

In this lab we'll study the **FitzHugh-Nagumo** model. To do so, we'll use the software package *XPPAUT*.

First, download and install the software from here,

<http://www.math.pitt.edu/~bard/xpp/download.html>

In lab we'll consider the model at two different values of parameter $I = \{0, 0.5\}$. You'll learn to:

- Write an *.ode* file for the FitzHugh-Nagumo model.
- Compute numerical solutions to the model and plot V vs t .
- Plot the phase portrait or scaled direction field.
- Plot the nullclines.
- Find the fixed point(s) numerically and check stability (through examination of eigenvalues).

Questions to answer in lab

1. For $I = 0$:
 - (a) How many fixed points exist?
 - (b) What is the stability of each?
 - (c) Convince yourself of both the number and stability of the fixed point(s) in two or more ways.

TABLE I. A list of XPPAUT keystroke commands I find useful

Plot vs time	X-Enter
Erase plot	E
Edit 2-d axes	V-2
Zoom in/out	W-Z or W-O
Zoom to fit	W-F
Run simulation	I-C
Run simulation from last point	I-L
Plot nullcline	N-N
Plot direction field	D-S
Find the fixed points	S-G

Also see

<http://www.math.pitt.edu/~bard/xpp/help/xpphelp.html>

for more commands and useful hints. And

<http://www.math.pitt.edu/~bard/bardware/tut/>

for XPPAUT tutorials.

We used XPPAUT to find numerically the fixed points of the FitzHugh-Nagumo model, and explored how these fixed points changed with parameter I . What if we instead demand an exact formula for the fixed point? To start, fix parameter $I = 0$ and solve the system of equations:

$$0 = \bar{V} - \frac{\bar{V}^3}{3} - \bar{W} \quad (1)$$

$$0 = \phi(\bar{V} + a - b\bar{W}) \quad (2)$$

for \bar{V} and \bar{W} . Is this an easy or hard problem? We'll attempt to do this by hand in lab, and see that finding a solution is not so simple. If we *really* want to know this formula, we can use the software package *Mathematica*. This should already be installed on the lab computers, and you can acquire this software and install it for free if you're a BU student. In lab, we'll use Mathematica to solve this system of equations and find an expression for the fixed point (\bar{V}, \bar{W}) as a function of I . We'll see it's not pretty . . .

Questions to answer in lab

1. Use Mathematica to find an expression for the fixed point (\bar{V}, \bar{W}) as a function of the parameter I . Plot the fixed points as a function of I .

Challenge Problems (Please answer three.)

1. For the FitzHugh-Nagumo model consider the range of parameter values $0 \leq I \leq 0.5$. At approximately what parameter value does the model begin spiking? Describe (in words and pictures) how the nullclines change as I increases through this range of parameters. Also describe how the eigenvalues change at the transition from resting to spiking.
2. Consider $I = 0.4$. Plot the nullclines in the (V, W) -plane, and explain how an orbit moves between and along the nullclines. *Suggestion:* Plot the scaled direction field and the periodic trajectory.
3. Using the tools developed in lab, study the following model:

$$\frac{dx}{dt} = f(x) + y + I \quad (3)$$

$$\frac{dy}{dt} = g(x) - y \quad (4)$$

where $f(x) = -x^3 + ax^2$, and $g(x) = 1 - bx^2$. Fix the parameters $a = 3$ and $b = 5$, and consider the range of values for parameter I : $-0.1 < I < 0.1$. How do the dynamics of the model change as I is varied in this range? To answer this, consider plotting the nullclines and phase portrait, finding the fixed points, and determining their stability for different values of I .

4. Using the tools developed in lab, study the following model:

$$\frac{dV}{dt} = I - g_L(V - E_L) - g_{Na}m_\infty(V)(V - E_{Na}) - g_Kn(V - E_K) \quad (5)$$

$$\frac{dn}{dt} = \frac{n_\infty(V) - n}{\tau_n(V)} \quad (6)$$

where

$$m_\infty(V) = 1/(1 + \exp((-20 - V)/15.0)) \quad (7)$$

$$n_\infty(V) = 1/(1 + \exp((-45 - V)/5)) \quad (8)$$

$$\tau_n(V) = 10 \quad (9)$$

Fix the parameters $g_L = 8$, $E_L = -78$, $g_K = 10$, $E_K = -90$, $g_{Na} = 20$ and $E_{Na} = 60$, and consider the range of values for parameter I : $0 < I < 20$. How do the dynamics of the model change as I is varied in this range? To answer this, consider plotting the nullclines and phase portrait, finding the fixed points, and determining their stability for different values of I .

5. Make up your own challenge. Make it interesting.