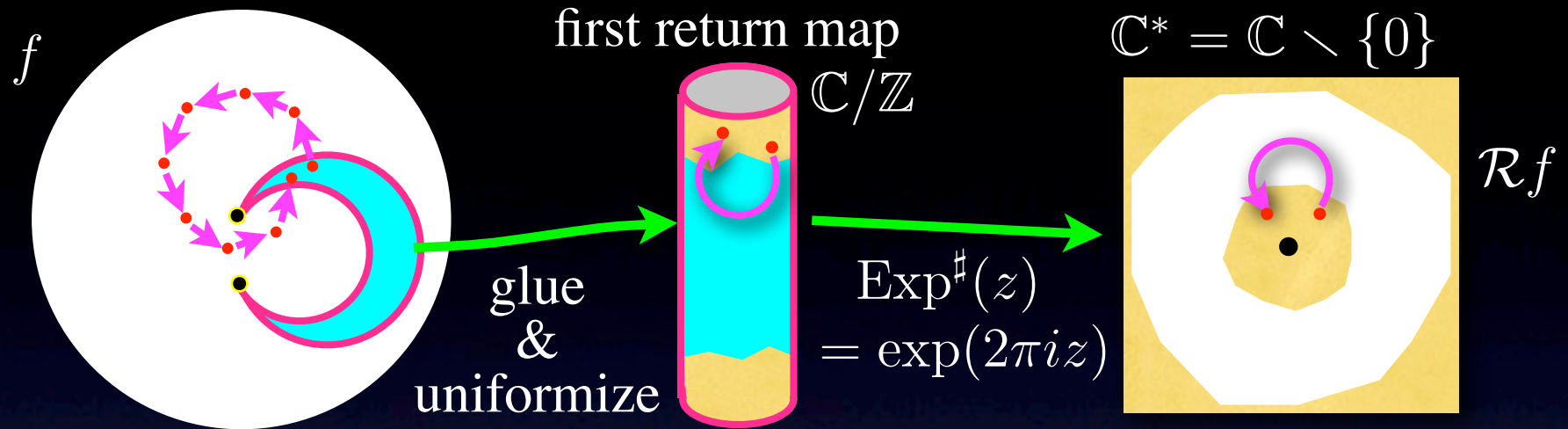
$$f'(0) = e^{2\pi i \alpha}, \quad \alpha \text{ small} \quad |\arg \alpha| < \frac{\pi}{4}$$



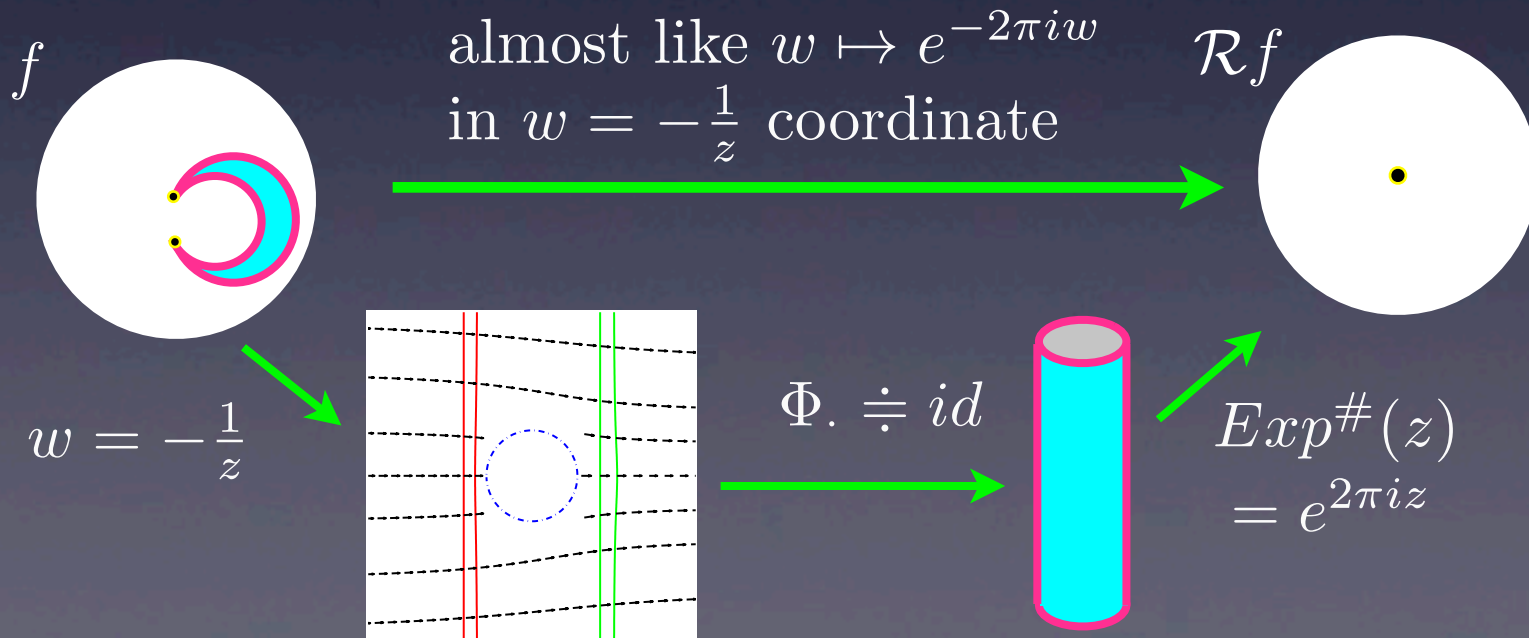
E_f depends continuously on f
(after a suitable normalization)

$$\chi_f(z) = z - \frac{1}{\alpha}$$

Near-parabolic renormalization



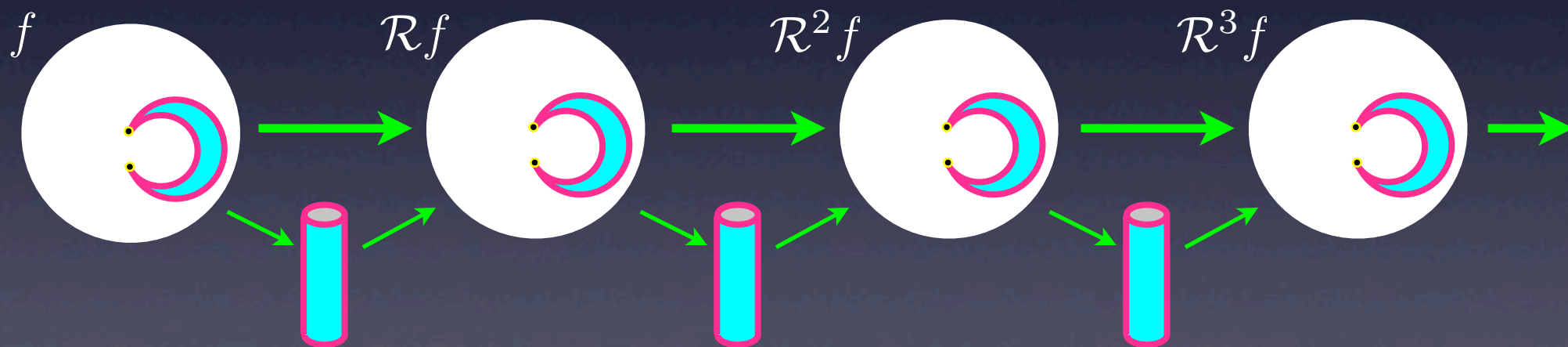
$\mathcal{R}f$ can be defined when $f(z) = e^{2\pi i\alpha}z + \dots$ is a small perturbation of $z + a_2z^2 + \dots$ ($a_2 \neq 0$) and $|\arg \alpha| < \pi/4$.



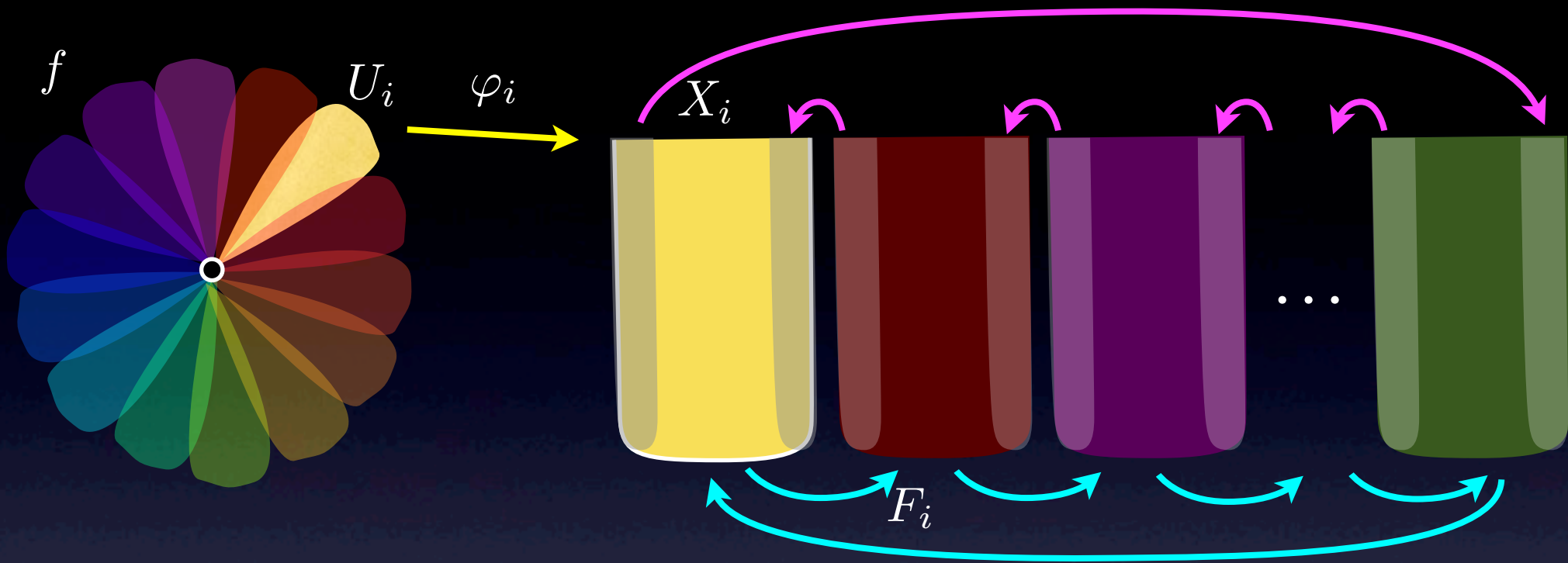
Theorem (Inou & S.): If α is an irrational number of sufficiently high type, then for $f(z) = e^{2\pi i\alpha}z + z^2$, the sequence of near-parabolic renormalizations

$$f, \mathcal{R}f, \mathcal{R}^2f, \mathcal{R}^3f, \dots$$

are well-defined and these functions $\mathcal{R}^n f$ belong to a certain pre-compact class of functions. Each $\mathcal{R}^n f$ has a unique critical point in its domain of definition and the critical points are inherited between the levels of renormalization.



Dynamical charts



Open sets U_i ($i \in I$), which cover a punctured nbd of fixed pt

Maps $\varphi_i : U_i \rightarrow X$, a small number of model spaces

A small number of model dynamics $F = \varphi_{r(i)} \circ f \circ \varphi_i^{-1}$
(for example, F_{can} and id)

Index set I with induced dynamics $r : I \rightarrow I$
(represents the combinatorics of the dynamics)

Gluing $\varphi_{i,j} = \varphi_i \circ \varphi_j^{-1}$ on overlaps, compatible with model dynamics
(absorbs the difference for particular maps)

Special for irrational dynamics: Refinements
one system of charts \rightarrow a new system of refined charts

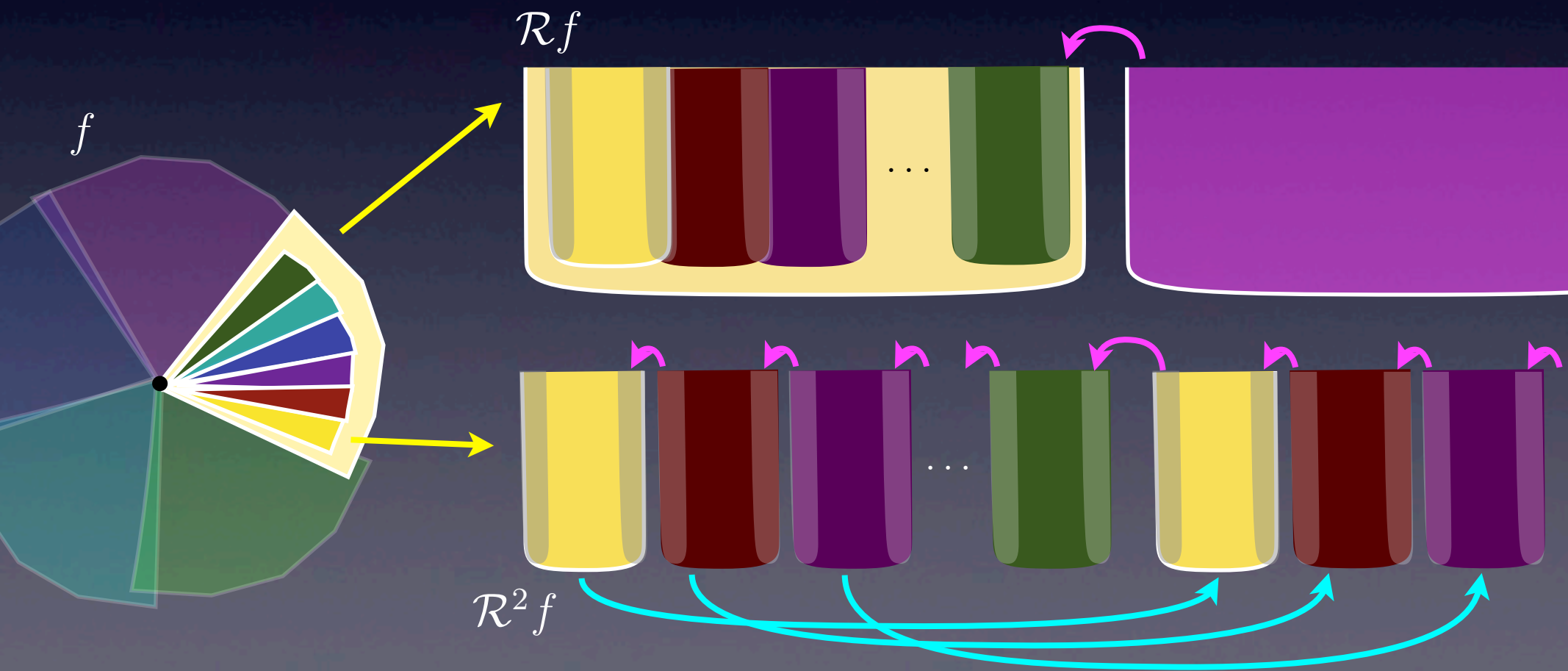
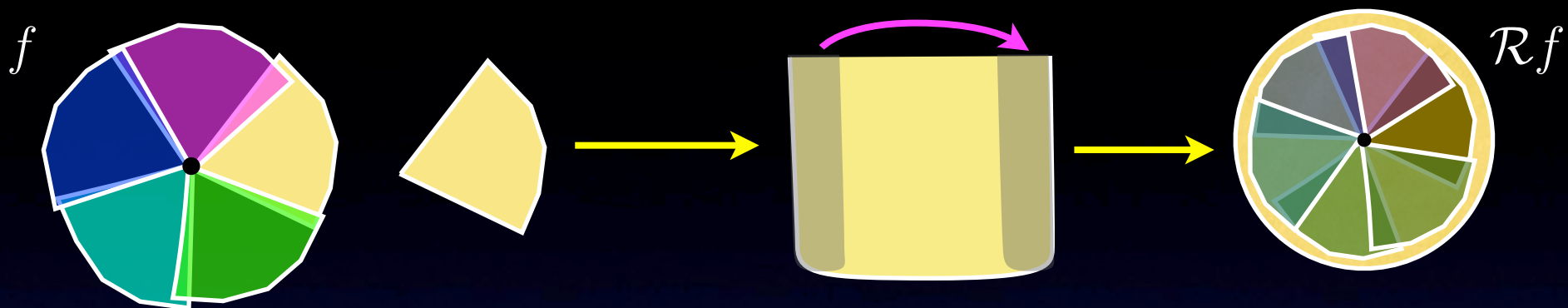
Convention

$z \rightarrow 0$ in U_i



$Im w \rightarrow +\infty$ in X_i

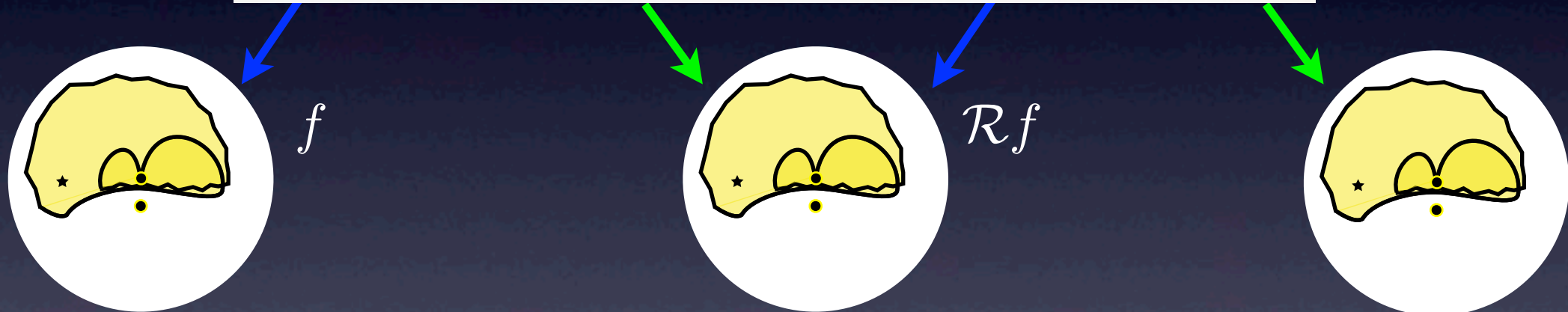
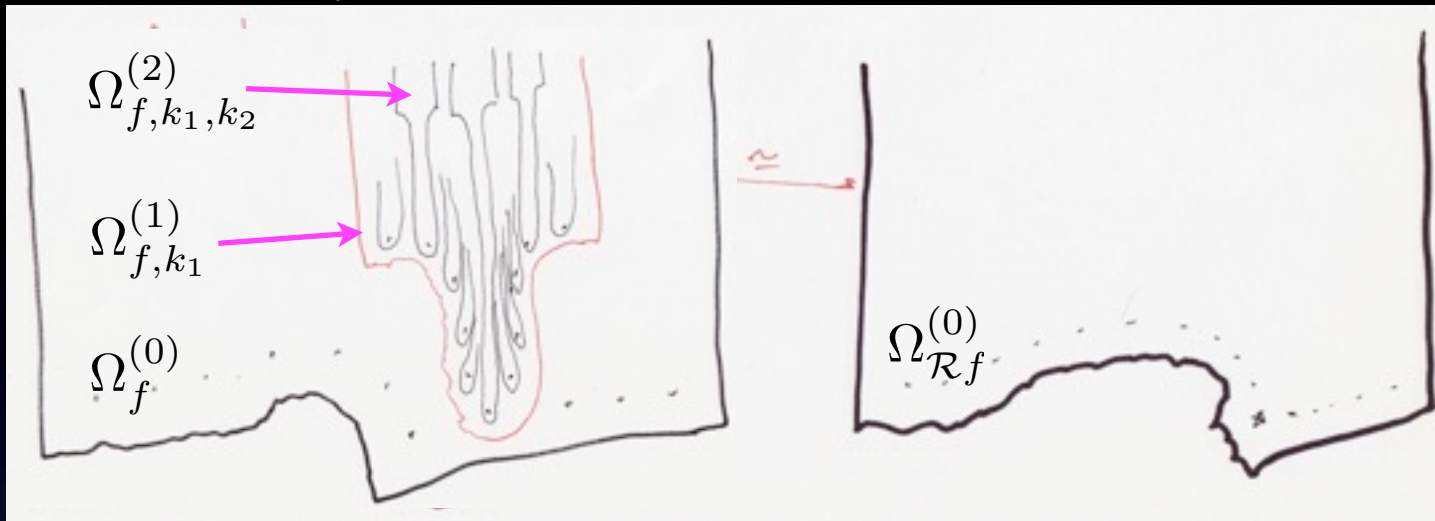
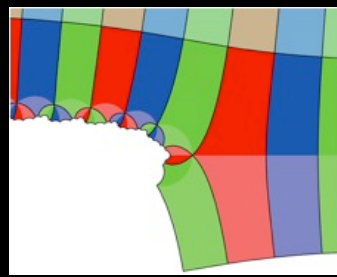
Successive renormalizations = refinements of dynamical charts



Construction of dynamical charts

Ω_f

$\Omega_{\mathcal{R}f}$

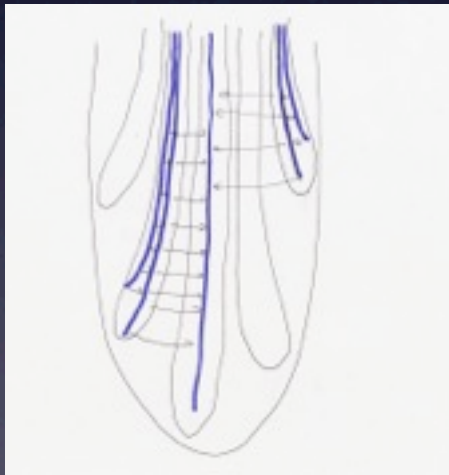
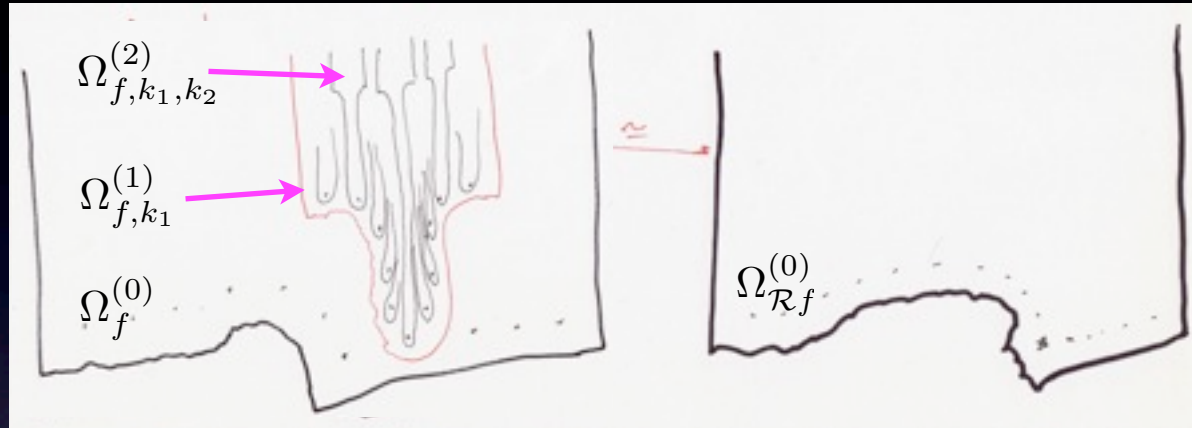


$$\Omega^{(0)} \supset \Omega_{k_1}^{(1)} \supset \dots \supset \Omega_{k_1, k_2, \dots, k_n}^{(n)} \supset \Omega_{k_1, k_2, \dots, k_n, k_{n+1}}^{(n+1)} \supset \dots$$

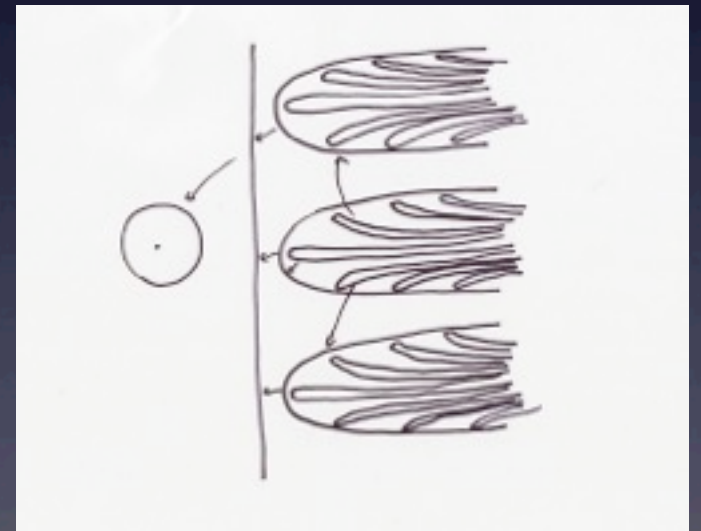
each $\Omega_{k_1, k_2, \dots, k_n}^{(n)}$ is isomorphic to truncated checkerboard pattern $\Omega_{\mathcal{R}^n f}$ they are glued via $\theta_{\mathcal{R}^n f}$

$\Lambda_f = \bigcap_{n=0}^{\infty} \bigcup_{(k_1, \dots, k_n) \in A_n} \Omega_{f, k_1, k_2, \dots, k_n}^{(n)}$ is an invariant set containing the critical orbit “maximal hedgehog”

Theorem For each $(k_1, k_2, \dots) \in A_\infty$ (set of admissible sequences of indices), the intersection $\bigcap_{n=1}^{\infty} \Omega_{f; k_1, \dots, k_n}^{(n)}$ is a simple arc ending at 0. (hair) The maximal hedgehog Λ_f is the union of arcs which are disjoint except at 0.



Proof by successive (cut-off) homotopies just like in the case of exponential maps



Iterating exponential(-like) maps is necessary to understand quadratic polynomials!

Thank you!