

## 7. Random variables as observables

**Definition 7.** A random variable (function)  $X$  on a probability measure space is called an *observable*

Note all functions are assumed to be measurable henceforth.

Note that if  $(\Omega, \mathcal{F}, \mathbb{P})$  is a probability space, then the family of (essentially) bounded random variables (functions on  $\Omega$ )  $X(\omega)$  has the structure of an integration algebra  $(\mathbf{A}, E)$ , with

$$E(X) = \int X(\omega) d\mathbb{P}(\omega).$$

In probability we interpret  $\Omega$  as the space of all possible outcomes, and for each outcome  $\omega$ , we define  $X(\omega)$  to be the value of the observable  $X$  given the outcome  $\omega \in \Omega$ .

We can call  $X(\omega)$  an observable.

We may study the integration algebra directly, since it determines the structure of the probability space up to isomorphisms (measure-preserving transformations).

Note that the algebra  $\mathbf{A}$  of observables is commutative, since  $X(\omega)Y(\omega) = Y(\omega)X(\omega)$ .

**Generalization:** Consider that in quantum mechanics observables also form an algebra which is more general, since it is non-commutative. But each observable still has an expected value.

**Example 3.** Consider the motion of a particle on the line  $\mathbb{R}^1$ . Let  $\mathcal{H} = L^2(\mathbb{R})$ . If  $\psi(x) \in \mathcal{H}$  and  $\|\psi\| = 1$  then  $\psi$  represents a *probability amplitude* that particle is located at  $x$ . Also  $|\psi(x)|^2$  represents the probability that particle is located at  $x$ .

The operator  $B = M_x$  (multiplication by  $x$ ) on  $L^2(\mathbb{R})$  is the *position operator*. If particle is in state  $\psi(x)$ , then its expected position is

$$\begin{aligned}\langle \psi, B\psi \rangle &= \int_{-\infty}^{\infty} dx \bar{\psi}(x) B\psi(x) = \int_{-\infty}^{\infty} dx \bar{\psi}(x) M_x \psi(x) \\ &= \int_{-\infty}^{\infty} \bar{\psi}(x) x \psi(x) dx = \int_{-\infty}^{\infty} x |\psi(x)|^2 dx\end{aligned}$$

The operator  $C = \frac{1}{i} \frac{\partial}{\partial x}$  (differentiation with respect to  $x$ ) on  $L^2(\mathbb{R})$  is the *momentum operator*. The expected momentum is

$$\langle \psi, C\psi \rangle = \int_{-\infty}^{\infty} dx \bar{\psi}(x) \frac{1}{i} \frac{\partial}{\partial x} \psi(x)$$

$$= -i \int_{-\infty}^{\infty} dx \bar{\psi}(x) \psi'(x).$$

Generally any observable quantity corresponds to a self-adjoint operator  $A$  on  $\mathcal{H}$ , and its expectation value (in a given state  $\psi \in \mathcal{H}$ ) is

$$E(A) = \langle \psi, A\psi \rangle.$$

## 8. Random variables as observables, I

We now view a random variable  $X(\omega)$ ,  $\omega \in \Omega$  as having a value for each outcome in the universe  $\Omega$  of outcomes. In other words,  $X$  has a value for each of the possible 'worlds' (possible  $\omega$  representing our reality) that we are in.

We have seen that just knowing expectation values of an algebra of random variables on  $\Omega$  is sufficient to determine the structure of  $\Omega$ .



Henceforth we will focus on the algebra structure  
of the (bounded) random variables  
 $\mathbf{A} = \{X(\omega) : X \text{ is a RV on } \Omega\}$ .

Now consider  $\mathcal{H} = L_{\mathbb{C}}^2(\Omega)$ . If  $\psi(\omega) \in \mathcal{H}$ , then  $\rho(\omega) = |\psi^2(\omega)| \in L_{\mathbb{R}}^1(\Omega)$ , and represents a probability distribution on the possible outcomes  $\omega \in \Omega$ . If  $X \in \mathbf{A}$ , then in probability

$$E(X) = \int_{\Omega} X(\omega) \rho(\omega) d\omega$$

$$= \int_{\Omega} \overline{\psi}(\omega) X(\omega) \psi(\omega) dP(\omega)$$

$$= \langle \psi(\omega), X(\omega) \psi(\omega) \rangle = \langle \psi, X\psi \rangle.$$

Thus we can interpret a state  $\psi(\omega)$  to be a probability distribution  $\rho(\omega) = |\psi(\omega)|^2$  on  $\Omega$ .

It represents our current knowledge of the world as a probability distribution  $\rho(\omega)$  on  $\Omega$ .

## 9. An alternative interpretation of $\psi(\omega)$

Note that if we have a state  $\psi$ , it forms a linear functional  $\phi$  on the set of observables  $X \in \mathbf{A}$ . Specifically, define

$$\phi(X) = E_\psi(X) = \int X(\omega) |\psi|^2(x) dP(\omega) = \langle \psi, X\psi \rangle.$$

Thus a state  $\psi$  can be interpreted as a linear functional  $\phi : \mathbf{A} \rightarrow \mathbb{C}$ .

**Definition 8.** More generally, we will define a *state* to be *any* bounded linear functional  $\phi$  on **A**.

## 10. Summary of commuting observables

So far we have showed that studying an algebra  $\mathbf{A}$  of random variables on a probability space  $\Omega$  is entirely equivalent to knowing the algebra structure of  $\mathbf{A}$ , i.e. knowing  $XY$  and  $aX + bY$  (for  $a, b \in \mathbb{C}$ ) if we know  $X$  and  $Y$ .

We call the algebra  $\mathbf{A}$  of observables *commuting* because  $XY = YX$  if  $X, Y \in \mathbf{A}$ .

We have seen that if  $\psi(\omega) \in L^2(\Omega)$ , then  $|\psi|^2(\omega) \in L^1(\Omega)$  and represents a *new* probability distribution on  $\Omega$ .

Note that the expectation with respect to this new distribution is

$$E_\psi(X) = \int_{\Omega} X(\omega) \underbrace{|\psi|^2(\omega) dP(\omega)}_{P_\psi(\omega)}.$$

Note that this is equivalent to defining a *new* measure on  $\Omega$

$$P_\psi = |\psi|^2(\omega)dP(\omega),$$

i.e., Radon-Nikodym derivative

$$\frac{dP_\psi}{dP} = |\psi|^2(\omega).$$

We have defined the state  $\psi$  through its expectation  $E_\psi$  above as a linear functional on  $X \in \mathbf{A}$ .

More generally, we have now defined a *state* as *any* linear functional  $\phi : \mathbf{A} \rightarrow \mathbb{C}$ .



But note that this  $E_\psi$  is an *expectation* on the algebra  $\mathbf{A}$  of random variables (i.e. satisfies the 4 properties defined earlier).

Thus we have a

**Proposition.** Given a probability space  $\Omega$ , an algebra  $\mathbf{A}$  of random variables on  $\Omega$ , and  $\psi(\omega) \in L^2(\Omega)$  with  $\|\psi\| = 1$ , there is a unique expectation  $E_\psi$  defined on  $\mathbf{A}$  given by

$$E_\psi(X) = \int_{\Omega} X(\omega) |\psi|^2(\omega) dP(\omega).$$

Note that this expectation can be interpreted as giving the average value of any observable  $X$  given the underlying state  $\psi$  on  $\Omega$ .

## 11. Non-commuting observables

Recall from above we have an algebra  $\mathbf{A}$  of observables  $X$  together with an expectation  $E$  on the algebra (we denote  $E = E_\psi$  for now). These form a *integration algebra* defined above.

We define the total measure of the integration algebra to be  $E(1)$  (i.e. expectation of the function  $X = 1$ ).

If  $E(1) = 1$  (i.e. total measure is 1) we will call  $\mathbf{A}$  a *probability algebra*.

Thus a probability algebra  $\mathbf{A}$  is just a generalization of the collection of random variables on a probability space  $\Omega$ .

Let's generalize the above ideas to the case where observables do not commute, i.e. we have an algebra  $\mathbf{A}$  of observables where  $XY \neq YX$ .