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## What is on today

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## 1 Introduction to Determinants

Lay–Lay–McDonald §3.1 pp. 166 – 169

Recall that we saw that a  $2 \times 2$  matrix is invertible if and only if its determinant is nonzero. To extend this useful fact to larger matrices, we need a definition for the determinant of an  $n \times n$  matrix. Let  $A = [a_{ij}]$  be an  $n \times n$  matrix.

When  $n = 1$ , we define  $\det A = a_{11}$ .

Recall that when  $n = 2$ , that is,  $A = \begin{bmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{bmatrix}$ , we have

$$\det A = a_{11}a_{22} - a_{12}a_{21}.$$

When  $n = 3$ , the determinant  $\det A$  is defined recursively using determinants of  $2 \times 2$  submatrices. That is, suppose  $A = \begin{bmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{bmatrix}$ . Then

$$\det A = a_{11} \det \begin{bmatrix} a_{22} & a_{23} \\ a_{32} & a_{33} \end{bmatrix} - a_{12} \det \begin{bmatrix} a_{21} & a_{23} \\ a_{31} & a_{33} \end{bmatrix} + a_{13} \det \begin{bmatrix} a_{21} & a_{22} \\ a_{31} & a_{32} \end{bmatrix}.$$

For brevity, we write this as

$$\det A = a_{11} \det A_{11} - a_{12} \det A_{12} + a_{13} \det A_{13},$$

where  $A_{11}$ ,  $A_{12}$ , and  $A_{13}$  are obtained from  $A$  by deleting the first row and one of the three columns. For any square matrix  $A$ , let  $A_{ij}$  denote the submatrix formed by deleting the  $i$ th row and  $j$ th column of  $A$ . Now we can give a recursive definition of determinants. When  $n = 4$ ,  $\det A$  uses determinants of  $3 \times 3$  submatrices, and in general, the determinant of an  $n \times n$  matrix is computed using determinants of  $(n - 1) \times (n - 1)$  submatrices.

**Definition 1.** For  $n \geq 2$ , the determinant of an  $n \times n$  matrix  $A = [a_{ij}]$  is the following:

$$\det A = \sum_{j=1}^n (-1)^{1+j} a_{1j} \det A_{1j}.$$

**Example 2.** Compute the determinant of  $A = \begin{bmatrix} 1 & 5 & 0 \\ 2 & 4 & -1 \\ 0 & -2 & 0 \end{bmatrix}$ .

To state the next theorem, it is convenient to write the definition of  $\det A$  in a slightly different form. Given  $A = [a_{ij}]$ , the  $(i,j)$ -cofactor of  $A$  is the number  $C_{ij}$  given by

$$C_{ij} = (-1)^{i+j} \det A_{ij}.$$

Then the formula we just wrote is

$$\det A = a_{11}C_{11} + a_{12}C_{12} + \cdots + a_{1n}C_{1n}.$$

This formula is called a *cofactor expansion across the first row of  $A$* .

**Theorem 3.** *The determinant of an  $n \times n$  matrix  $A$  can be computed by a cofactor expansion across any row or column. The expansion across the  $i$ th row is*

$$\det A = a_{i1}C_{i1} + a_{i2}C_{i2} + \cdots + a_{in}C_{in}.$$

*The expansion down the  $j$ th column is*

$$\det A = a_{1j}C_{1j} + a_{2j}C_{2j} + \cdots + a_{nj}C_{nj}.$$

The theorem tells us that we have some flexibility in computing the determinant: by picking a favorable row or column (e.g., one with many zeros), we can cut down on the number of computations we have to do.

**Example 4.** Compute  $\det A$ , where  $A = \begin{bmatrix} 3 & -7 & 8 & 9 & -6 \\ 0 & 2 & -5 & 7 & 3 \\ 0 & 0 & 1 & 5 & 0 \\ 0 & 0 & 2 & 4 & -1 \\ 0 & 0 & 0 & -2 & 0 \end{bmatrix}$ .

The previous example motivates the following useful result:

**Theorem 5.** *If  $A$  is a triangular matrix, then  $\det A$  is the product of the entries on the main diagonal of  $A$ .*

## 2 Properties of Determinants

Lay–Lay–McDonald §3.2 pp. 171 – 177

The properties of determinants are governed by row operations. Here are some useful results:

**Theorem 6.** *Let  $A$  be a square matrix.*

1. *If a multiple of one row of  $A$  is added to another row to produce a matrix  $B$ , then  $\det B = \det A$ .*
2. *If two rows of  $A$  are swapped to produce  $B$ , then  $\det B = -\det A$ .*
3. *If one row of  $A$  is multiplied by  $k$  to produce  $B$ , then  $\det B = k \cdot \det A$ .*

Suppose a square matrix  $A$  has been reduced to an echelon form  $U$  by row replacements and row swaps. (This is always possible by the row reduction algorithm.) If there are  $r$  swaps, the previous theorem tells us that

$$\det A = (-1)^r \det U.$$

Moreover, since  $U$  is in echelon form, it is triangular, and so  $\det U$  is the product of the diagonal entries  $u_{ii}$ . If  $A$  is invertible, the entries  $u_{ii}$  are all pivots (because  $A \sim I_n$  and the  $u_{ii}$  have not been scaled to 1s). Otherwise, at least  $u_{nn}$  will be zero, and the product of diagonal entries will be 0. This gives us

$$\det A = \begin{cases} (-1)^r \cdot (\text{product of pivots in } U) & \text{when } A \text{ is invertible} \\ 0 & \text{when } A \text{ is not invertible.} \end{cases}$$

The formula above proves the following theorem:

**Theorem 7.** *A square matrix  $A$  is invertible if and only if  $\det A \neq 0$ .*

**Example 8.** *Compute  $\det A$ , where  $A = \begin{bmatrix} 3 & -1 & 2 & -5 \\ 0 & 5 & -3 & -6 \\ -6 & 7 & -7 & 4 \\ -5 & -8 & 0 & 9 \end{bmatrix}$ .*

Here are some further useful properties of determinants:

**Theorem 9.** *If  $A$  is an  $n \times n$  matrix, then  $\det A^T = \det A$ .*

**Theorem 10.** *If  $A$  and  $B$  are  $n \times n$  matrices, then  $\det AB = (\det A)(\det B)$ .*