

Day 19: July 29th

- **Chapter: 4.3 Undamped Forcing & Resonance**
- **Chapter: 5.1 Equilibrium Point Analysis**
- Homework:
 - Page 466 #1, 3, 7, 9, 11, 17, 23, 25.
- **Chapter: 5.2 Qualitative Analysis**
- Homework:
 - Page 481 #1-11 odd #17-21 odd
- **Midterm 3, Monday Aug. 2nd**
 - Chapters: 3,4 and 5.

Non-linear Systems

$$\frac{dx}{dt} = F(x, y)$$

$$\frac{dy}{dt} = G(x, y)$$

Generally very hard to solve

- Two techniques:
 - Linearization
 - Nullclines

- Example: Competing species

Populations that compete for the same resources

$$\frac{dx}{dt} = x \left(1 - \frac{x}{M} - a \frac{y}{M} \right)$$

$$\begin{cases} \frac{dx}{dt} = \frac{1}{M} x (M - x - ay) \\ \frac{dy}{dt} = \frac{1}{N} y (N - y - bx) \end{cases}$$

- Example: Competing species

$$\begin{cases} y' = \frac{1}{400}y\left(400 - y - \frac{3}{2}x\right) \\ x' = \frac{1}{400}x\left(400 - x - \frac{3}{2}y\right) \end{cases}$$

$$y = 0$$

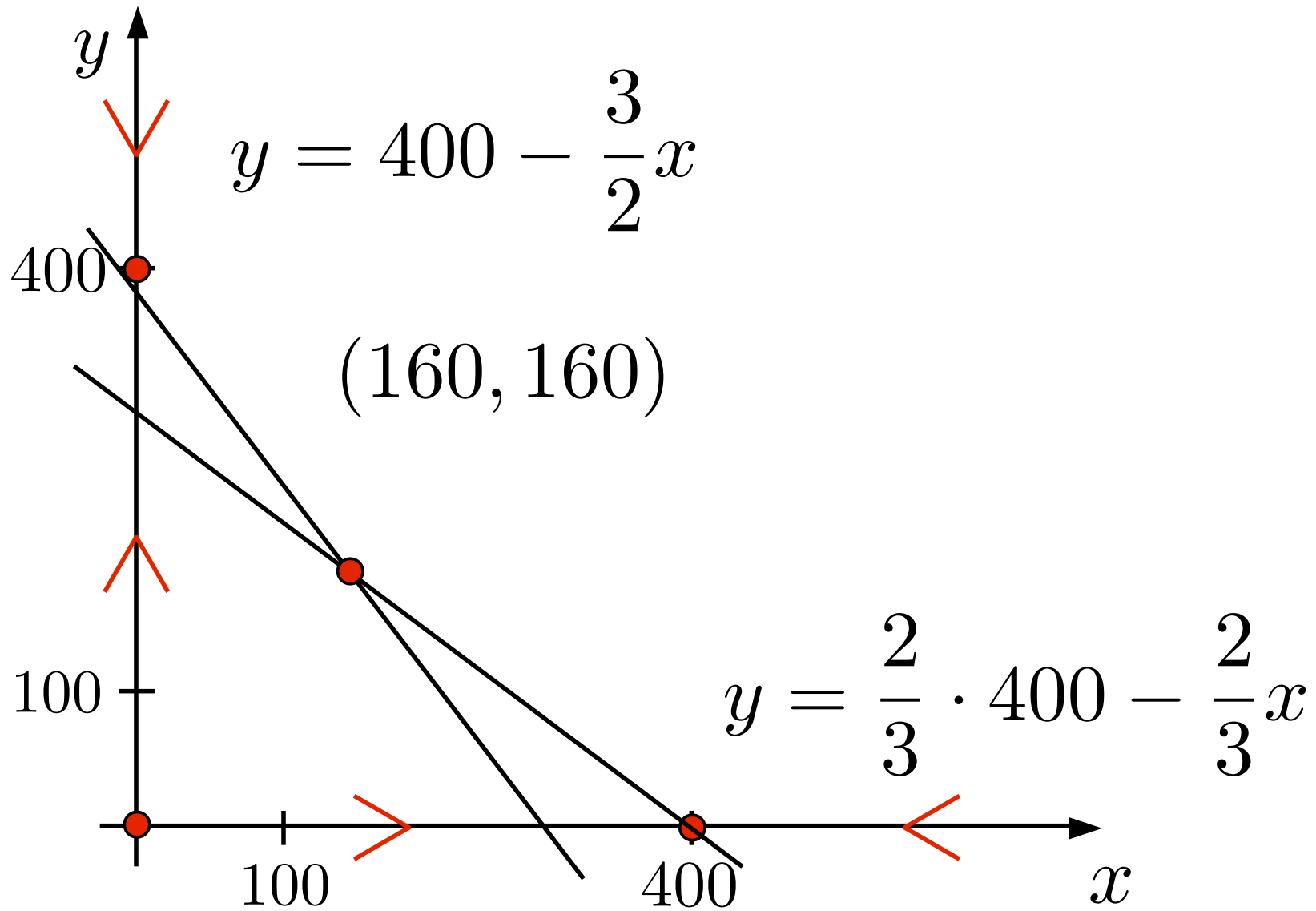
$$y = 400 - \frac{3}{2}x$$

$$x = 0$$

$$y = \frac{2}{3} \cdot 400 - \frac{2}{3}x$$

- Phase Lines:

• Phase Plane: Other Equilibrium Points



Equilibrium Points

What happens near equilibrium points?

We can “linearize” differential equations near equilibrium points

Jacobian Matrix

Near an equilibrium point a nonlinear system is “almost” linear

Find Jacobian matrix and evaluate at the equilibrium point

$$\mathbf{J} = \begin{pmatrix} \frac{\delta F}{\delta x} & \frac{\delta F}{\delta y} \\ \frac{\delta G}{\delta x} & \frac{\delta G}{\delta y} \end{pmatrix}$$

$$\vec{\mathbf{Y}}' = \mathbf{J} \cdot \vec{\mathbf{Y}}$$

- Example:

$$x' = -x = F(x, y)$$

$$y' = -4x^3 + y = G(x, y)$$

$$\mathbf{J} = \begin{pmatrix} \frac{\delta F}{\delta x} & \frac{\delta F}{\delta y} \\ \frac{\delta G}{\delta x} & \frac{\delta G}{\delta y} \end{pmatrix}$$

Equilibrium point: $(0, 0)$

Linearized System: $\vec{\mathbf{Y}}' = \mathbf{J} \cdot \vec{\mathbf{Y}}$

Evaluated at $(0, 0)$

• Example:

$$x' = -x = F(x, y)$$

$$y' = -4x^3 + y = G(x, y)$$

$$\mathbf{J} = \begin{pmatrix} \frac{\delta F}{\delta x} & \frac{\delta F}{\delta y} \\ \frac{\delta G}{\delta x} & \frac{\delta G}{\delta y} \end{pmatrix}$$

$$\mathbf{J} = \begin{pmatrix} -1 & 0 \\ -12x^2 & 1 \end{pmatrix} = \begin{pmatrix} -1 & 0 \\ 0 & 1 \end{pmatrix}$$

$$\vec{\mathbf{Y}}' = \begin{pmatrix} -1 & 0 \\ 0 & 1 \end{pmatrix} \vec{\mathbf{Y}}$$

- Example:

$$x' = -x + y^2 = F(x, y)$$

$$y' = x^2 + y = G(x, y)$$

Equilibrium point: $(0, 0)$

$$\mathbf{J} = \begin{pmatrix} \frac{\delta F}{\delta x} & \frac{\delta F}{\delta y} \\ \frac{\delta G}{\delta x} & \frac{\delta G}{\delta y} \end{pmatrix} = \begin{pmatrix} -1 & 2y \\ 2x & 1 \end{pmatrix}$$

$$= \begin{pmatrix} -1 & 0 \\ 0 & 1 \end{pmatrix}$$

Evaluated at $(0, 0)$

- Example:

$$x' = -x + y^2 = F(x, y)$$

$$y' = x^2 + y = G(x, y)$$

Linearized System:

$$\vec{Y}' = \begin{pmatrix} -1 & 0 \\ 0 & 1 \end{pmatrix} \vec{Y}$$

- Example:

$$x' = -x + y^2 = F(x, y)$$

$$y' = x^2 + y = G(x, y)$$

Equilibrium point: $(1, -1)$

$$\mathbf{J} = \begin{pmatrix} \frac{\delta F}{\delta x} & \frac{\delta F}{\delta y} \\ \frac{\delta G}{\delta x} & \frac{\delta G}{\delta y} \end{pmatrix} = \begin{pmatrix} -1 & 2y \\ 2x & 1 \end{pmatrix}$$
$$= \begin{pmatrix} -1 & -2 \\ 2 & 1 \end{pmatrix}$$

Evaluated at $(1, -1)$

- Example:

$$x' = -x + y^2 = F(x, y)$$

$$y' = x^2 + y = G(x, y)$$

Equilibrium point: $(1, -1)$

Linearized System:

$$\vec{\mathbf{Y}}' = \begin{pmatrix} -1 & -2 \\ 2 & 1 \end{pmatrix} \vec{\mathbf{Y}}$$