

Nakajima quiver variety

Saturday, February 1, 2020 11:46 AM

[Nakajima - Instantons on ALE spaces, quiver varieties and Kac-Moody Algebras]

- Provide nice examples of (non-compact) holomorphic symplectic varieties and resolutions of singularities
- Cohomologies give representations of Kac-Moody Lie algebras
- Naturally come up as mod. of ASD connections over $\widehat{\mathbb{C}_2/\Gamma}$ [Kronheimer]

Hyper-Kaehler quotient

Given graph with no self edge.

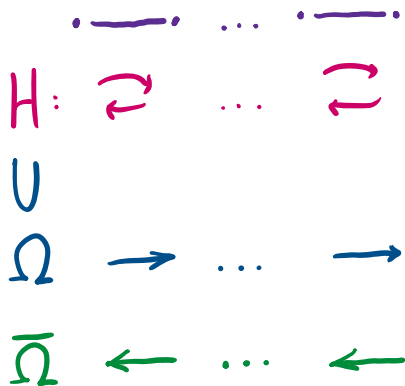
H : set of all edges together with orientation.

Choose $\Omega \subset H$ with

$$\Omega \cup \bar{\Omega} = H, \Omega \cap \bar{\Omega} = \emptyset$$

such that Ω has no oriented cycle.

ex.



Fix Herm. v.s. $V_k, W_k \quad \forall$ vertex k .

Dim. vector v, w .

Framed rep. space:

$$\mathbf{M} \stackrel{\text{def.}}{=} \left(\bigoplus_{h \in H} \text{Hom}(V_{\text{out}(h)}, V_{\text{in}(h)}) \right) \oplus \left(\bigoplus_{k=1}^n \text{Hom}(W_k, V_k) \oplus \text{Hom}(V_k, W_k) \right).$$

W_k are the framing.

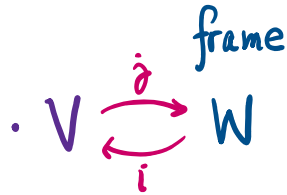
(We have started with M_Ω below.)

$(B, i, j) \in M.$

$$\dim_{\mathbb{R}} \mathbf{M} = 2^i \mathbf{v} \mathbf{A} \mathbf{v} + 4^i \mathbf{v} \mathbf{w}$$

where A is adj. matrix.

ex. Quiver with only one vertex.



Holomorphic symplectic:

$$\omega_{\mathbb{C}}((B, i, j), (B', i', j')) \stackrel{\text{def.}}{=} \sum_{h \in H} \text{tr}(\epsilon(h) B_h B'_h) + \sum_{k=1}^n \text{tr}(i_k j'_k - i'_k j_k)$$

where $\epsilon(h) = 1, -1$ for $h \in \Omega, \bar{\Omega}$ resp.

Decompose into Lagrangian subspaces:

$$\mathbf{M}_{\Omega} \stackrel{\text{def.}}{=} \left(\bigoplus_{h \in \Omega} \text{Hom}(V_{\text{out}(h)}, V_{\text{in}(h)}) \right) \oplus \left(\bigoplus_{k=1}^n \text{Hom}(W_k, V_k) \right)$$

$$\mathbf{M}_{\bar{\Omega}} \stackrel{\text{def.}}{=} \left(\bigoplus_{h \in \bar{\Omega}} \text{Hom}(V_{\text{out}(h)}, V_{\text{in}(h)}) \right) \oplus \left(\bigoplus_{k=1}^n \text{Hom}(V_k, W_k) \right).$$

$M = M_{\Omega} \oplus M_{\bar{\Omega}}$ can be understood as T^*M_{Ω} .

M has Herm. metric induced from that of V, W .

HyperKaehler:

$$J(m, m') = (-m'^{\dagger}, m^{\dagger}) \quad \forall (m, m') \in M_{\Omega} \oplus M_{\bar{\Omega}} = M$$

Where $(\cdot)^{\dagger}$ is the Herm. adj. for Hom space.

$$G = \prod_k U(V_k)$$

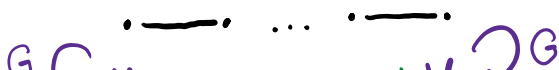
acts on M :

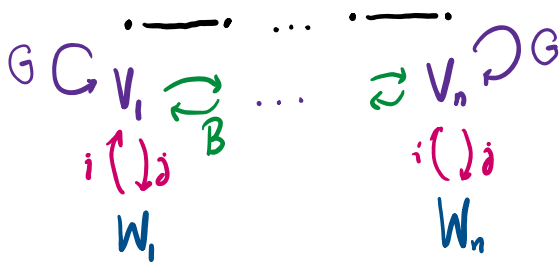
$$(B_h, i_k, j_k) \mapsto (g_{\text{in}(h)} B_h g_{\text{out}(h)}^{-1}, g_k i_k, j_k g_k^{-1})$$

preserving hyperKaehler structure.

(G does not act on the framing W .)

ex.





Moment maps of G and $G_{\mathbb{C}}$ (w.r.t. $\omega_{\mathbb{R}}$ and $\omega_{\mathbb{C}}$):

$$\mu_{\mathbb{R}}(B, i, j) = \frac{i}{2} \left(\sum_{h \in H: k = \text{in}(h)} B_h B_h^\dagger - B_h^\dagger B_h + i_k i_k^\dagger - j_k^\dagger j_k \right) \in \bigoplus_k \mathfrak{u}(V_k) = \mathfrak{g}_{\mathbb{R}},$$

$$\mu_{\mathbb{C}}(B, i, j) = \left(\sum_{h \in H: k = \text{in}(h)} \varepsilon(h) B_h B_h^\dagger + i_k j_k \right) \in \bigoplus_k \mathfrak{gl}(V_k) = \mathfrak{g}_{\mathbb{C}} \otimes \mathbb{C},$$

Fix $\zeta = (\zeta_{\mathbb{R}}, \zeta_{\mathbb{C}}) \in Z_{\mathbb{R}} \oplus (Z_{\mathbb{C}} \otimes \mathbb{C})$ where $Z_{\mathbb{R}} \subset \mathfrak{g}_{\mathbb{R}}$ center ($i\mathbb{R} \cdot \text{Id}$ over each vertex k).

$Z_{\mathbb{R}} \subset \mathbb{R}^{Q_0}$ (analog of real Cartan subalg.)
 (Some $v(k)$ can be zero and so $\mathfrak{gl}_k = 0$.
 Then $Z_{\mathbb{R}}$ may not be whole \mathbb{R}^{Q_0} .)

HK quotient:

$$\mathfrak{M}_{\zeta} = \mathfrak{M}_{\zeta}(\mathbf{v}, \mathbf{w}) \stackrel{\text{def.}}{=} \{(B, i, j) \in \mathbf{M} \mid \mu(B, i, j) = -\zeta\} / G_{\mathbb{R}}.$$

$$\mathfrak{M}_{\zeta}^{\text{reg}} \stackrel{\text{def.}}{=} \{(B, i, j) \in \mu^{-1}(-\zeta) \mid \text{the stabilizer of } (B, i, j) \text{ in } G_{\mathbb{R}} \text{ is trivial}\} / G_{\mathbb{R}}.$$

$$\dim_{\mathbb{R}} \mathbf{M} = 2^t \mathbf{v} A \mathbf{v} + 4^t \mathbf{v} \mathbf{w} \quad \leftarrow \begin{matrix} \dagger \\ \mathbf{v} \cdot \mathbf{v} \end{matrix}$$

$$\dim_{\mathbb{R}} \mathfrak{M}_{\zeta}^{\text{reg}} = \dim_{\mathbb{R}} \mathbf{M} - 4 \dim_{\mathbb{R}} G_{\mathbb{R}} = 2^t \mathbf{v} (2\mathbf{w} - C\mathbf{v})$$

where

$C = 2I - A$ and A is adj. matrix.

(Euler form)

ex.

$$\left\{ \begin{array}{l} (1) \quad i \cdot j = -\overset{0}{\parallel_{\text{set}}} \zeta_{\mathbb{C}} \cdot \text{Id} \\ (2) \quad i \cdot i^\dagger - j^\dagger j = -\underset{\text{V set}}{\zeta_{\mathbb{R}}} \cdot \text{Id} \end{array} \right\} \Bigg/ \text{Id}(k) \quad (i, j) \mapsto (g_i, j g_j^{-1})$$

$$U(k) \begin{matrix} \curvearrowright \\ \mathbb{V} \\ \leftarrow \\ i \end{matrix} \begin{matrix} \mathbb{W} \\ \\ \\ \end{matrix} \quad \left((2) \quad i \cdot i' - j' \cdot j = -\zeta_{\mathbb{R}} \cdot \text{Id} \right) / U(k) \quad (i, j) \mapsto (g_i, j g')$$

$$(2) \Rightarrow j \cdot i j' : \text{If } 0 \neq v \in \text{Ker } j, v^t (\text{LHS}) v = (v^t \cdot i) \cdot (v^t \cdot i)^t > 0, \\ \text{but } v^t (\text{RHS}) v < 0.$$

Take $S = \text{Im } j$.

$$(1) \Rightarrow S \subset \text{Ker } i.$$

$A = j i$ maps W/S to S

(that is, $W \rightarrow S$ and $S \rightarrow 0$).

$$\therefore \mathcal{M} \simeq T^* \text{Gr}(k, n) \ni (S, A).$$

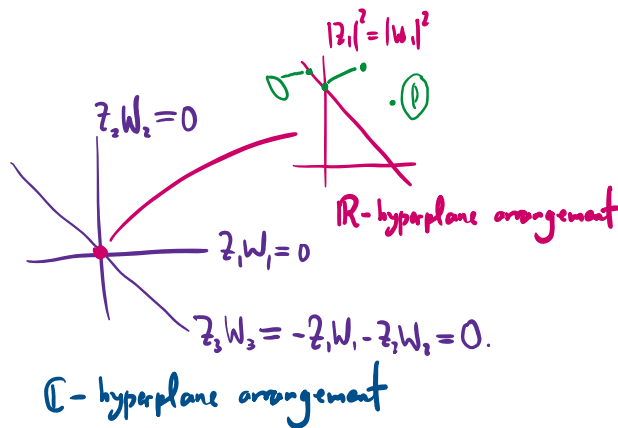
ex. $k=1$. $T^* \mathbb{P}^n$.

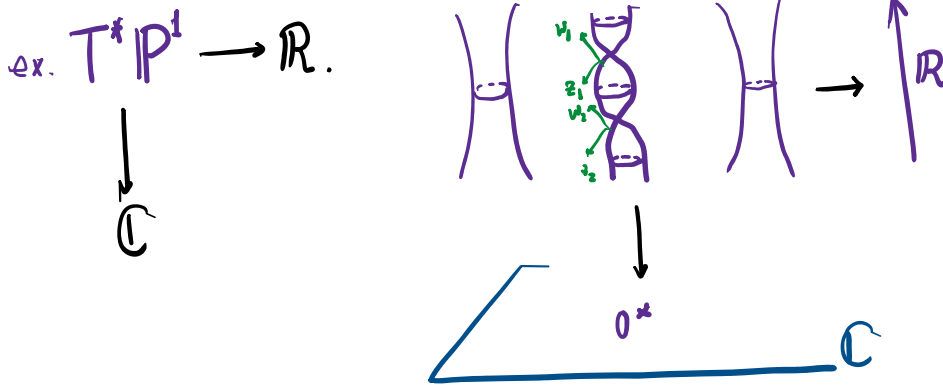
$$(1) \sum_i w_i \bar{z}_i = 0.$$

$$(2) \sum_i (|z_i|^2 - |w_i|^2) = \zeta_{\mathbb{R}}.$$

$$(z, w) \mapsto (\lambda z, \lambda w) \\ \lambda \in U(1)$$

$$T^* \mathbb{P}^n \xrightarrow{(|z_i|^2 - |w_i|^2)} \mathbb{R}^n \\ \downarrow (z_1, w_1, \dots, z_n, w_n) \\ \mathbb{C}^n$$





Smoothness

$R_+ := \{\theta \in \mathbb{Z}_{\geq 0}^n : \theta^t C \theta \leq 2\} - \{0\}$.
 (Recall $\epsilon_x^t C \epsilon_x = 2$, and so positive real roots have $\theta^t C \theta = 2$.)

$R_+(v) := \{\theta \in R_+ : \theta_k \leq v^{(k)} \forall k\}$ (finite set).

(wall)
 $D_\theta := \{x \in \mathbb{R}^n : x \cdot \theta = 0\}$
 where $\theta \in R_+$.

Thm. 2.8.

If

$$\zeta \in \mathbb{R}^3 \otimes \mathbb{R}^n \setminus \bigcup_{\theta \in R_+(v)} \mathbb{R}^3 \otimes D_\theta$$

then M_ζ is smooth.
 (The HK quotient is complete.)

Proof.

Want: no non-trivial stabilizer.
 Suppose has stabilizer: $(B, i, j) \in \mu^{-1}(-\zeta)$ is fixed by $g \in G_v$ (whose action is non-trivial).

Eigenspace decomp. of V_k by g_k :

$$V_k = \bigoplus_{\lambda} V_k(\lambda).$$



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Recall action of g :

$$(B_h, i_k, j_k) \mapsto (g_{\text{in}(h)} B_h g_{\text{out}(h)}^{-1}, g_k i_k, j_k g_k^{-1})$$

Hence B preserves eigenspaces (with same eigenvalues);

$$i(W) \subset V(1);$$

$$j(V(\lambda)) = 0 \text{ unless } \lambda = 1.$$

Hence B_h restricted on $V_k(\lambda)$ (for $\lambda \neq 1$) defines a rep. in $M(\theta, 0)$ (where $\theta = \dim V(\lambda)$).

Momentum μ remains the same:

μ is originally $-\zeta \cdot \text{Id}$. Hence restricts to $-\zeta \cdot \text{Id}$ on eigenspaces.

Consider the action of $G_{\theta}/U(1)$ on $G_{\theta} \cdot \{B_h\} \subset \text{Rep}_{\theta}$.

If has non-trivial stabilizer, take eigen-decomp. of that.

Keep on doing this, until

$G_{\theta}/U(1)$ acts freely on orbit of B_h .

Momentum of B_h is still $-\zeta \cdot \text{Id}$.

Then B_h is a smooth point of $\mu^{-1}(-\zeta)/G_{\theta}$ (where μ here is $M(\theta, 0) \rightarrow Z_v \oplus (Z_v \otimes \mathbb{C})$).

Denote the corresponding rep. by V' .

Recall at a smooth point with framing,

$$\dim_{\mathbb{R}} \mathfrak{M}_{\zeta}^{\text{reg}} = \dim_{\mathbb{R}} M - 4 \dim_{\mathbb{R}} G_v = 2^t v (2w - Cv)$$

Without framing:

$$\dim \mu^{-1}(-\zeta)/G_{\theta} = 2 - \theta^t C \theta \geq 0$$

(where 2 comes from that $U(1)$ acts trivially in hyperKaehler quotient. $w = 0$.)

Hence the dim. vector of V' : $\theta \in R_+(v)$.

By Lemma below,

$\zeta_{\mathbb{R}} \perp \theta$ and $\zeta_{\mathbb{C}} \perp \theta$, that is,

$$\zeta \in \mathbb{R}^3 \otimes D_{\theta}.$$

QED.

Lemma:

Given any subrep. $V' \subset V$ with

$$i(W) \subset (V')^{\perp} \text{ and } j(V') = 0,$$

$$\zeta_{\mathbb{R}} \perp \theta \text{ and } \zeta_{\mathbb{C}} \perp \theta.$$

$\mu(V) = \zeta.$

Proof.

Take

π : ortho. proj. $V \rightarrow V'$.

$i\pi \in \mathfrak{g}$ (skew-Herm.)

$e^{ti\pi} \in G$ fixes (B, i, j) :

$e^{ti\pi}$ is Id on V'^{\perp} and $\in U(1)$ on V' .

Hence acts trivially (as overall scaling) on V' ;

i, j are only supported on V'^{\perp} .

Hence Hamiltonian function in direction of $i\pi$ is constant, which must be 0 since $\mu(B = 0, i = 0, j = 0) = 0$.

$$\langle \mu(B, i, j), i\pi \rangle_{\mathfrak{g}} = 0.$$

Since $\mu(B, i, j) = \zeta \cdot \text{Id}$, get

$$\langle \zeta \cdot \text{Id}, i\pi \rangle_{\mathfrak{g}} = \sum_k \zeta_k \dim V'_k = 0 \in \mathbb{R} \oplus \mathbb{C}.$$

Holomorphic description

[Kirwan],[Ness]

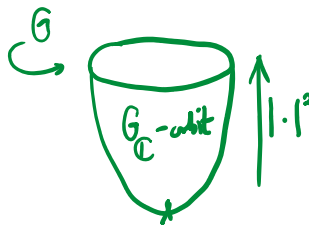
For $\xi_{\mathbb{R}} = 0$,

symp. = GIT quot:

$$M_{(0, \xi_{\mathbb{C}})} \cong \mu_{\mathbb{C}}^{-1}(-\xi_{\mathbb{C}}) // G_{\mathbb{V}}^{\mathbb{C}}$$

(affine GIT).

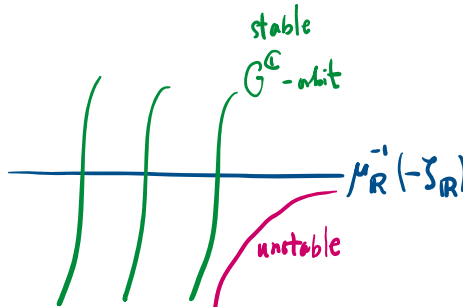
$$(G_{\mathbb{V}}^{\mathbb{C}} = \prod_k GL(V_k).)$$



Key point: a $G^{\mathbb{C}}$ -orbit is stable iff the orbit has a minimum for $||^2$.

In this case,

each crit. pt. of $|\mu_{\mathbb{R}}|^2$ lies in $\mu_{\mathbb{R}}^{-1}\{0\}$.



For generic $(\zeta_{\mathbb{R}}, \zeta_{\mathbb{C}})$,

$$\mathfrak{M}_{\zeta} \xrightarrow{\cong} H_{\zeta}^s / G_{\mathbb{V}}^{\mathbb{C}}$$

where

$$H_{\zeta}^s \stackrel{\text{def.}}{=} \{m \in \mu_{\mathbb{C}}^{-1}(-\zeta_{\mathbb{C}}) | \text{the } G_{\mathbb{V}}^{\mathbb{C}}\text{-orbit through } m \text{ intersects the level set } \mu_{\mathbb{R}}^{-1}(-\zeta_{\mathbb{R}})\}.$$

If $(0, \zeta_{\mathbb{C}})$ is generic (in the above sense that there is no strictly semi-stable points), then for $(\zeta_{\mathbb{R}}, \zeta_{\mathbb{C}})$,

all points are stable:

$$H_{(\zeta_{\mathbb{R}}, \zeta_{\mathbb{C}})}^S = \mu_{\mathbb{C}}^{-1}(-\xi_{\mathbb{C}}) \forall \zeta_{\mathbb{R}}.$$

Then complex structure is indep. of $\zeta_{\mathbb{R}}$.

(Only Kaehler structure depends.)

(No resolution occurs.)

The above def. of H_{ζ}^S is not practical enough.

Prop.

If $\zeta_{\mathbb{R}}^{(k)} > 0 \forall k$,

$(B, i, j) \in H_{\zeta}^S$

\Leftrightarrow

No non-trivial subrep. of B lies in kernel of j_k ,
namely,

for $(S_k \subset V_k)_k$, preserved by B and

$j_k(S_k) = 0 \forall k$,

then $S_k = 0 \forall k$.

Resolution of singularity

Denote

$\zeta = (0, \zeta_{\mathbb{C}})$ generic.

$\tilde{\zeta} = (\zeta_{\mathbb{R}}, \zeta_{\mathbb{C}})$.

Have I-holomorphic

$$\pi: \mathfrak{M}_{\tilde{\zeta}} \rightarrow \mathfrak{M}_{\zeta}.$$

(Also known as affinization.)

RHS is Spec of $G_{\mathbb{C}}$ -inv. functions.)

Thm. 4.1.

1. π is proper.
2. $\pi^{-1}(M_{\zeta}^{\text{reg}}) \cong M_{\tilde{\zeta}}^{\text{reg}}$. (π is resol. of sing.)
3. If $M_{\zeta}^{\text{reg}} \neq \emptyset$, then $\pi^{-1}(M_{\zeta}^{\text{reg}})$ dense in $M_{\tilde{\zeta}}$.

\mathbb{C}^{\times} -action

Assume $(\zeta_{\mathbb{R}}, 0)$ generic.

$$M_{\zeta_{\mathbb{R}}} := \bigcup_{\zeta_{\mathbb{C}}} M_{(\zeta_{\mathbb{R}}, \zeta_{\mathbb{C}})} \rightarrow Z_{\mathbb{C}}.$$

(Need to take union since $\mu_{\mathbb{C}} = \zeta_{\mathbb{C}}$ is generally not preserved by the following action.)

If we take $\zeta_{\mathbb{C}} = 0$, then preserved and don't need to take

union.)

S^1 -action:

$$(B_h, i_k, j_k) \mapsto (t^{(1-\varepsilon(h))/2} B_h, i_k, t j_k)$$

That is,

arrows in $M_{\bar{\Omega}}$ are multiplied by t ,
those in M_{Ω} are unchanged.

Recall that

$$\mu_{\mathbb{R}}(B, i, j) = \frac{i}{2} \left(\sum_{h \in H: k = \text{in}(h)} B_h B_h^\dagger - B_h^\dagger B_h + i_k i_k^\dagger - j_k^\dagger j_k \right) \in \bigoplus_k \mathfrak{u}(V_k) = \mathfrak{g}_{\mathbf{v}},$$

$$\mu_{\mathbb{C}}(B, i, j) = \left(\sum_{h \in H: k = \text{in}(h)} \varepsilon(h) B_h B_h^\dagger + i_k j_k \right) \in \bigoplus_k \mathfrak{gl}(V_k) = \mathfrak{g}_{\mathbf{v}} \otimes \mathbb{C},$$

$\mu_{\mathbb{R}} = -\zeta_{\mathbb{R}}$ preserved;

(Note: this is not preserved if we take $t \in \mathbb{C}^\times$.)

$$\mu_{\mathbb{C}}(t \cdot (B, i, j)) = t \mu_{\mathbb{C}}(B, i, j).$$

Use this action (and its moment map flow) to understand topology.

THEOREM 5.1. *The S^1 -action on $\mathcal{M}_{\zeta_{\mathbb{R}}}$ has the following properties:*

(1) *The natural projection map $\mathcal{M}_{\zeta_{\mathbb{R}}} \rightarrow Z \otimes \mathbb{C}$ is equivariant; here we make S^1 act on the vector space $Z \otimes \mathbb{C}$ with weight 1. (In particular, $\mathfrak{M}_{(\zeta_{\mathbb{R}}, 0)}$ admits an S^1 -action.)*

(2) *It preserves the complex structure I and the metric.*

(3) *The holomorphic symplectic form $\omega_{\mathbb{C}}$ transforms as $\omega_{\mathbb{C}} \rightarrow t \omega_{\mathbb{C}}$.*

(4) *The corresponding moment map*

$$F([B, i, j]) = \sum_{h \in \bar{\Omega}} \|B_h\|^2 + \sum_k \|j_k\|^2$$

is proper.

(5) *The action is extended to a holomorphic (with respect to I) \mathbb{C}^* -action. If we use the holomorphic description $\mathfrak{M}_{(\zeta_{\mathbb{R}}, \zeta_{\mathbb{C}})} = H_{(\zeta_{\mathbb{R}}, \zeta_{\mathbb{C}})}^s / G_{\mathbf{v}}^{\mathbb{C}}$, the \mathbb{C}^* -action is given by*

$$G_{\mathbf{v}}^{\mathbb{C}}(B_h, i_k, j_k) \mapsto G_{\mathbf{v}}^{\mathbb{C}}(t^{(1-\varepsilon(h))/2} B_h, i_k, t j_k).$$

Recall

$$\omega_{\mathbb{C}}((B, i, j), (B', i', j')) \stackrel{\text{def.}}{=} \sum_{h \in H} \text{tr}(\varepsilon(h) B_h B_h') + \sum_{k=1}^n \text{tr}(i_k j_k' - i_k' j_k)$$

(4):

Assume not. Then there exists a sequence $[(B, i, j)_l]$ in

$M_{\zeta_{\mathbb{R}}}$ that has no convergent subsequence, whose F -image lies in a bounded interval.

$|(B, i, j)_l| \rightarrow \infty$ or otherwise must have convergent subseq. Take $(B, i, j)_l / |(B, i, j)_l|$ lying in the unit sphere and hence must have convergent subseq.

$$\mu_{\mathbb{R}}((B, i, j)_l / |(B, i, j)_l|) \rightarrow 0 \text{ (since } \mu_{\mathbb{R}}((B, i, j)_l) = \zeta_{\mathbb{R}})$$

and

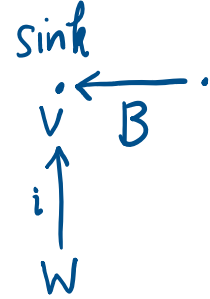
$$F((B, i, j)_l / |(B, i, j)_l|) \rightarrow 0 \text{ (since } F((B, i, j)_l) \text{ is bounded).}$$

Then the limit (B, i, j) has

$$|(B, i, j)| = 1, \mu_{\mathbb{R}}(B, i, j) = 0 \text{ and } F(B, i, j) = 0.$$

$F = 0$ means (B, i, j) is usual framed quiver rep. (without doubling).

$\mu_{\mathbb{R}} = 0$ implies at sink, $i = 0$ and arrow maps to sink = 0. Inductively, $(B, i, j) = 0$. But $|(B, i, j)| = 1$!



In (5), still need to take $M_{\zeta_{\mathbb{R}}} := \cup_{\zeta_{\mathbb{C}}} M_{(\zeta_{\mathbb{R}}, \zeta_{\mathbb{C}})}$ since $\zeta_{\mathbb{C}} \mapsto t\zeta_{\mathbb{C}}$. The holo. description implies the new point has orbit closure intersects the orbit closure of $(t^{1-\frac{\epsilon(h)}{2}} B_{h,,}, i_k, tj_k)$. Want to argue it has the same orbit as $(t^{1-\frac{\epsilon(h)}{2}} B_{h,,}, i_k, tj_k)$.

Since the moment map F has compact fibers, the corresponding Ham. flow (which is J of the S^1 -flow) is complete.

The new point after action lies in $M_{(\zeta_{\mathbb{R}}, t\zeta_{\mathbb{C}})}$, whose representative has $G_{\mathbb{C}}$ -orbit of max. dim. (All points are strictly stable since $\zeta_{\mathbb{R}}$ is generic.)

Hence it lies in $G_{\mathbb{C}} \cdot (t^{1-\frac{\epsilon(h)}{2}} B_{h,,}, i_k, tj_k)$.

(Note that $(t^{1-\frac{\epsilon(h)}{2}} B_{h,,}, i_k, tj_k) \notin \mu_{\mathbb{R}}^{-1}\{\zeta_{\mathbb{R}}\}$!)

The \mathbb{C}^{\times} -action preserve $\cup_{\zeta_{\mathbb{C}}} H_{(\zeta_{\mathbb{R}}, \zeta_{\mathbb{C}})}^S$, since subrepresentations survive under scaling of arrows.

From the holomorphic description,

Thm. 5.2.

$\pi: M_{\zeta_{\mathbb{R}}} \rightarrow M_0 := \cup_{\zeta_{\mathbb{C}}} M_{(0, \zeta_{\mathbb{C}})}$ is \mathbb{C}^{\times} -equiv.

Note that in this notation, M_0 is DIFFERENT from $M_{(0,0)}$!

$$\pi: M_{\zeta_{\mathbb{R}}} \rightarrow M_0$$

can be understood as simultaneous resolution
(of every fiber of $M_0 := \cup_{\zeta_{\mathbb{C}}} M_{(0, \zeta_{\mathbb{C}})} \rightarrow Z_{\mathbb{C}}$).

[Slodowy]:

$M_{(\zeta_{\mathbb{R}}, 0)}$ is homotopy equiv. to $L := \pi^{-1}\{0 \in M_{(0,0)}\}$.

(Contraction of $M_{(0,0)}$ to 0 induces contraction of $M_{(\zeta_{\mathbb{R}}, 0)}$ to L .)

\mathbb{C}^\times -fixed point set F must be contained in $M_{(\zeta_{\mathbb{R}}, 0)}$

(since the base point $\zeta_{\mathbb{C}}$ needs to be fixed by \mathbb{C}^\times).

Since π is equiv, $\pi(F)$ must be contained in fixed point set of $M_{(0,0)}$.

Fixed point set of $M_{(0,0)}$ is just $[0]$:

(B, i, j) fixed by \mathbb{C}^\times implies

it has doubled part = 0.

$\zeta_{\mathbb{R}} = 0$ implies $(B, i, j) = 0$ inductively
like proof of (4) above.

Thus

$$F \subset \pi^{-1}\{0\} =: L.$$

Homology

Denote conn. cpnt. of F by $F_1 \dots F_p$.

f : moment map of the \mathbb{S}^1 -action on $M_{(\zeta_{\mathbb{R}}, 0)}$.

Perfect Morse function.

Proper by Thm. 5.1 (4).

$$\text{grad } f = 2I \cdot V.$$

F is the set of critical points of f .

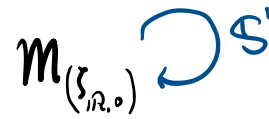
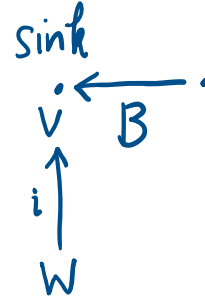
\mathbb{S}^1 -action on $T_x M_{(\zeta_{\mathbb{R}}, 0)}$ for $x \in F$

gives weight decomp.

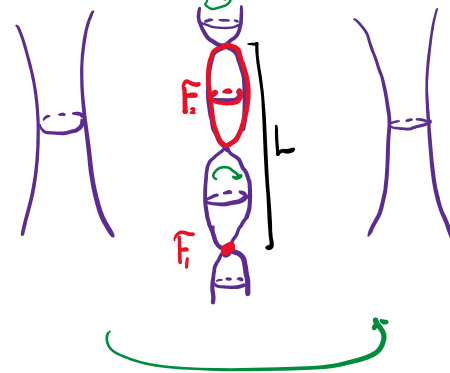
$$T_x M_{(\zeta_{\mathbb{R}}, 0)} = \bigoplus_m H^m.$$

$$T_x F_\alpha = H^{m=0}.$$

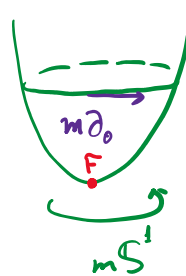
$\text{Hess}_x(f)$ acts on H^m as multi. by m .



ex.



ex.



$$f = \frac{m r^2}{2}$$

$$\text{Hess} = \begin{pmatrix} m & \\ & m \end{pmatrix}$$

$$\int_{m\partial_0} \omega = m r dr.$$

$$\text{Ind}(x) = m_\alpha := \sum_{m < 0} \dim_{\mathbb{R}} H^m.$$

(Points in the same fixed component have the same index.)

Since $M_{(\zeta_{\mathbb{R}}, 0)}$ is homotopy equiv. to L ,

Prop. 5.7.

$$H_i(M_{(\zeta_{\mathbb{R}}, 0)}) \cong H_i(L) \cong \bigoplus_{1 \leq \alpha \leq p} H_{i-m_\alpha}(F_\alpha).$$

The second equality is due to f being perfect Morse.

In general,

$$\text{Ind}(x) = \dim_{\mathbb{R}} M - \dim_{\mathbb{R}} F_\alpha - \#(\text{positive directions}).$$

We can do better in this case:

Lem. 5.6.

For each α (indexing of fix set),

$$m_\alpha = \dim_{\mathbb{C}} M_{(\zeta_{\mathbb{R}}, 0)} - \dim_{\mathbb{R}} F_\alpha.$$

Proof.

Consider $\omega_{\mathbb{C}}: T_x M_{(\zeta_{\mathbb{R}}, 0)} \wedge T_x M_{(\zeta_{\mathbb{R}}, 0)} \rightarrow \mathbb{C}$.

$\omega_{\mathbb{C}}$ becomes $t\omega_{\mathbb{C}}$ under the action.

Hence it has weight 1.

$$\omega_{\mathbb{C}}: H^m \cong H^{1-m}.$$

(Recall that H^m are the weight spaces of $T_x M_{(\zeta_{\mathbb{R}}, 0)}$.)

Then

$$\sum_{m \leq 0} \dim H^m = \sum_{m > 0} \dim H^m.$$

They add up to $\dim_{\mathbb{R}} M_{(\zeta_{\mathbb{R}}, 0)}$, and hence each is half.

$$\text{LHS} = m_\alpha + \dim_{\mathbb{R}} F_\alpha.$$

Thm. 5.8.

$L = \pi^{-1}(0)$ decomposes into

{points that flows to F_α }

for $\alpha = 1, \dots, p$.

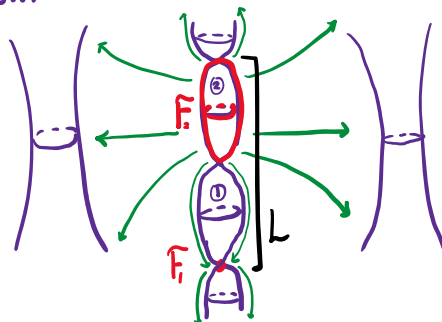
Closure of each is an irred. component.

L is Lag. w.r.t. $\omega_{\mathbb{C}}$.

Reason:

ω becomes $t\omega$ under pull-back by the

\mathbb{C}^\times -action.



$$m_1 = 2.$$

$$m_2 = 0.$$

Thus $\omega(t \cdot u, t \cdot v) = t\omega(u, v)$.

If $u, v \in TL$, LHS is bounded for $t \rightarrow \infty$.

(Paths are gradually sent to the fixed locus by the action.)

Hence $\omega(u, v) = 0$,

L must be isotropic.

Also it is half dim. since at fixed point,

$$T_x L = \bigoplus_{m \leq 0} H^m.$$

ex. Cotangent bundle of A_n flag

$F(v_1, \dots, v_n; r)$ for

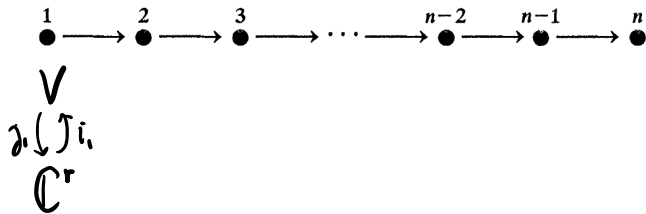
$r > v_1 > \dots > v_n > 0$.

$T^*F = \{(\phi, A) \in F \times \text{End}(\mathbb{C}^r) : A(E^k) \subset E^{k+1}\}$

where $\phi = (E^0 = \mathbb{C}^r \supset E^1 \supset \dots \supset E^{n+1} = 0)$.

Take $M_\zeta(v, w)$ where

$v = (v_1, \dots, v_n), w = (r, 0, \dots, 0)$.



Thm. 7.3.

Let $\zeta_{\mathbb{R}} = \left(\frac{i\zeta_{\mathbb{R}}^{(1)}}{2}, \dots, \frac{i\zeta_{\mathbb{R}}^{(n)}}{2} \right)$

where $\zeta_{\mathbb{R}}^{(k)} > 0, k = 1, \dots, n$.

$$M_{(\zeta_{\mathbb{R}}, 0)} \cong T^*F.$$

Proof.

$B_{k-1, k}$ (arrow from k to $k - 1$) and j_1 are injective:

the last vertex:

$$B_{n, n-1} B_{n, n-1}^\dagger - B_{n-1, n}^\dagger B_{n-1, n} = -\zeta_{\mathbb{R}}^{(n)} \mathbf{1}_{V_n}$$

hence $B_{n-1, n}$ is injective.

Suppose $B_{k-1, k}$ is inj.

At the vertex $(k - 1)$:

$$B_{k-1, k} B_{k, k-1} - B_{k-1, k-2} B_{k-2, k-1} = 0$$

Hence $\text{Ker } B_{k-2, k-1} \subset \text{Ker } B_{k, k-1}$.

$$B_{k-1,k}B_{k-1,k}^\dagger - B_{k,k-1}^\dagger B_{k,k-1} + B_{k-2,k-1}B_{k-1,k-2}^\dagger - B_{k-1,k-2}^\dagger B_{k-2,k-1}$$

$$= -\zeta_{\mathbb{R}}^{(k-1)} 1_{V_{k-1}}$$

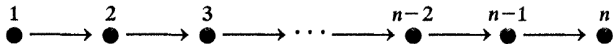
$$V_1 \hookrightarrow V_2 \subset V_3 \dots \subset V_n$$

Hence $B_{k-2,k-1}$ is inj.

Similarly, consider the equations at the first vertex, get j_1 inj.

Thus

$$M_{(\zeta_{\mathbb{R}}, 0)} \subset \{(B, i, j) : \mu_{\mathbb{C}}(B, i, j) = 0, B_{k-1,k} \text{ and } j_1 \text{ are inj.}\} / G_v^{\mathbb{C}}$$



From RHS to T^*F :

Get a flag $E^k = \text{Im } j_1 B_{1,2} \dots B_{k-1,k}$.

$$E^1 \supset \dots \supset E^n.$$

Take $A = j_1 i_1 \in \text{End } \mathbb{C}^r$.

$$A(E^k) \subset E^{k+1};$$

$$j_1 i_1 j_1 B_{1,2} \dots B_{k-1,k} = j_1 B_{1,2} B_{2,1} B_{1,2} \dots B_{k-1,k}$$

(like moving $B_{1,2}$ to the left and create $B_{2,1} B_{1,2}$)

$$= j_1 B_{1,2} \dots B_{k-1,k} B_{k,k-1} B_{k-1,k} = j_1 B_{1,2} \dots B_{k-1,k} B_{k,k+1} B_{k+1,k}$$

and hence image lies in $\text{Im}(j_1 B_{1,2} \dots B_{k-1,k} B_{k,k+1}) = E^{k+1}$.

Surjective:

construct $j_1, B_{k-1,k}$ according to the flag E .

$$A(\mathbb{C}^r) \subset E^1 = \text{Im } j_1 \stackrel{j_1}{\cong} V_1 \text{ defines } i_1.$$

Similarly $A(E^k) \subset E^{k+1}$ defines $B_{k+1,k}$.

Injective:

If (B, i, j) and (B', i', j') give the same (E, A) , can make $B_{k-1,k} = B'_{k-1,k}$ and $j = j'$ by $G_v^{\mathbb{C}}$.

$$A = j_1 i_1 = j'_1 i'_1 = j_1 i'_1$$

implies $i_1 = i'_1$ since j_1 is inj.

$$B_{1,2} B_{2,1} + i_1 j_1 = 0 = B'_{1,2} B'_{2,1} + i'_1 j'_1$$

and $B_{1,2} = B'_{1,2}$ implies $B_{2,1} = B'_{2,1}$.

Keep on doing this, get $(B, i, j) = (B', i', j')$.

$$M_{(\zeta_{\mathbb{R}}, 0)} \rightarrow T^*F$$

is open and closed, and hence is iso:

Whether $G_v^{\mathbb{C}}$ -orbit has solution to $\mu_{\mathbb{R}} = \zeta_{\mathbb{R}}$ is open cond.

The map $A = j_1 i_1: M_{(\zeta_{\mathbb{R}}, 0)} \rightarrow \text{End}(\mathbb{C}^r)$ is proper and hence closed.

([Kraft-Procesi] proved $M_0 \rightarrow \text{End}(\mathbb{C}^r)$ is isom. to closure of conj. class of a nilpotent matrix.)