

A Sierpinski Mandelbrot Spiral

E. Chang

Department of Mathematics and Statistics
Boston University

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- 1 Introduction
- 2 A Sierpinski Mandelbrot Arc
- 3 A Different Sierpinski Mandelbrot Arc
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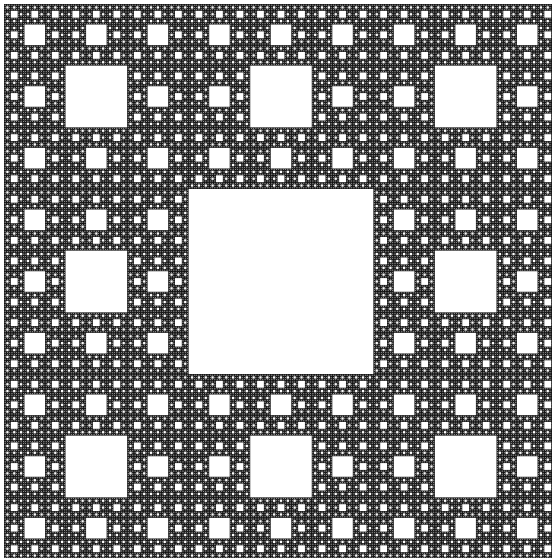
What Do I Do?

- I study topological structures of bifurcation diagrams for singularly perturbed complex rational maps.

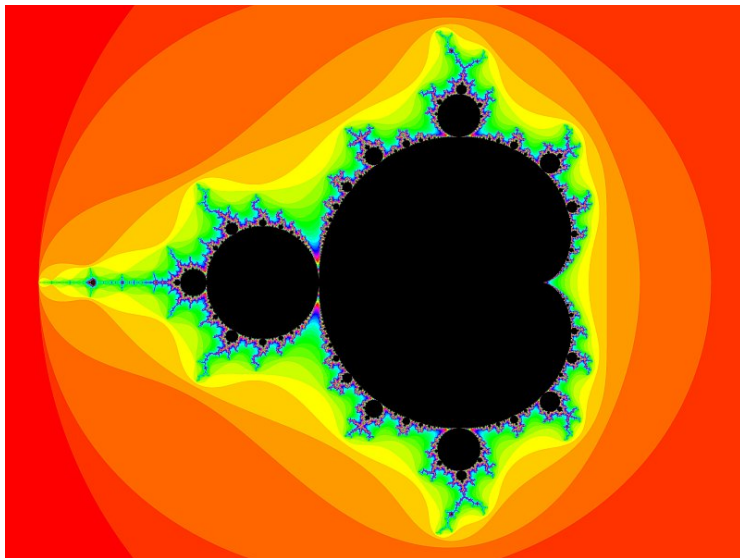
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- I study topological structures of bifurcation diagrams for singularly perturbed complex rational maps.
- I am mainly interested in Sierpinski holes and Mandelbrot sets.

Sierpinski Carpet Fractal



Mandelbrot Set

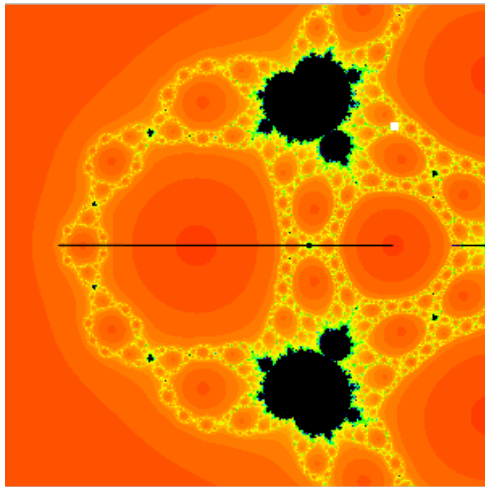


Arcs and Spirals

We will find a Sierpinski Mandelbrot arc.

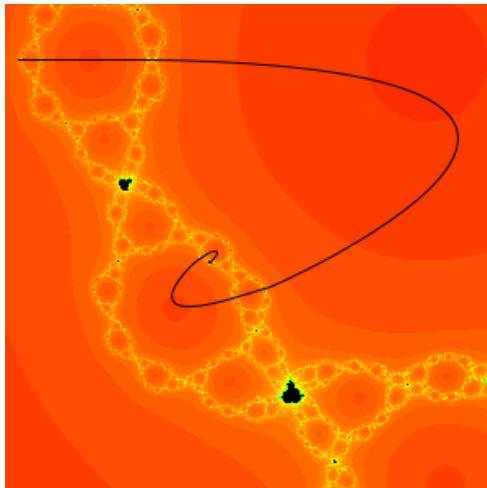
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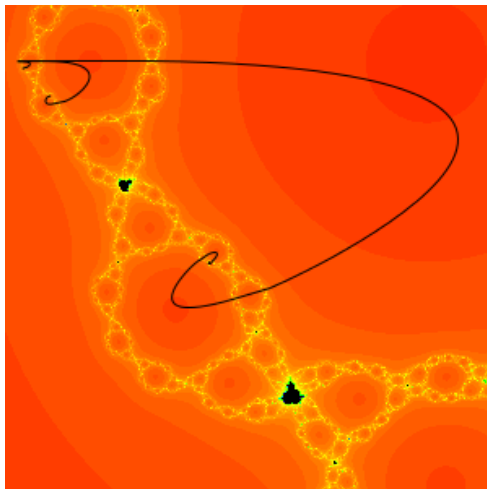
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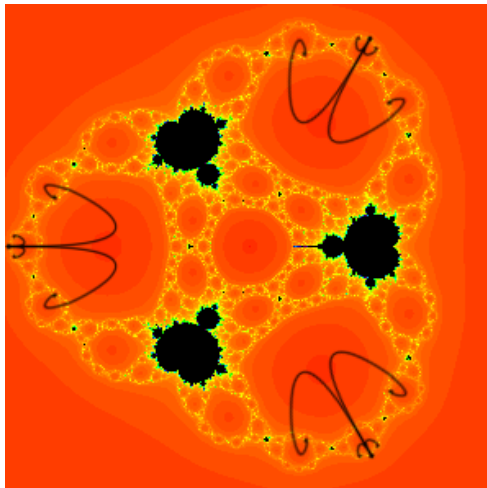
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We will find infinitely many Sierpinski Mandelbrot spirals.



Arcs and Spirals

We will find a Sierpinski Mandelbrot hydra.



Iterated Functions

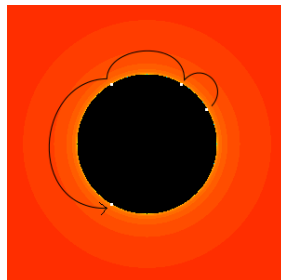
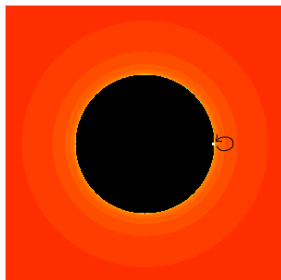
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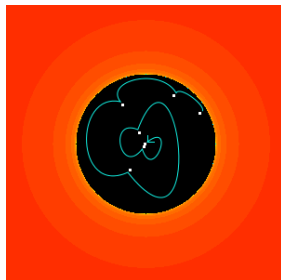
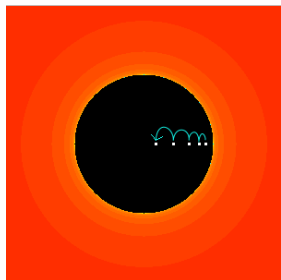
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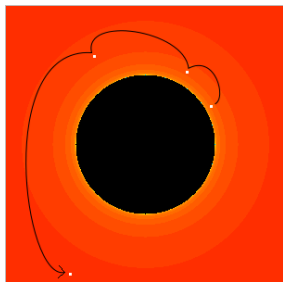
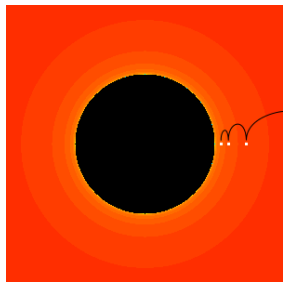
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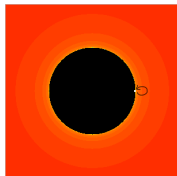
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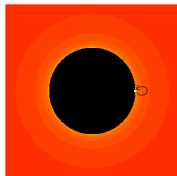
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Drawing the Dynamical Plane



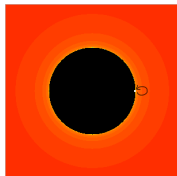
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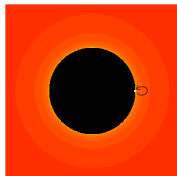
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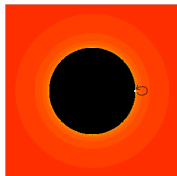
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- the Fatou Set, or $\mathcal{F}(F)$. This is the complement of $\mathcal{J}(F)$.

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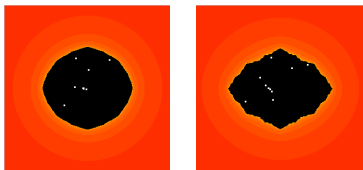


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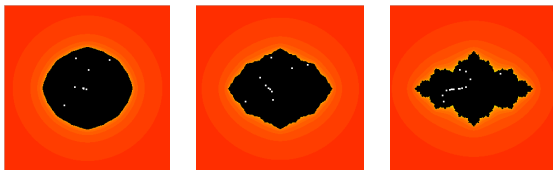


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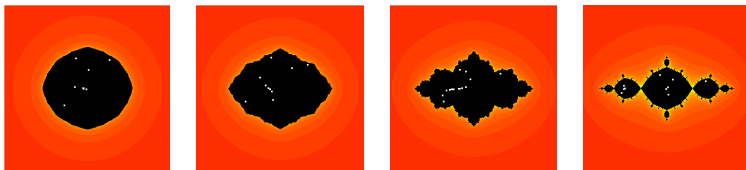


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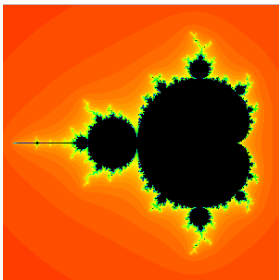
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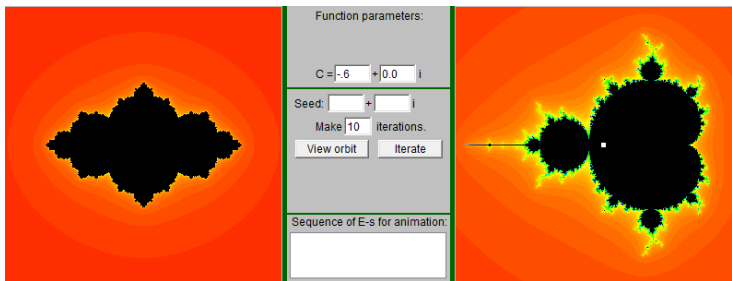
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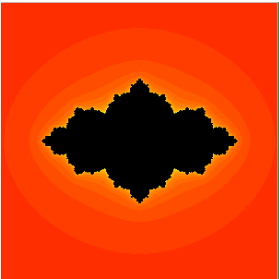
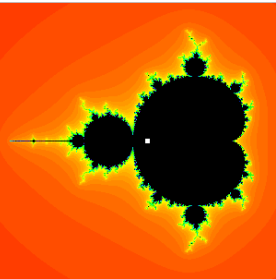
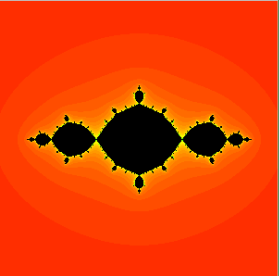
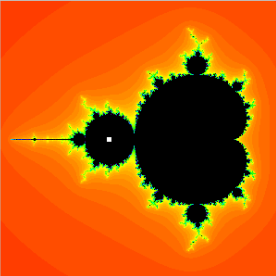
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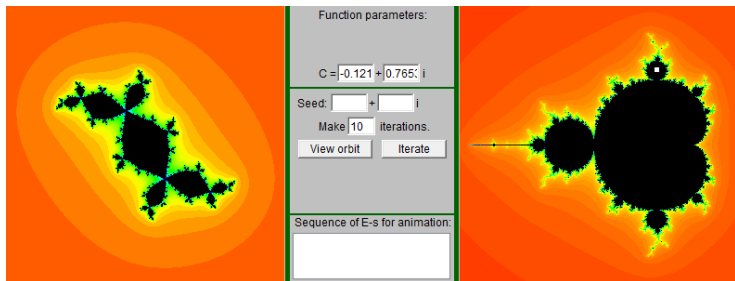
$\mathcal{J}(F_\lambda)$ Depends on λ



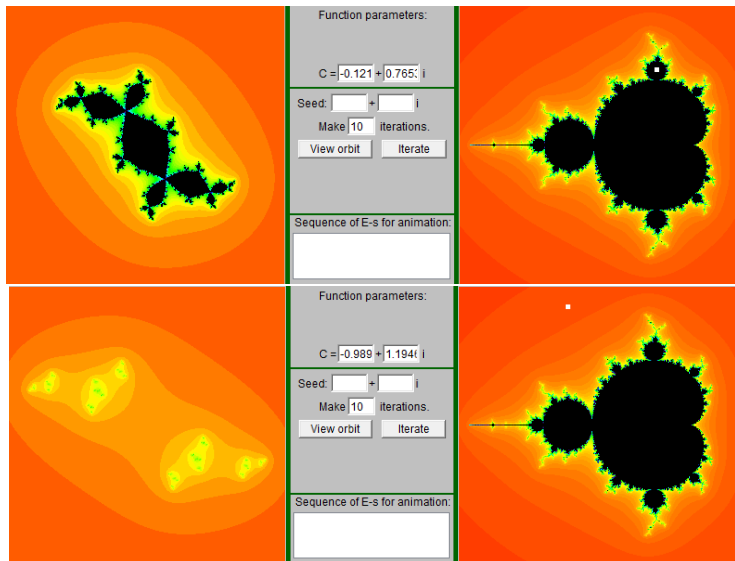
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- Critical values are the next iterates of critical points.

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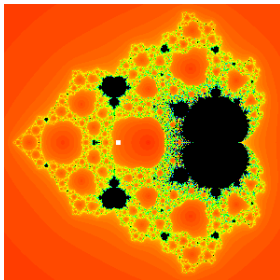
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- Following the same algorithm used to draw the Mandelbrot set:

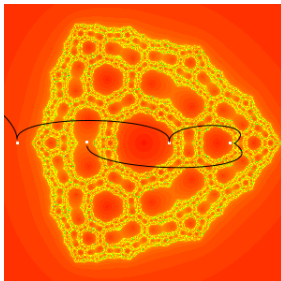
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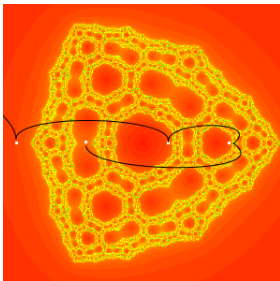
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The Basin and Trap Door

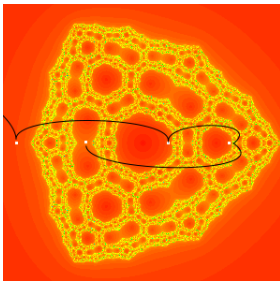


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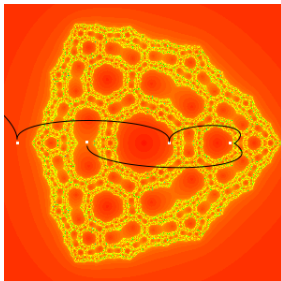
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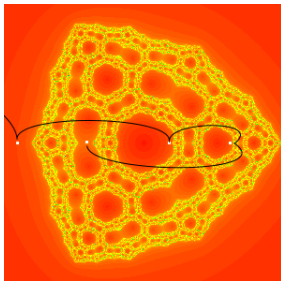
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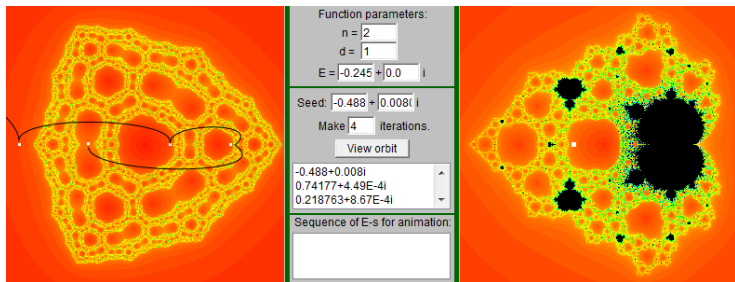
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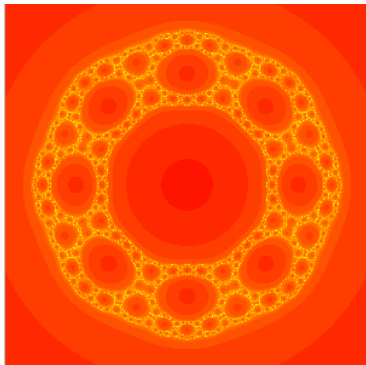
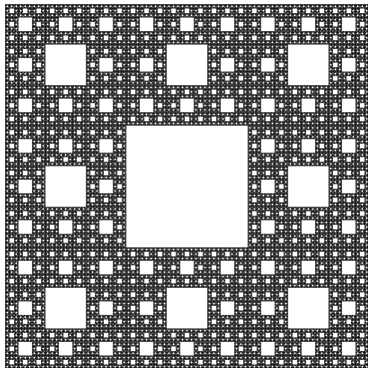
- For large enough z , each iterate will be larger. B_λ is the immediate basin of attraction of ∞ .
- For small enough z , the next iterate lands in the basin. If the preimage of B_λ surrounding the origin is disjoint from B_λ , we call this region the trap door (T_λ).

Sierpinski Holes



- $\mathcal{J}(F)$ is homeomorphic to a Sierpinski carpet fractal for λ in a Sierpinski hole.

Sierpinski Carpet Fractal



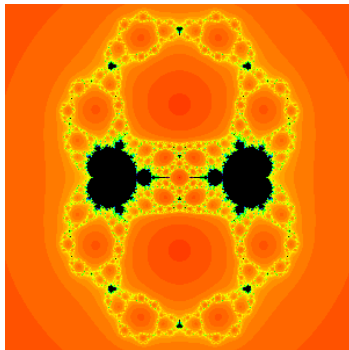
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$$F_\lambda(z) = z^3 + \lambda/z^3 \quad z, \lambda \in \mathbb{C}$$

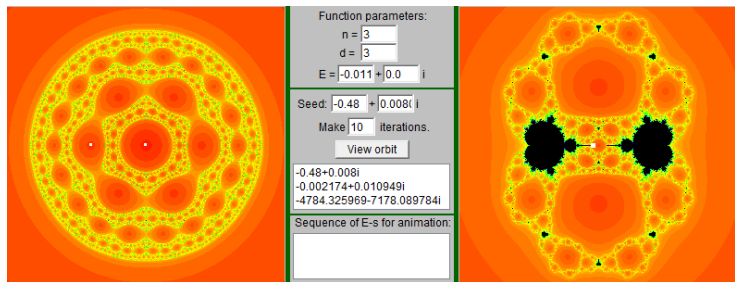
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The McMullen Domain



- $\mathcal{J}(F)$ is a Cantor set of simple closed curves.

Recap

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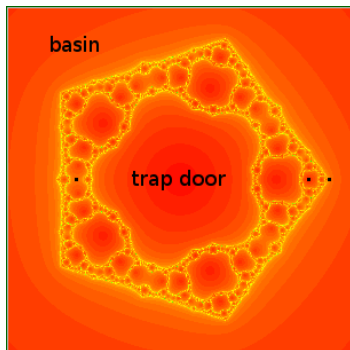
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- yellow is actually either black or not-black - zoom in.

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A Typical Dynamical Plane

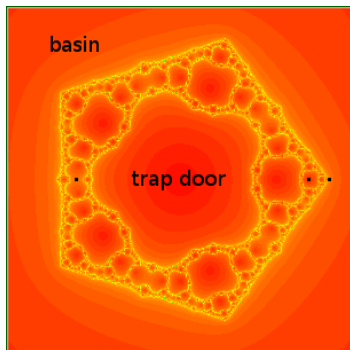
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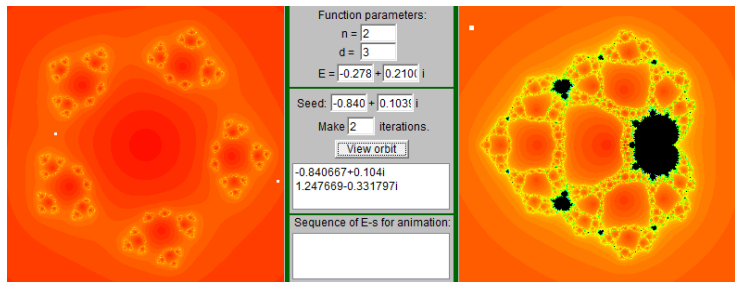
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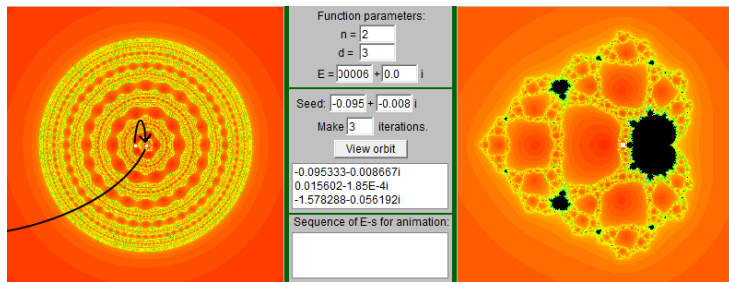
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- We can classify all of the regions in the parameter plane.

The Cantor Set Locus



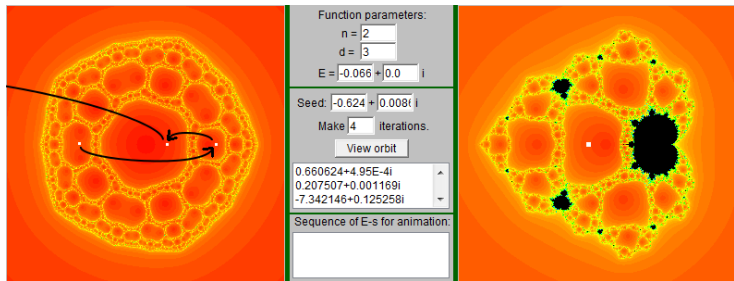
- c^λ lies in B_λ .

The McMullen Domain



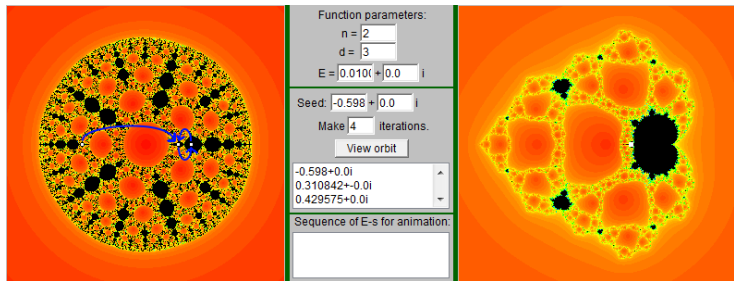
- c^λ enters T_λ after 1 iteration.

A Sierpinski Hole



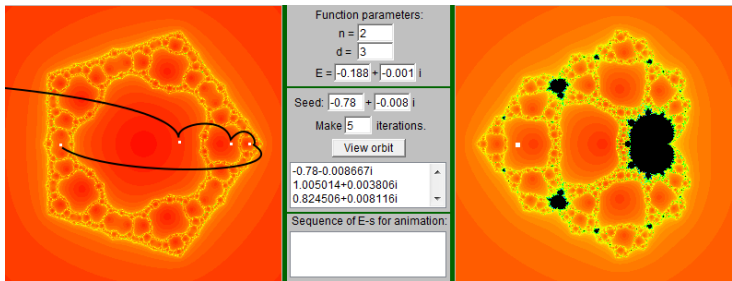
- c^λ enters T_λ after 2 iterations.

A Mandelbrot Set



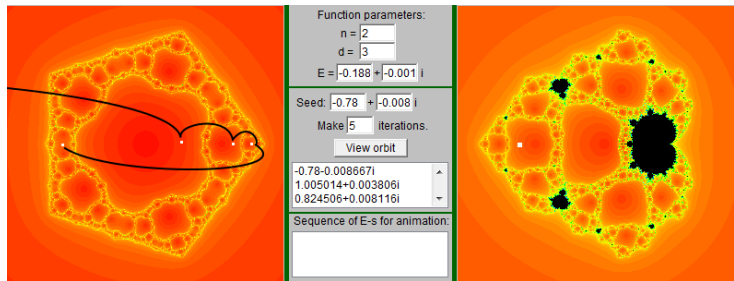
- c^λ does not escape and is instead trapped in some periodic orbit.

A Sierpinski Hole with Higher Escape Time



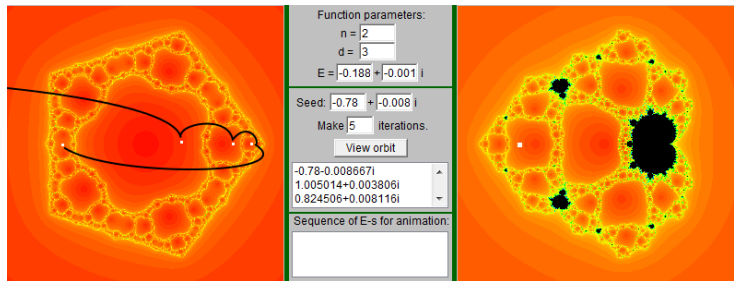
- For λ in the next Sierpinski hole to the left:

A Sierpinski Hole with Higher Escape Time



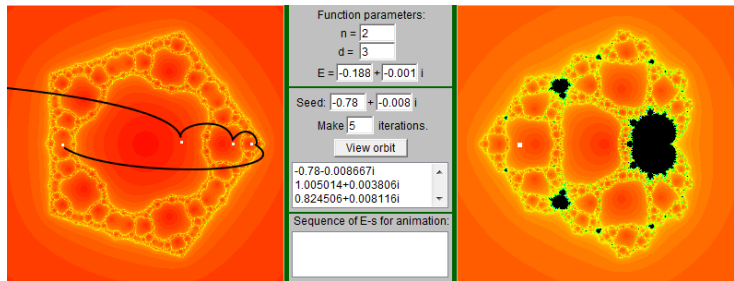
- For λ in the next Sierpinski hole to the left:
 c^λ enters T_λ at iteration 3.

A Sierpinski Hole with Higher Escape Time



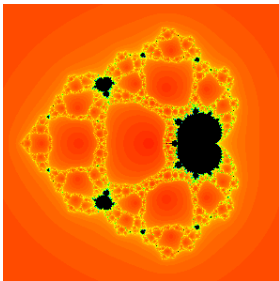
- For λ in the next Sierpinski hole to the left:
 c^λ enters T_λ at iteration 3.
- What about escape time of the next Sierpinski hole?

A Sierpinski Hole with Higher Escape Time



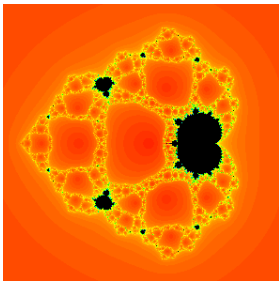
- For λ in the next Sierpinski hole to the left:
 c^λ enters T_λ at iteration 3.
- What about escape time of the next Sierpinski hole?
Anything besides Sierpinski holes?

Many Mandelbrot Sets



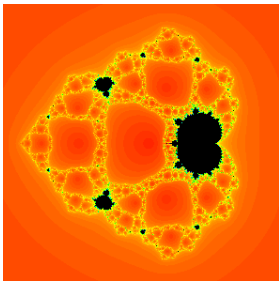
- There is the clearly visible principal Mandelbrot set.

Many Mandelbrot Sets



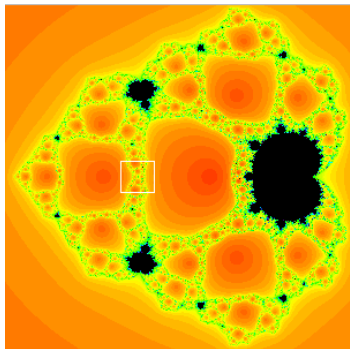
- There is the clearly visible principal Mandelbrot set.
- Also two baby Mandelbrot sets.

Many Mandelbrot Sets

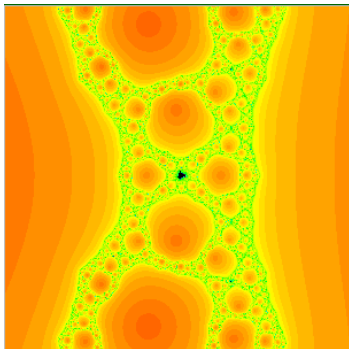
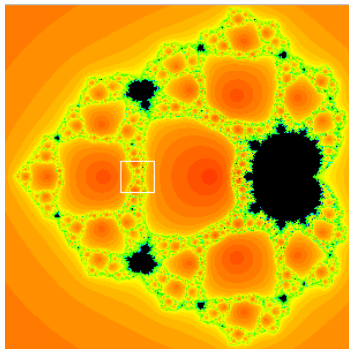


- There is the clearly visible principal Mandelbrot set.
- Also two baby Mandelbrot sets.
- Six more baby Mandelbrot sets.

Zooming In

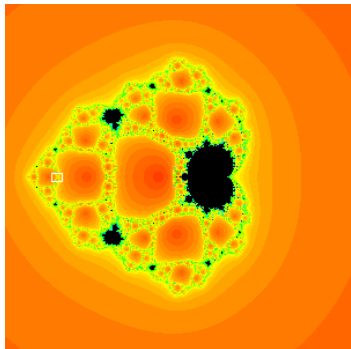


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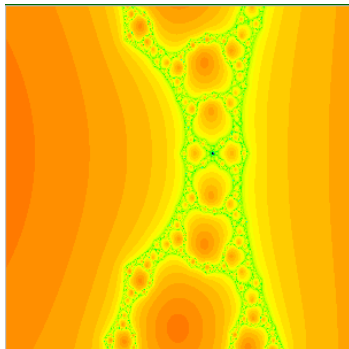
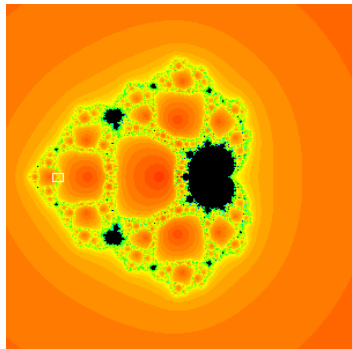


- There is a Mandelbrot between the Sierpinski holes of c^λ escape time 2 and 3.

Further Along \mathbb{R}^-



Further Along \mathbb{R}^-



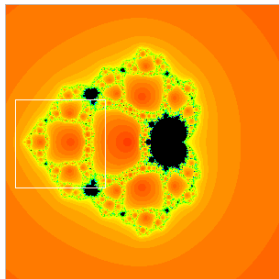
- Looks like another Mandelbrot set between the next pair of Sierpinski holes.

Claim

- There are infinitely many Sierpinski holes along the negative real axis of the parameter plane.

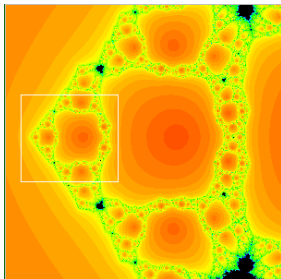
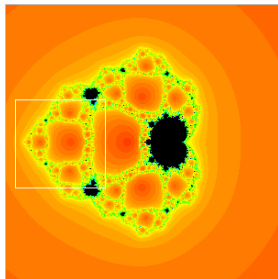
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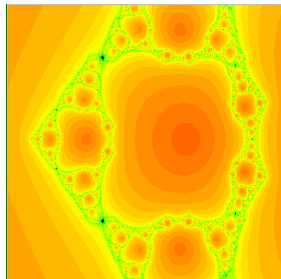
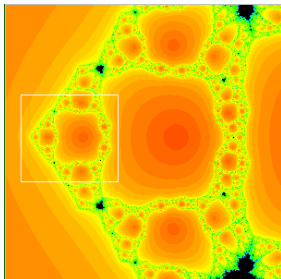
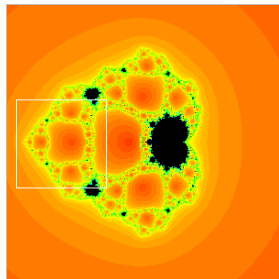
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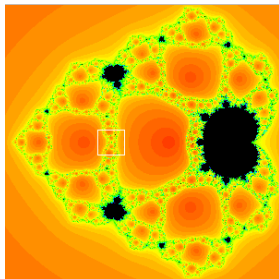


Claim

- Between each of the infinitely many pairs of Sierpinski holes is a Mandelbrot set.

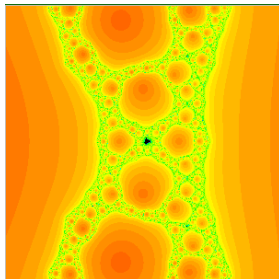
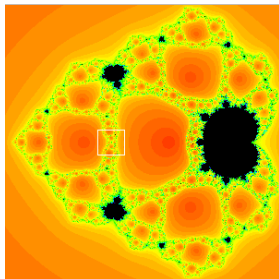
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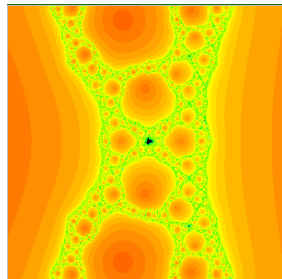
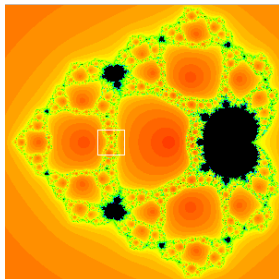
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- This set of infinitely many alternating Sierpinski holes and Mandelbrot sets along the negative real axis in the parameter plane is a *Sierpinski Mandelbrot arc*.

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- We prove some properties about those sets.
- We restrict λ to some subset of the entire parameter plane, and prove that the dynamical properties hold even if we move λ around.
- Then these dynamical constructs prove the existence of structures in that subset of the parameter plane.

Dynamical Constructs \implies Parameter Structures

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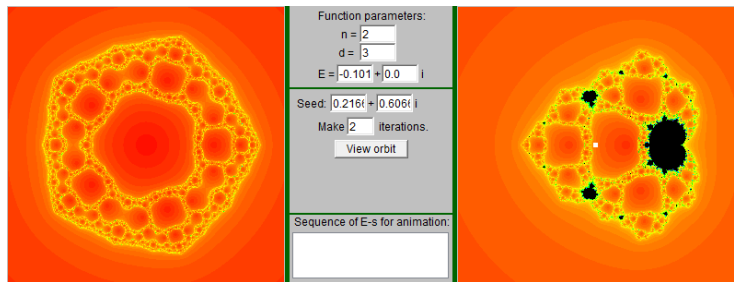
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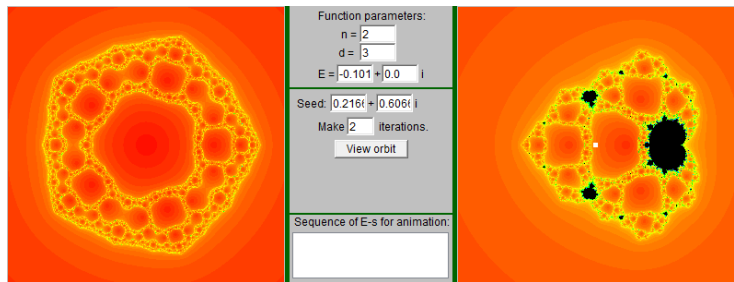
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- We need to find a set in the dynamical plane that maps 2-1 over another set. That (plus some other **conditions**) $\implies F_\lambda$ is a polynomial-like map of degree 2 on those sets. As shown by Douady and Hubbard, that proves the existence of a homeomorphic copy of the Mandelbrot set.

Dynamical Sets



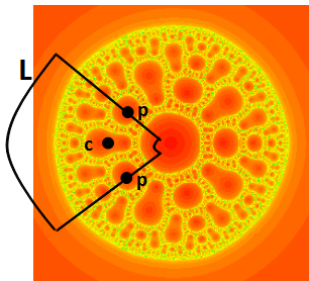
- The left image is the dynamical plane for $n = 2$, $d = 3$ and λ in a Sierpinski hole on the negative real axis.

Dynamical Sets



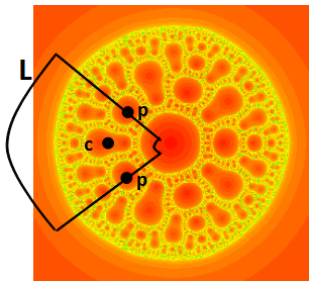
- The left image is the dynamical plane for $n = 2$, $d = 3$ and λ in a Sierpinski hole on the negative real axis.
- This λ is in the subset of the parameter plane ([details](#)).

The Left Wedge L^λ



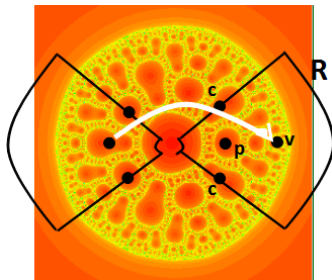
- Let the left wedge, or L^λ , be the closed set as shown.

The Left Wedge L^λ



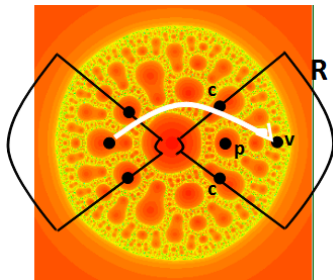
- Let the left wedge, or L^λ , be the closed set as shown.
- There is one critical point c_0^λ in the interior of L^λ .

The Right Wedge R^λ



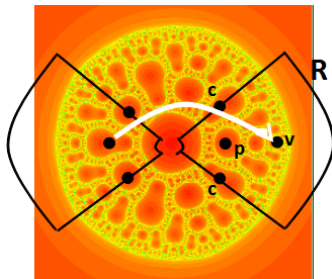
- Let R^λ be the symmetric right wedge.

The Right Wedge R^λ



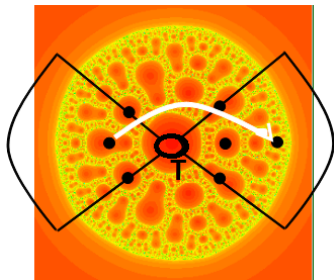
- Let R^λ be the symmetric right wedge.
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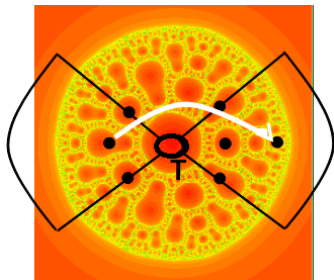
- Let R^λ be the symmetric right wedge.
- There is one prepole p_2^λ in the interior of R^λ .
- The critical point in L^λ maps to the critical value in R^λ .

The (Subset of the) Trapdoor $T_{\mathcal{A}}$



- Let $T_{\mathcal{A}}$ be the closed subset of the trapdoor containing 0 such that $L^{\lambda} \cup T_{\mathcal{A}} \cup R^{\lambda}$ are connected, and they only intersect along boundaries.

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- Let $T_{\mathcal{A}}$ be the closed subset of the trapdoor containing 0 such that $L^{\lambda} \cup T_{\mathcal{A}} \cup R^{\lambda}$ are connected, and they only intersect along boundaries.
- This union of the wedges and $T_{\mathcal{A}}$ will be referred to as the bowtie.

Proposition

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For each λ in that annular region:

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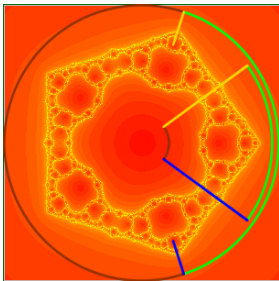
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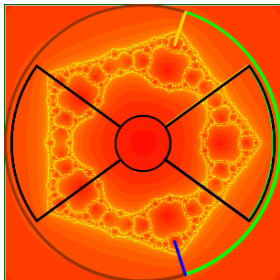
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2. F_λ maps L^λ 2-1 over a region that contains the interior of R^λ
3. As λ winds once around the boundary of the the annular region, the critical value $F_\lambda(c_0^\lambda)$ winds once around the boundary of R^λ .

R^λ Contains the Bowtie



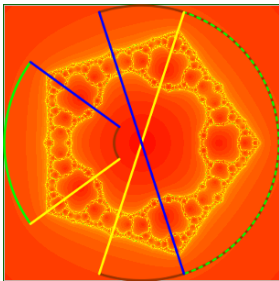
- For λ on \mathbb{R}^- , the image of R^λ is disjoint from the bowtie.

R^λ Contains the Bowtie



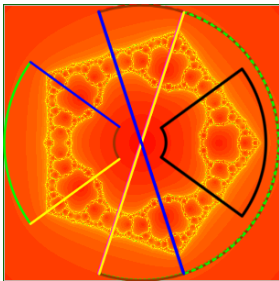
- For λ on \mathbb{R}^- , the image of R^λ is disjoint from the bowtie.
- This remains true as we rotate λ to the edges of the λ region.

L^λ Contains R^λ



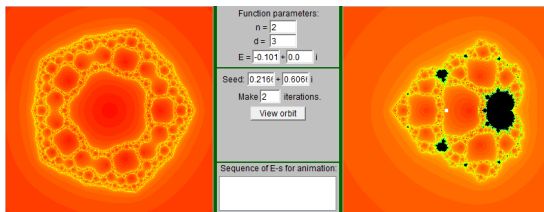
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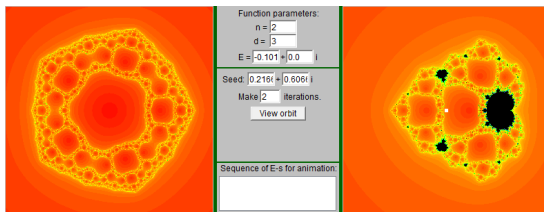


- For λ on \mathbb{R}^- , the image of L^λ is disjoint from R^λ .
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Drawing a Picture

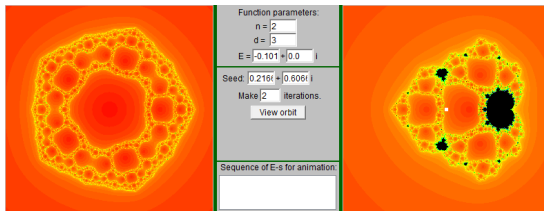


Drawing a Picture

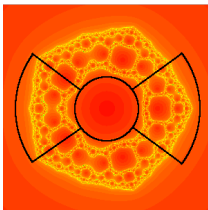


- We can “put a bowtie” on the dynamical plane.

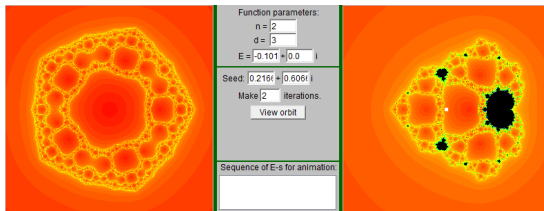
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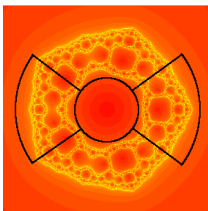
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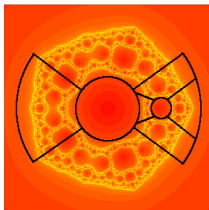
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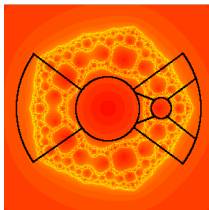


Bowties in bowties



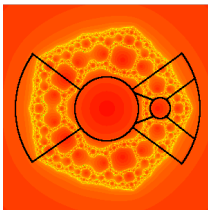
- This is the preimage of the bowtie inside R^λ .

Bowties in bowties



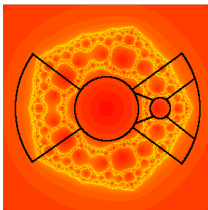
- This is the preimage of the bowtie inside R^λ .
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Bowties in bowties

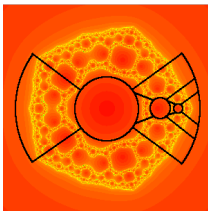


- This is the preimage of the bowtie inside R^λ .
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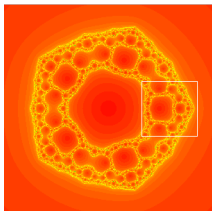
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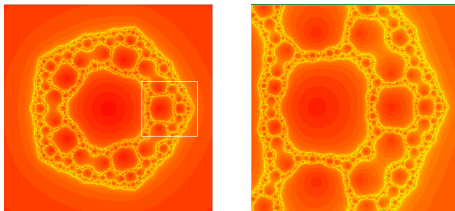
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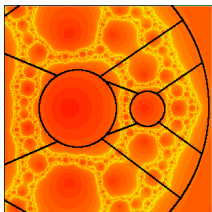
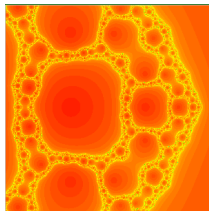
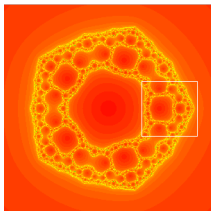
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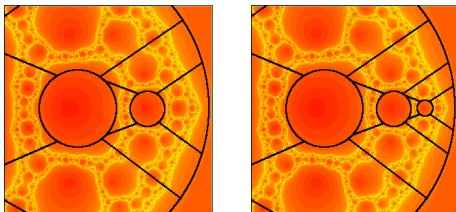
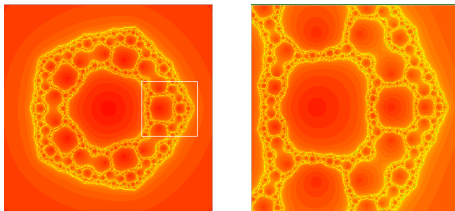
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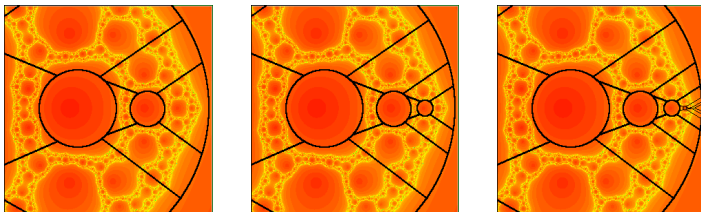
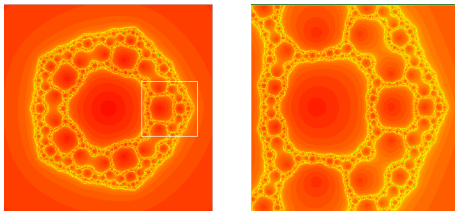
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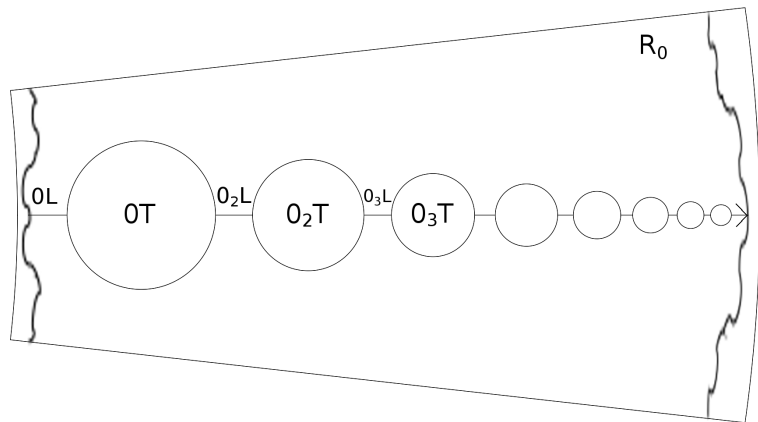
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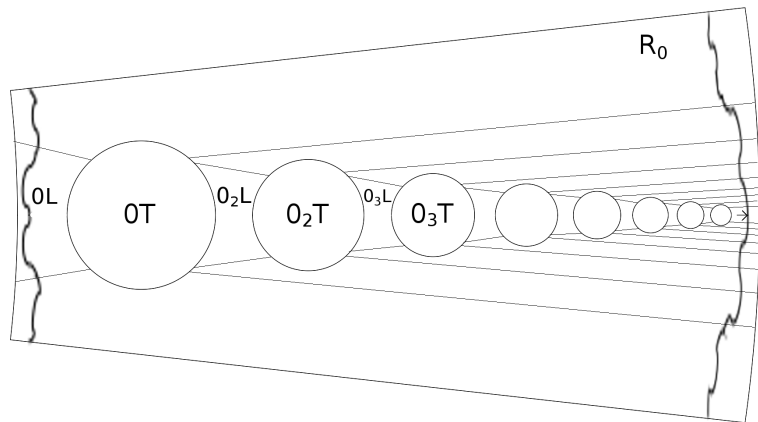


The Dynamical $\bar{0}TL$ Arc



- This is a stylized representation of the $\bar{0}TL$ arc in the dynamical plane.

The Dynamical $\bar{0}TL$ Arc



- This is a stylized representation of the $\bar{0}TL$ arc in the dynamical plane. With the wedges shown.

Dynamical TL Arc \implies Parameter SM Arc

- There is an arc of infinitely many alternating preimages of L^λ and $T_{\mathcal{A}}$ in R^λ in the dynamical plane.

Dynamical TL Arc \implies Parameter SM Arc

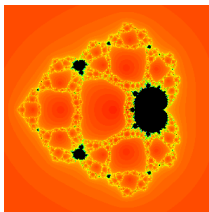
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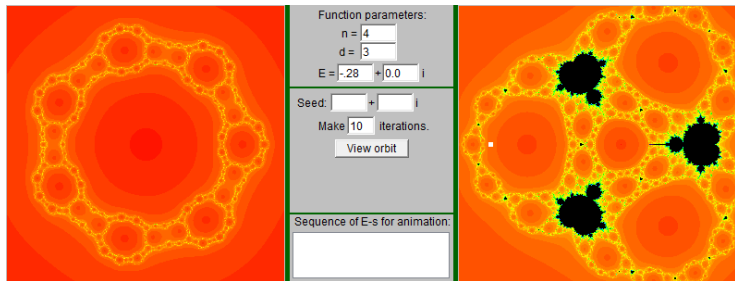
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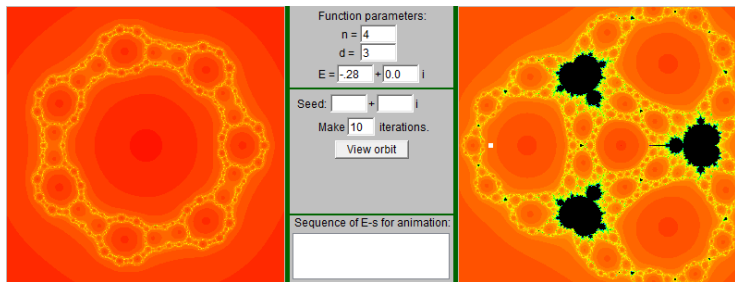
Outline

- 1 Introduction
- 2 A Sierpinski Mandelbrot Arc
- 3 A Different Sierpinski Mandelbrot Arc**
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$$n = 4, d = 3$$



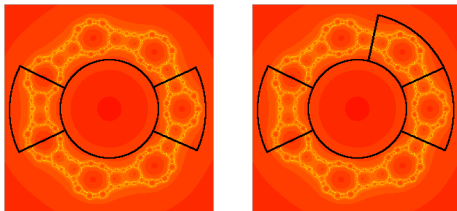
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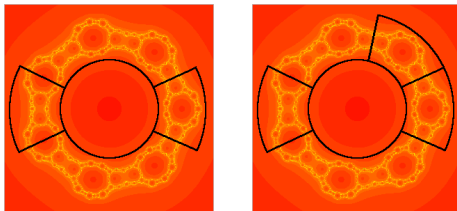
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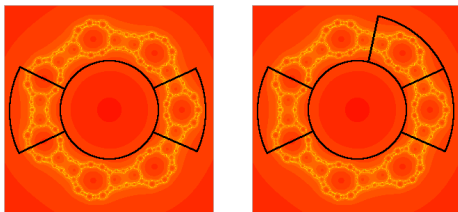


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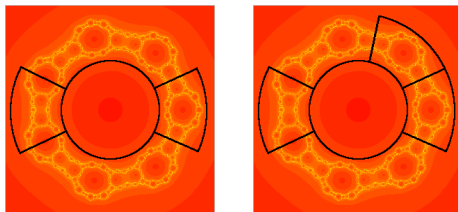
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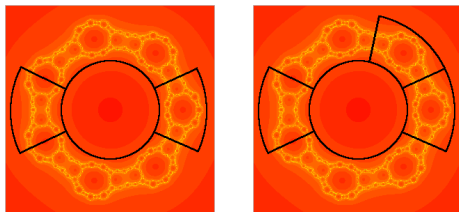
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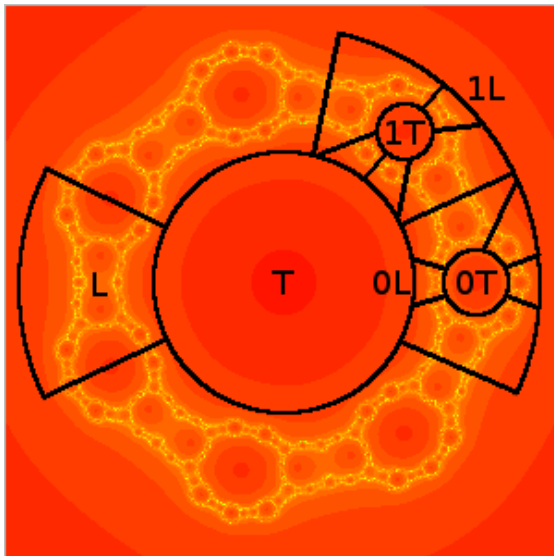
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- R_0^λ still contains a preimage of the lopsided bowtie. R_1^λ also contains a preimage, but rotated.

Labeling

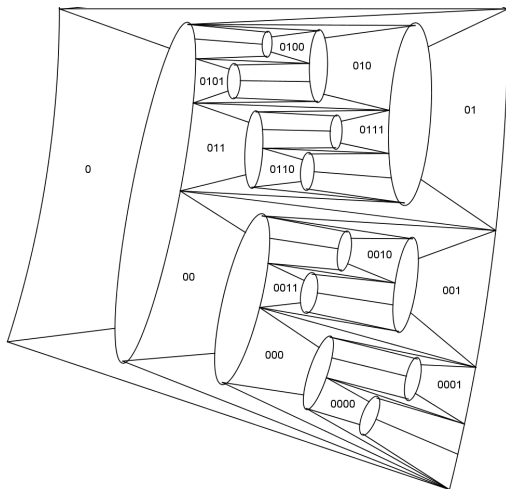


Scale is a Problem

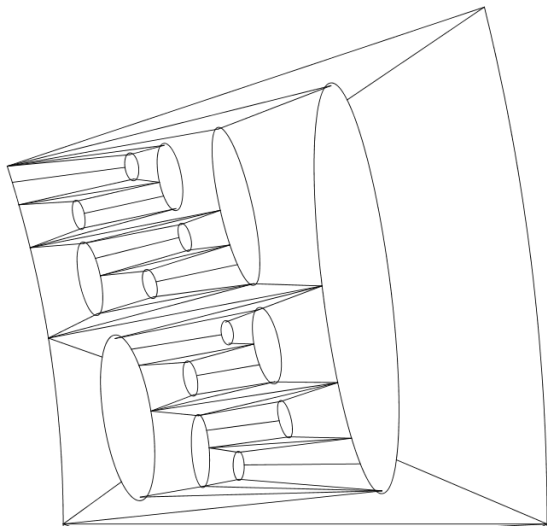
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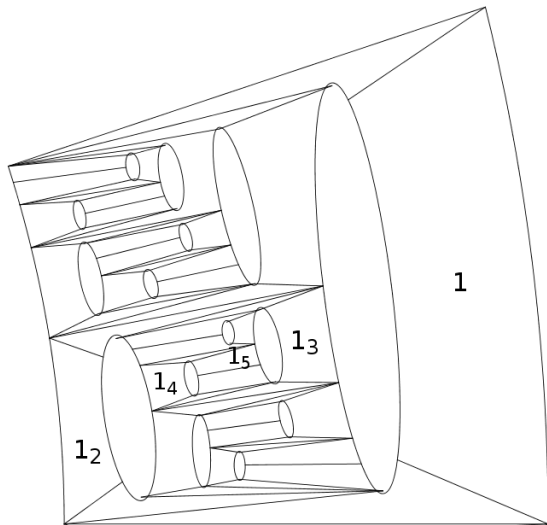
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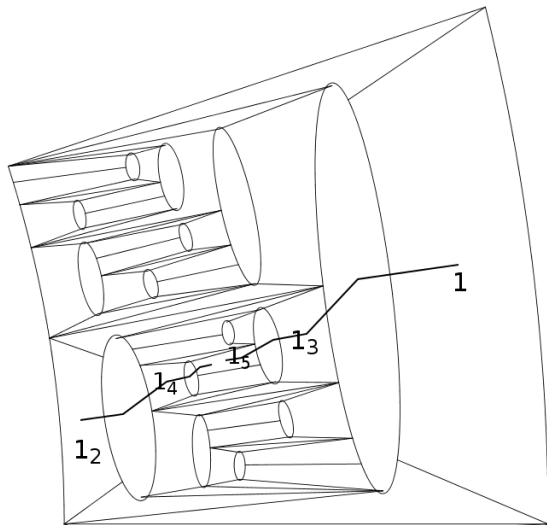
Looking for the Fixed Point in R_1^λ



Sequences of all 1's



Arc of all 1's



Two Arcs

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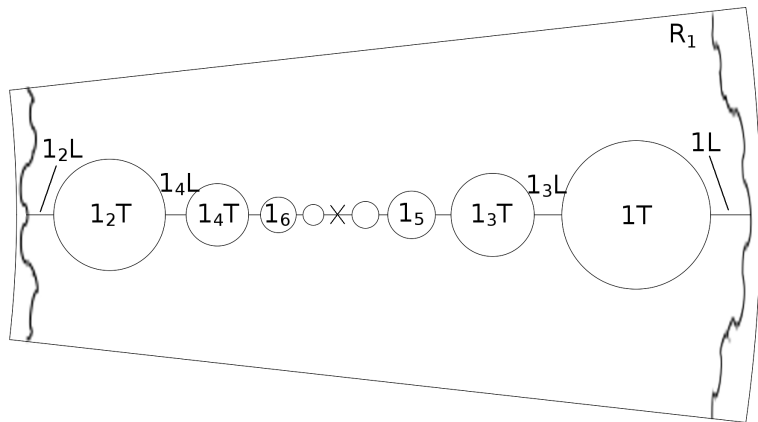
Two Arcs

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Two Arcs

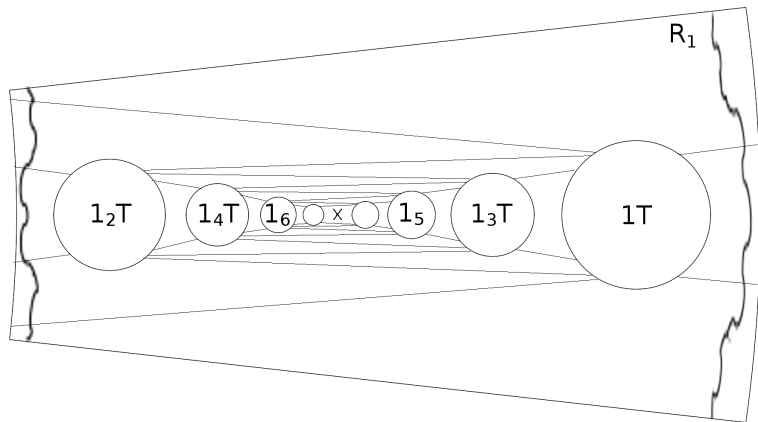
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- There exists a different $\bar{1}TL$ arc in R_1^λ for the rational map for $(4, 3)$ such that the arc grows from both the boundary in T_λ and the boundary in B_λ , and accumulates at the fixed point in the interior of R_1^λ .

The Dynamical \bar{ITL} Arc



- This is a stylized representation of the \bar{ITL} arc in the dynamical plane.

The Dynamical \bar{ITL} Arc

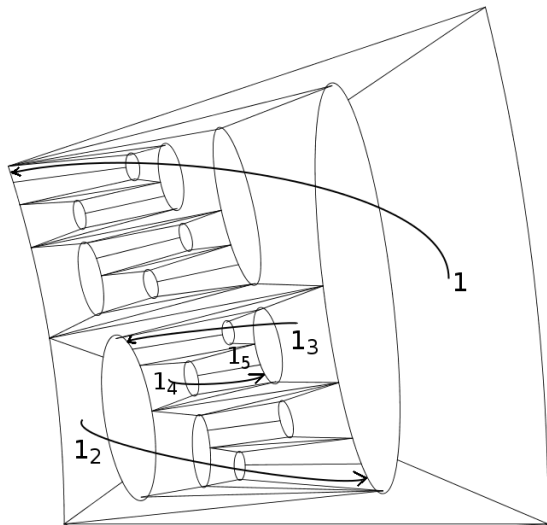


- This is a stylized representation of the \bar{ITL} arc in the dynamical plane. With the wedges shown.

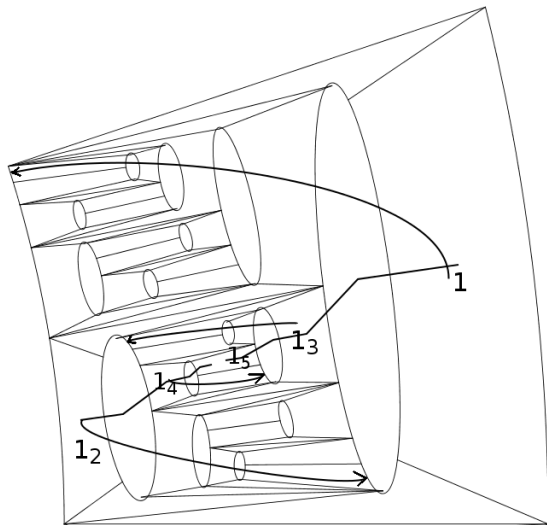
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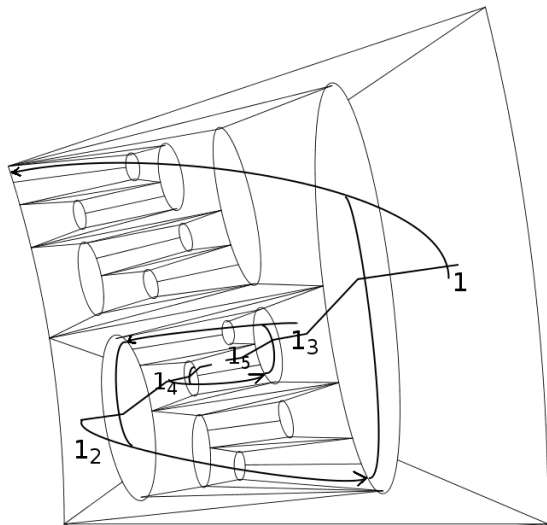
Infinitely many $\bar{0}TL$ arcs



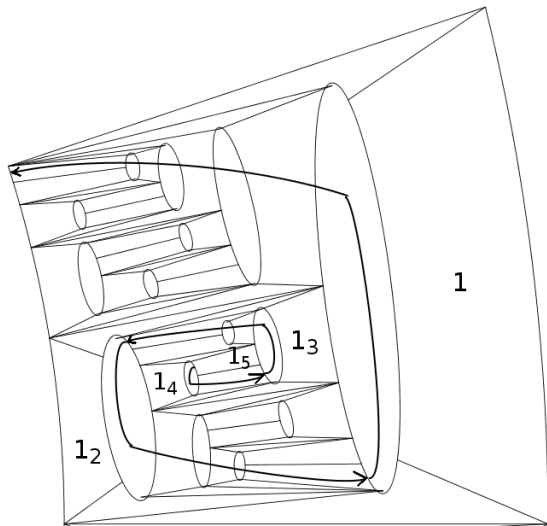
Infinitely Many $\bar{0}TL$ Arcs Intersecting the $\bar{1}TL$ Arc



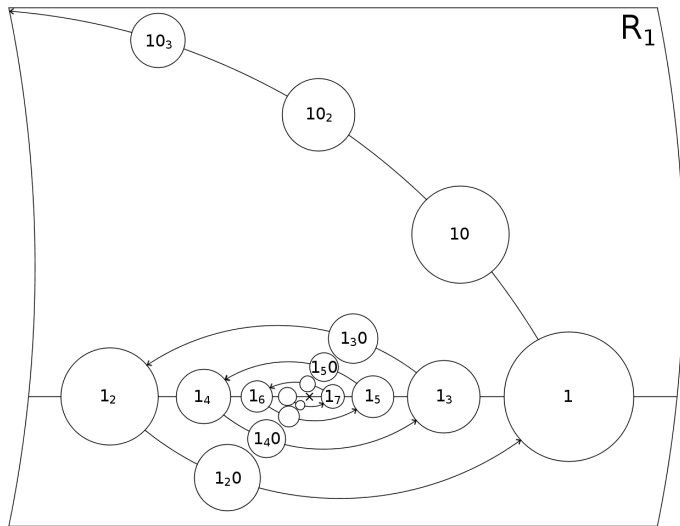
A Continuous Path for λ



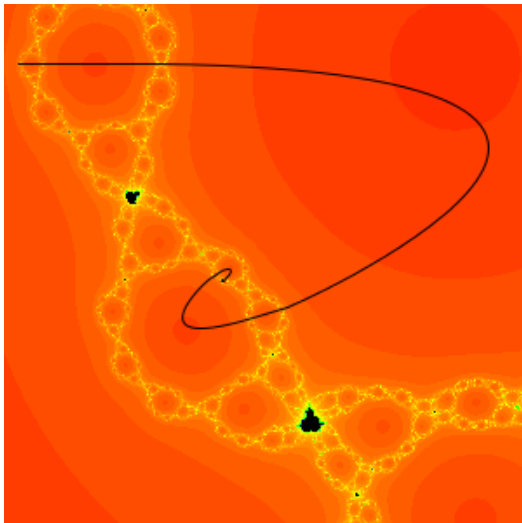
The $\bar{1}TL$ Spiral



Stylized $\bar{1}TL$ Spiral



The $0\bar{1}$ SM Spiral



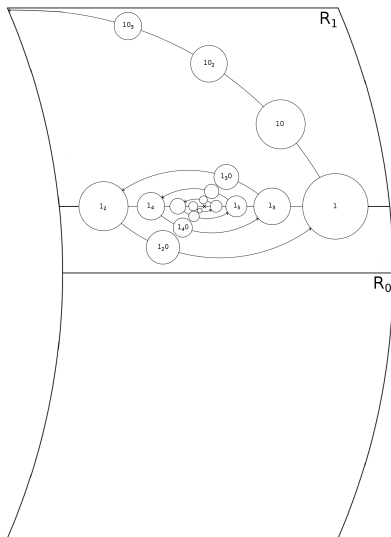
Mathematically Rigorous Statement

Theorem

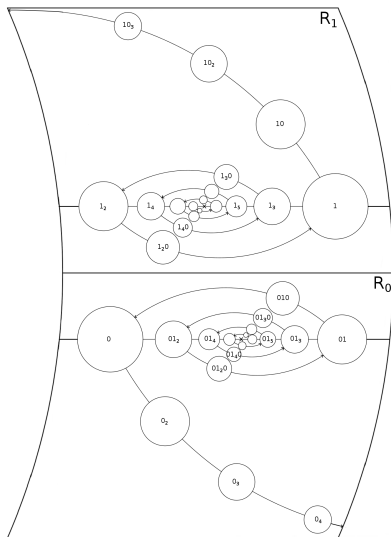
There exists a $0\bar{1}$ SM arc below the negative real axis in the parameter plane that consists of infinitely many Mandelbrot sets \mathcal{M}^k and infinitely many Sierpinski holes \mathcal{E}^k both with $k \geq 3$. k denotes the base period of \mathcal{M}^k and the escape time of \mathcal{E}^k .

Furthermore, there exists a $0\bar{1}$ SM spiral in the parameter plane that “spirals” from the Cantor set locus along infinitely many $\bar{0}$ type arcs while passing through each Sierpinski hole in the $0\bar{1}$ arc, and limits to λ such that $F_\lambda^2(c_0^\lambda)$ is the fixed point in R_1^λ .

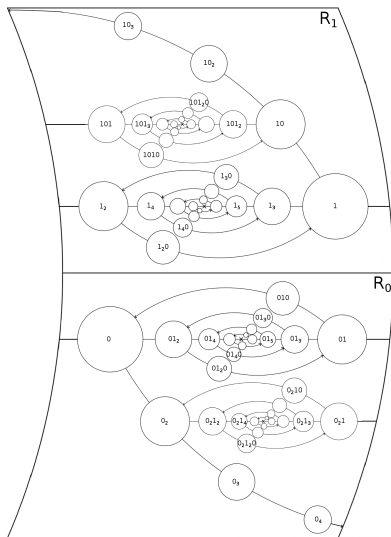
Infinitely Many TL Spirals



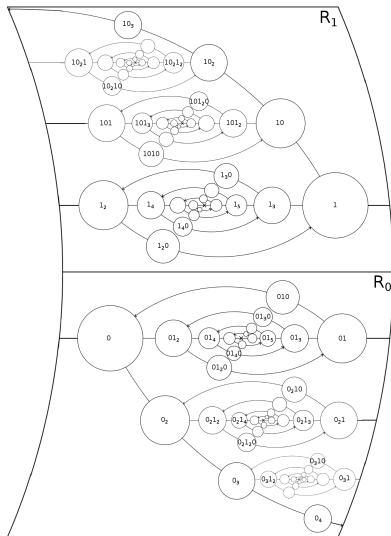
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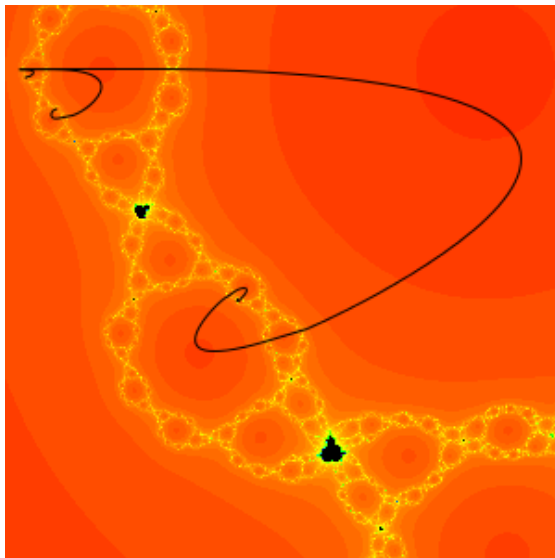
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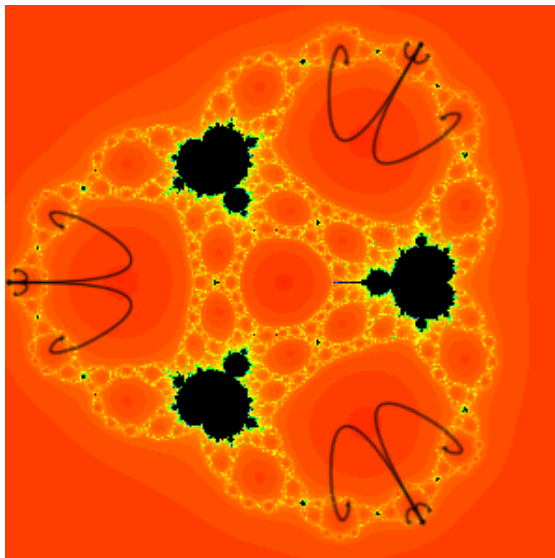
Infinitely Many TL spirals



Infinitely Many SM Spirals



Infinitely Many SM Spirals x6



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- Alternative upper right wedge \implies alternative $\bar{2}$ arc \implies alternative spiral for almost every exception.
- Alternative spirals exist for almost every (n, d) , not only exceptional cases.

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- There is probably some way to prove the existence of a SM spiral for the $(6, 3)$, $(4, 7)$ cases.
- We require n is even and d is odd, but there may be some way to tweak the argument to look at the case $n = d$ or n is odd, d is even.

The End

Thank you!

5 Details

Equivalent Definitions of the Julia Set

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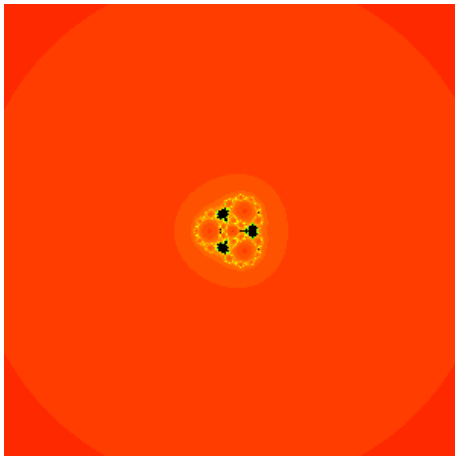
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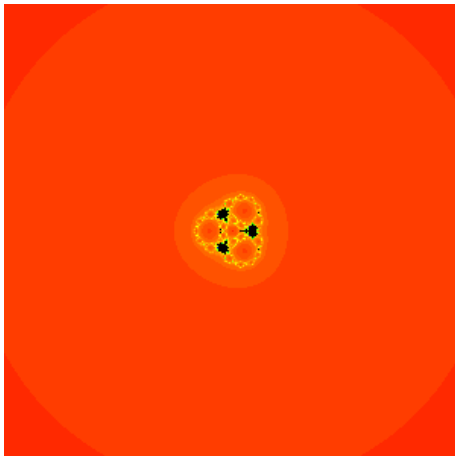
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λ Annulus



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back

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- [back](#)