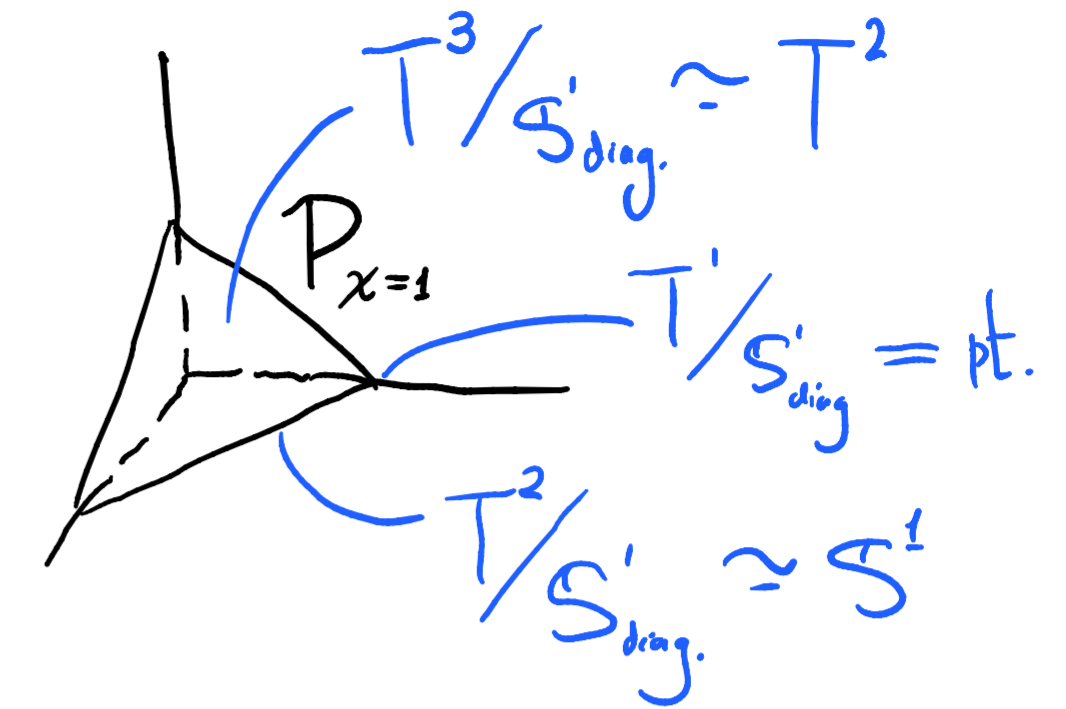


- Motivation: endow a Kaehler structure; better understand the role of the polytope. Outcome: toric manifold is Kaehler
- Def. of Kaehler manifold. Holonomy: $U(n)$. $(X, J, g, \omega): g(u, Jv) = \omega(u, v)$. $g(Ju, Jv) = g(u, v)$, $d\omega = 0$.
- Example: $C^n = T^*R^n$ (also P^n and its submanifolds)
- Newton's equation and Hamiltonian mechanics on T^*R^n
- T^n action on C^n
- Definition of moment map.
- Eg. $C^n \rightarrow R^n_{\geq 0} \Rightarrow$ Lagrangian torus fibration
- The exact sequence and corresponding torus action
- Moment map of subgroup action
- Naïve quotient is not symplectic: dimension is not correct
- Symplectic quotient $C^n // K$
- Symplectic structure descends to quotient
- Eg. P^2, K_{P^1}
- Residual torus action and moment map
- Kempf-Ness theorem: symplectic quotient = GIT quotient



$$K \curvearrowright X \xrightarrow{\mu} k_{\mathbb{R}}^*$$

$$\text{Moment map } \mu: \tilde{X} \rightarrow k_{\mathbb{R}}^*$$

$$d(\langle \mu, \xi \rangle) = \iota_{\rho(\xi)} \omega \quad (\text{Ham.})$$

unique up to transl. in $k_{\mathbb{R}}^*$.

K -equiv. ($\Rightarrow K$ -inv. if Abelian $\Rightarrow \mu^{-1}(x)$ preserved by K)

$$T^n \curvearrowright \mathbb{C}^n \xrightarrow{|z_i|^2/2} \mathbb{R}_{\geq 0}^n. \quad |z_i|^2 \text{ are inv. under } T.$$

$$q_i dq_i + p_i dp_i = \underbrace{\omega}_{\sum_j dp_j \wedge dq_j},$$

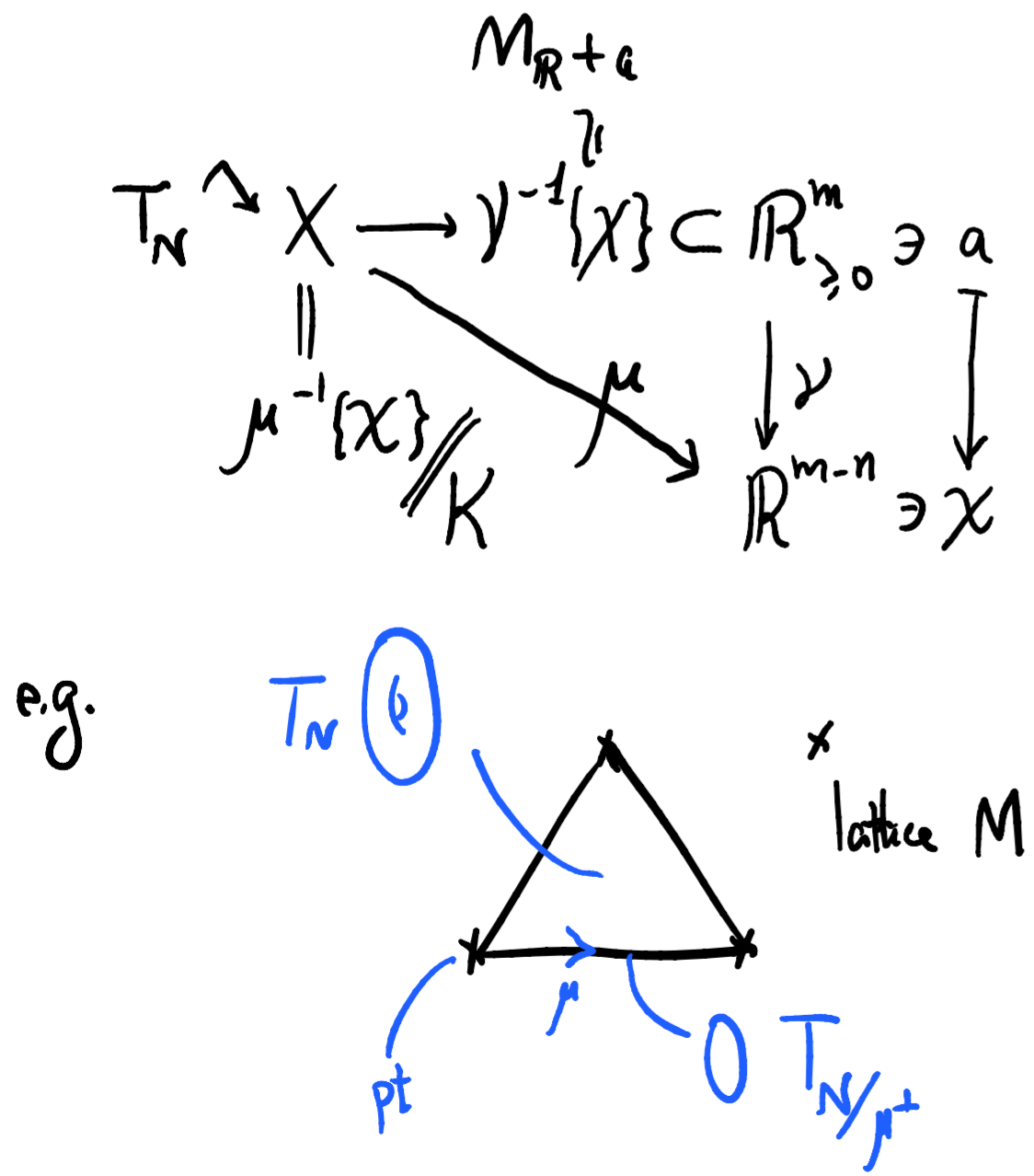
$$\xi_i = -p_i \partial_{q_i} + q_i \partial_{p_i} : t \curvearrowright \mathbb{C}^n.$$

$$K \subset T^n \curvearrowright \mathbb{C}^n \xrightarrow{\bar{\mu}} \mathbb{R}_{\geq 0}^n \rightarrow k_{\mathbb{R}}^*$$

$$d(\langle \bar{\mu}, \xi \rangle) = d(\langle \mu, \xi \rangle) = \underbrace{\iota_{\xi} \omega}_{k_{\mathbb{R}} \subset \mathbb{R}^n}$$

K -inv. $\Rightarrow \eta_{\#} \mu^{\xi} = \omega(\xi_{\#}, \eta_{\#}) = 0$
 $\forall \xi, \eta.$

Orbit is isotropic,
 hence at most dim. n .
 Also orbit \subset fiber of μ .
 \therefore If $\dim K = n$ and the
 action is free,
 μ is a Lag. fib.



Motivation (Hamiltonian dynamics)

\mathbb{R}^3 our space.

$X = T^*\mathbb{R}^3 = \mathbb{R}^3 \times (\mathbb{R}^3)^*$ 'phase space' of a particle.
 (q, p) position momentum

How can we talk about momentum without knowing the velocity?
 Momentum of a particle at q assigns to each $v \in T_q\mathbb{R}^3$ the 'impact' along $v \in \mathbb{R}$. Hence it is a covector.

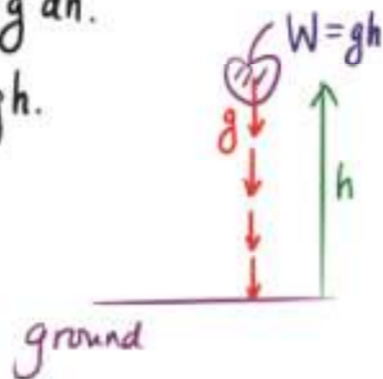
Newton's law: $F(q(t)) = m q''(t)$.
 vector field constant 2nd order ODE.

written as 1st order ODE system: $\begin{cases} q'(t) = \frac{1}{m} p(t) \\ p'(t) = F(q(t)) \end{cases}$

Suppose the force field F have a 'source':

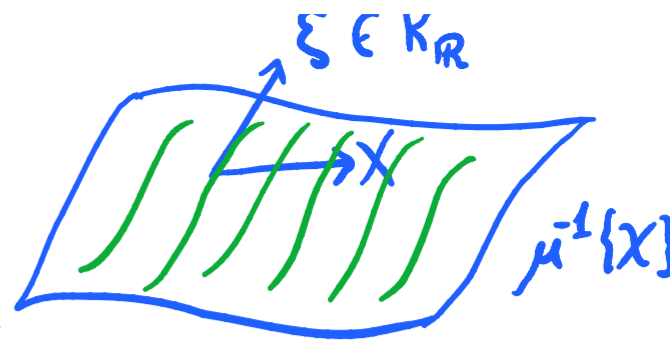
$$\sum_i F_i(q) dq_i = -dW \text{ called potential}$$

eg. $F dh = -g dh$
 $W = gh$



Take $-H(q, p) = \frac{\|p\|^2}{2m} + W(q)$.
 (Total energy, or Hamiltonian.)

Simpl. str. ω descends to $\tilde{X} //_{X} K$:



$$\bar{\omega}(\bar{X}, \bar{Y}) \triangleq \omega(X, Y)$$

$$\omega(X + \xi, Y + \eta) = \omega(X, Y) + \underbrace{\omega(\xi, Y)}_{\text{const}} + \underbrace{\omega(X, \eta)}_{-\partial_x(\mu, \eta)} + \underbrace{\omega(\xi, \eta)}_{\partial_\eta(\mu, \xi)}$$

$$-dH = \sum_i \frac{p_i}{m} dp_i - \sum_i F_i(q) dq_i \leftarrow \text{closed 1-form}$$

$$X_H = \sum_i \frac{p_i}{m} \frac{\partial}{\partial q_i} + \sum_i F_i(q) \frac{\partial}{\partial p_i} \leftarrow \text{sympl. v.f.}$$

setting $\omega = \sum_i dq_i \wedge dp_i$

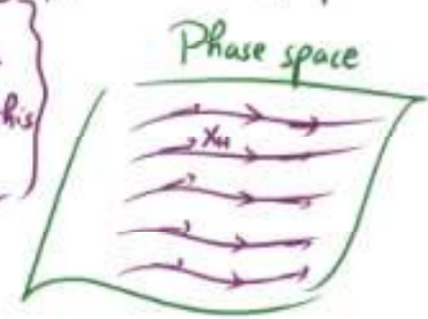
Note: H is conserved. $L_{X_H} \omega = dH$

$$dH(X_H) = X_H H = \omega(X_H, X_H) = 0$$

\therefore Newton's law

$$\Leftrightarrow \text{Hamiltonian flow } \begin{pmatrix} q \\ p \end{pmatrix}'(t) = X_H \left(\begin{pmatrix} q \\ p \end{pmatrix}(t) \right)$$

Want to formulate a global theory out of this structure.



$$\mathbb{R} \curvearrowright (M, \omega) \xrightarrow{H} \mathbb{R}$$

$H^{-1}\{c\} // \mathbb{R}$: phases of same energy 'unrelated' to each other.

symmetries of $(M, H) \leftrightarrow$ conserved quantities

$$X_\varphi \cdot H = \pm \omega(X_H, X_\varphi) = X_H \cdot \varphi$$

eg. $X_\varphi = \frac{\partial}{\partial q_i} \leftrightarrow -\varphi = p_i$ lin. momentum

$$X_\varphi = -p_2 \frac{\partial}{\partial q_1} + q_2 \frac{\partial}{\partial q_2} \leftrightarrow -\varphi = \det \begin{pmatrix} p_1 & p_2 \\ q_1 & q_2 \end{pmatrix} \text{ angular momentum.}$$

(Generalization:
 symmetries of $(X, \mu) \leftrightarrow G$ -inv. fns
 $X_\varphi \cdot \mu^X = \pm \omega(X_\varphi, X_\#) = X_\# \cdot \varphi$)