

Lie(G) := $T_1 G \cong \{\text{left-G-invariant vector fields}\}$.

Integrating along $X \in \text{Lie}(G)$ gets a

one-parameter subgroup of diffeomorphisms $\exp^t X = \exp tX : G \rightarrow G$.

$(\exp(s+t)X = \exp sX \circ \exp tX)$

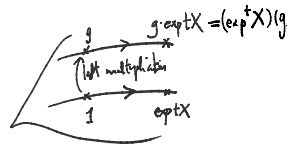
$X \in \text{Lie}(G)$ is complete: walk a bit, and left multiplication by the endpoint

Abuse of notation: under the diffeomorphism $\exp tX$, denote $1 \mapsto \exp tX \in G$.

This defines **exp: g → G**. (Don't even use metric!)

Since X is left-invariant, the diffeomorphism $\exp^t X$ is $g \mapsto g \exp tX$ (right multiplication.)

$d\exp|_0 = \text{Id}$. Hence \exp is a local diffeomorphism.



Def: $\begin{cases} \frac{d}{dt}(\exp^t X)(g) = X|_{\exp^t X}(g) \\ (\exp^t X)(g) = g \end{cases}$

Denote $(\exp^t X)(1) = \exp^t X$.

$(\exp^t X)(g) = g \cdot \exp^t(X)$:

$\begin{cases} \frac{d}{dt}(g \cdot \exp^t(X)) = g \cdot (X|_{\exp^t X}) = X|_{g \cdot \exp^t X} \\ g \exp^t(X) = g \end{cases}$

Denote $\exp^t X = \exp^t X$.

$\exp^t X = \exp^t X$:

$\exp^t X = \exp^{ts} X$ since both satisfy the same D.E.

$\frac{d}{ds} \exp^s tX = t \cdot X|_{\exp^s tX}$

$\frac{d}{ds} \exp^{ts} X = t \cdot X|_{\exp^{ts} X}$

$\exp^{st} X = \exp^s X \exp^t X$:

$\begin{cases} \frac{d}{dt} \exp^t X \exp^s X = (\exp^t X)_* X|_{\exp^s X} = X|_{\exp^t X \exp^s X} \\ \exp^t X \exp^s X|_{t=0} = \exp^s X \end{cases}$

$\exp^{st} X$ satisfies the same D.E.

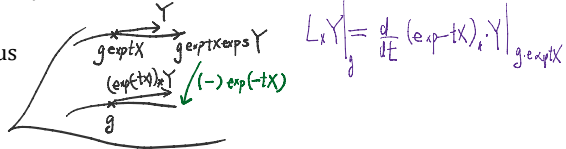
Lie bracket on $\text{Lie}(G)$: $[X, Y] = L_X Y$ (Lie derivative).

Lie derivative satisfies $[X, Y] = -[Y, X]$ and Jacobi identity.

$L_X Y$ is still left-invariant:

$L_X Y|_g = \frac{d}{dt} \Big|_{t=0} \frac{d}{ds} \Big|_{s=0} g \exp tX \exp sY \exp(-tX)$. Thus

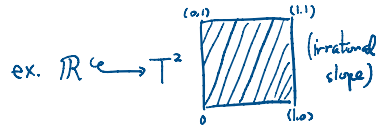
$h L_X Y|_g \cong L_X Y|_{hg}$.



$\text{Lie}(G)$ is a **Lie algebra**: a vector space with $[-, -]$.

Lie subalgebra: subspace closed under $[-, -]$.

Lie subgroup H: Image of an injective group homomorphism to G which is an **immersion**. (NOTE: NEED NOT EMBEDDED, that is, may not be homeomorphism to image!)



Theorem:

Subalgebra of $\text{Lie}(G) \iff$ connected Lie subgroup of G.

\leftarrow is trivial: take tangent space at 1. Closed under Lie bracket since H is a submanifold near 1.

\rightarrow follows from the **Frobenius theorem** in differential topology:

A sub-bundle of TM whose sheaf of local sections are closed under $[-, -]$ integrates to a foliation.

Then take the leaf containing 1. It is closed under multiplication:

suppose $g, h \in \text{leaf}_1$. $g \cdot h = L_g \cdot h \in L_g \cdot \text{leaf}_1 = \text{leaf}_g = \text{leaf}_1$.

(Foliation: a collection of disjoint connected immersed submanifolds (called leaves) whose union is the whole space M, and can take local coordinates x_1, \dots, x_n of M such that the leaves are given by taking x_{k+1}, \dots, x_n to be constants.)

Closed subgroup theorem:

A closed subgroup H of G must be a submanifold (that is embedded).

(Note: don't need H to be Lie subgroup in the condition.)

Topology + group str.

\implies smooth str.

Proof:

Need to restrict charts of G to charts of H at all $h \in H$. Consider an open set U of g where \exp is a diffeomorphism.

Want to argue $h \cdot \exp$ restricted to $U \cap \mathfrak{h}$ provides a chart of H. Need to define \mathfrak{h} !

$\mathfrak{h} := \{X \in \mathfrak{g} : \exp tX \in H \text{ for all } t \in \mathbb{R}\}$.

$\mathfrak{h} \subset \mathfrak{g}$ is a vector subspace: $0 \in \mathfrak{h}$. Closed under scaling.

$X + Y \in \mathfrak{h}$ if X and Y are: consider $\exp t(X + Y)$.

TRICKY: $\exp t(X + Y) \neq (\exp tX)(\exp tY)$!

For t small,

$(\exp tX)(\exp tY) = \exp(\phi(t))$ for some smooth path ϕ . ($\phi(0) = 0$.)

Take $\frac{d}{dt} \Big|_{t=0}$, get $\phi'(0) = X + Y$. Thus $\phi = t(X + Y) + t^2 Z(t)$.

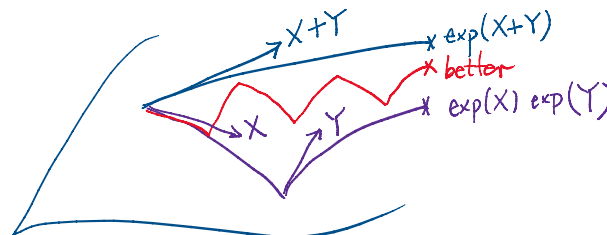
Replace t by $\frac{t}{n}$:

$\left(\exp \frac{tX}{n} \exp \frac{tY}{n} \right)^n = \exp \left(t(X + Y) + \frac{t^2}{n} Z \left(\frac{t}{n} \right) \right)$ and hence

$\lim_{n \rightarrow \infty} \left(\exp \frac{tX}{n} \exp \frac{tY}{n} \right)^n = \exp t(X + Y)$

Since H is closed, LHS belongs to H.

Thus $\mathfrak{h} \subset \mathfrak{g}$ is a vector subspace.

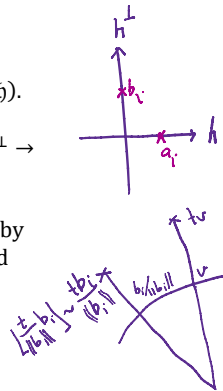


Need to take U sufficiently small such that $\exp(U \cap \mathfrak{h}) = (\exp U) \cap H$. (Always have $\exp(U \cap \mathfrak{h}) \subset (\exp U) \cap H$.) Then $h \cdot \exp$ restricted to $U \cap \mathfrak{h}$ provides a chart of H around h.

\mathfrak{h}^\perp
↑

Need to take U sufficiently small such that $\exp(U \cap \mathfrak{h}) = (\exp U) \cap H$. (Always have $\exp(U \cap \mathfrak{h}) \subset (\exp U) \cap H$.) Then $h \cdot \exp$ restricted to $U \cap \mathfrak{h}$ provides a chart of H around h . Assume such U does not exist. Then have a sequence of points in H converging to 1 but not in $\exp(U \cap \mathfrak{h})$. Take a metric on \mathfrak{g} and $\mathfrak{g} = \mathfrak{h} \oplus \mathfrak{h}^\perp$. Then the points can be written as $(\exp a_i)(\exp b_i)$ for $a_i \in \mathfrak{h}$ and $b_i \in \mathfrak{h}^\perp$ (since $(\exp a)(\exp b): \mathfrak{h} \times \mathfrak{h}^\perp \rightarrow G$ is local diffeo).

NOTE THAT $\exp b_i \in H$ since $(\exp a_i)(\exp b_i) \in H$. But still $\exp b_i/m$ may not in H for some $m \in \mathbb{Z}$. b_i are normalized to points on the unit sphere. Take a convergent subsequence and denote its limit by $v \in \mathfrak{h}^\perp$. For any $t \in \mathbb{R}$, tv is a limit of $\{t_i b_i\}$ for some $t_i \in \mathbb{Z}_{>0}$. (This uses $|b_i| \rightarrow 0$.) $\exp t_i b_i \in H$, and hence $\exp tv \in H$ since H is closed! Then $v \in \mathfrak{h}$ by definition of \mathfrak{h} , a contradiction!



Lie homomorphism $G \rightarrow H$:
smooth group homomorphism.

Theorem:

Continuous homomorphism $G \rightarrow H$ is automatically smooth!

Proof:

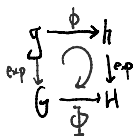
First, any continuous homomorphism $\gamma: \mathbb{R} \rightarrow H$ is $\gamma(t) = \exp tX$ for some X (and hence smooth):

For t_0 small, $\gamma(t_0) = \exp t_0 X$ for some X . $\gamma(t_0) = \gamma\left(\frac{t_0^k}{k}\right) = \exp\left(\frac{t_0^k X}{k}\right)$ and hence

$\gamma\left(\frac{t_0^k}{k}\right) = \exp\left(\frac{t_0^k X}{k}\right)$. (In the region that \exp is diffeomorphism, $(-)^k \in G$ corresponds to $k \cdot (-) \in \mathfrak{g}$ which is injective.)

Then $\gamma\left(\frac{p t_0^k}{k}\right) = \exp\left(\frac{p t_0^k X}{k}\right)$ for all p, k . By continuity $\gamma(t) = \exp tX$.

Now consider $\Phi: G \rightarrow H, 1_G \mapsto 1_H$. Use charts provided by \exp to understand the map.



$\Phi \circ \exp_G(X) = \exp_H \circ \phi(X)$. ϕ is a priori only defined near $X = 0$.
For each X , $\Phi \circ \exp_G(tX)$ gives a continuous homomorphism $\mathbb{R} \rightarrow H$. From above
 $\Phi \circ \exp_G(tX) = \exp_H tY$. Such Y is unique since \exp_H is a local diffeomorphism.
We define $\phi(X) = Y$. Thus $\phi: \mathfrak{g} \rightarrow \mathfrak{h}$.
Suffice to prove ϕ is linear, and hence Φ is smooth around 1_G .
Then $\Phi = L_{\Phi(g)} \circ \Phi \circ L_{g^{-1}}$ (since it is homomorphism) is smooth around g .

ϕ is linear:

$\Phi \circ \exp_G(t sX) = \exp_H t s\phi(X)$. $\phi(sX)$ also satisfies this. By uniqueness $\phi(sX) = s\phi(X)$.

$$\begin{aligned} \exp_H t \phi(X + Y) &= \Phi \circ \exp_G t(X + Y) = \Phi \left(\lim_{n \rightarrow \infty} \left(\exp_G \left(\frac{tX}{n} \right) \exp_G \left(\frac{tY}{n} \right) \right)^n \right) \\ &= \lim_{n \rightarrow \infty} \Phi \left(\exp_G \left(\frac{tX}{n} \right) \exp_G \left(\frac{tY}{n} \right) \right) \quad (\Phi \text{ is continuous}) \\ &= \lim_{n \rightarrow \infty} \left(\Phi \circ \exp_G \left(\frac{tX}{n} \right) \Phi \circ \exp_G \left(\frac{tY}{n} \right) \right) \quad (\Phi \text{ is homomorphism}) \\ &= \lim_{n \rightarrow \infty} \left(\exp_H \phi \left(\frac{tX}{n} \right) \exp_H \phi \left(\frac{tY}{n} \right) \right) \\ &= \lim_{n \rightarrow \infty} \left(\left(\exp_H \frac{t \phi(X)}{n} \right) \left(\exp_H \frac{t \phi(Y)}{n} \right) \right)^n \\ &= \exp_H t(\phi(X) + \phi(Y)). \end{aligned}$$

By uniqueness $\phi(X + Y) = \phi(X) + \phi(Y)$.

Exercises. (Section 2.6)

5. Show that

$$\exp \begin{pmatrix} a & b \\ 0 & d \end{pmatrix} = \begin{pmatrix} e^a & b \frac{e^a - e^d}{a-d} \\ 0 & e^d \end{pmatrix} \quad (\text{where the right hand side is defined by taking limit when } a = d).$$

8. Consider $X = \begin{pmatrix} 1 & 2 \\ -2 & 1 \end{pmatrix}$ and $Y = \begin{pmatrix} 1 & 2 \\ 2 & 1 \end{pmatrix}$. Compute e^{tX} and e^{tY} by diagonalization. Visualize the curves $e^{tX} \cdot v$ and $e^{tY} \cdot v$ for $v \neq 0$.