Much more on linear differential equations

Recall the following important defintions from last class:

A first-order differential equation

$$\frac{dy}{dt} = f(t, y)$$

with independent variable t and dependent variable y is linear if it can be written as

$$\frac{dy}{dt} = a(t)y + b(t).$$

In other words, the dependent variable only appears linearly in the equation.

The linear differential equation

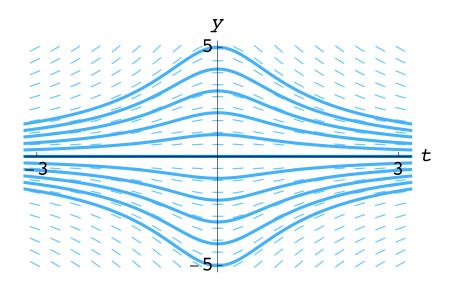
$$\frac{dy}{dt} = a(t)y + b(t)$$

is **homogeneous** if b(t) = 0 for all t. Otherwise, it is **nonhomogeneous**. (Some people use the term inhomogeneous.)

Where have we seen homogeneous linear differential equations before?

MA 226 February 19, 2015

Example.  $\frac{dy}{dt} = \frac{-ty}{1+t^2}$ 



Linearity Principles

Why are linear equations so much more amenable to analytic techniques than nonlinear equations? The reason is that their solutions satisfy important linearity principles.

Let's begin with homogeneous linear equations:

**Linearity Principle.** If  $y_h(t)$  is a solution of a homogeneous linear differential equation

$$\frac{dy}{dt} = a(t) y,$$

then any constant multiple  $y_k(t) = k y_h(t)$  of  $y_h(t)$  is also a solution. In other words, given a constant  $k \neq 1$  and a nonzero solution  $y_h(t)$ , we obtain another solution by multiplying  $y_h(t)$  by k.

Note that the Linearity Principle is not true for nonlinear equations. For example, consider

$$\frac{dy}{dt} = y^2.$$

Check that one solution is

$$y_1(t) = \frac{1}{1-t},$$

and then check that

$$y_2(t) = 2y_1(t) = \frac{2}{1-t}$$

is not a solution.

There is a similar "linearity" principle for nonhomogeneous linear equations:

Extended Linearity Principle For First-Order Equations. Consider a first-order, nonhomogeneous, linear equation

$$\frac{dy}{dt} = a(t)y + b(t)$$

and its associated homogeneous equation

$$\frac{dy}{dt} = a(t)y.$$

- 1. If  $y_h(t)$  is any solution of the homogeneous equation and  $y_p(t)$  ("p" for particular solution) is any solution of the nonhomogeneous equation, then  $y_h(t) + y_p(t)$  is also a solution of the nonhomogeneous equation.
- 2. Suppose  $y_p(t)$  and  $y_q(t)$  are two solutions of the nonhomogeneous equation. Then  $y_p(t) y_q(t)$  is a solution of the associated homogeneous equation.

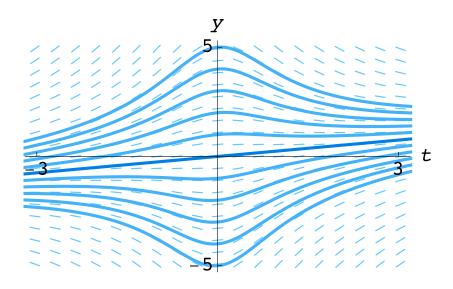
Therefore, if  $y_h(t)$  is nonzero,  $ky_h(t) + y_p(t)$  is the general solution of the nonhomogeneous equation.

We can paraphrase the Extended Linearity Principle by saying that:

The general solution of a nonhomogeneous linear equation consists of the sum of any particular solution of the nonhomogeneous equation and the general solution of the associated homogeneous equation.

MA 226 February 19, 2015

Example.  $\frac{dy}{dt} = \frac{-ty}{1+t^2} + \frac{2t^2+1}{4t^2+4}$ 



The Extended Linearity Principle provides one way to solve nonhomogeneous equations:

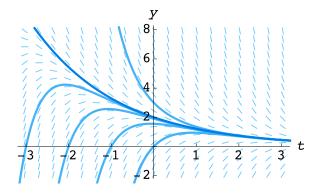
## Method of the Lucky Guess:

- 1. Solve the associated homogeneous equation.
- 2. Guess one solution to the nonhomogeneous equation.

How do we go about guessing a solution? This question is best answered by doing a number of typical examples.

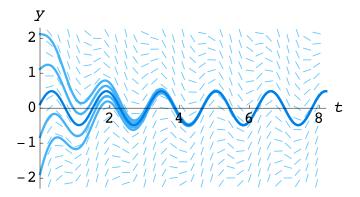
Example 1. 
$$\frac{dy}{dt} = -2y + 3e^{-t/2}$$

- 1. General solution of the associated homogeneous equation:
- 2. Particular solution of the nonhomogeneous equation:



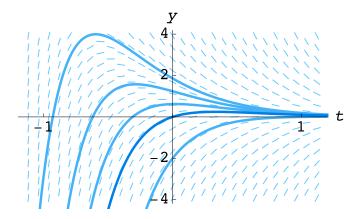
Example 2.  $\frac{dy}{dt} = -y + 2\cos 4t$ 

- 1. General solution of the associated homogeneous equation:
- 2. Particular solution of the nonhomogeneous equation:



**Example 3.**  $\frac{dy}{dt} = -3y + 2e^{-3t}$ 

- 1. General solution of the associated homogeneous equation:
- 2. Particular solution of the nonhomogeneous equation (trick question):



The method of integrating factors

For this method we rewrite the nonhomogeneous equation

$$\frac{dy}{dt} = a(t)y + b(t)$$

as

$$\frac{dy}{dt} + g(t)y = b(t).$$

In other words, g(t) = -a(t). There is no mathematical significance to this step. It just avoids an annoying minus sign in one of the formulas.

Now for some magic:

Summary: Given a linear differential equation of the form

$$\frac{dy}{dt} + g(t)y = b(t),$$

the integrating factor (magic function) is  $\mu(t) = e^{\left(\int g(t) dt\right)}$ .