1. (20 points) The following volume problem appeared in Marilyn Vos Savant's April 20, 1996 column:

Start with a solid sphere of any radius greater than 6 inches. Bore a cylindrical hole through the center of the sphere so that what remains is exactly 6 inches high. (The center line of the cylinder should correspond to a diameter of the sphere.) What is the volume of the solid that remains after the cylindrical hole is removed?

Calculate this volume. Does it depend on the radius R of the original sphere?



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If
$$u = R^2 - r^2$$
, then
 $du = -2rdr$
 $r = R \Rightarrow u = 0$
 $r = \sqrt{R^2 - q} \Rightarrow u = 9$.

Then
volume =
$$\int_{0}^{2\pi} \int_{0}^{7} u^{\frac{1}{2}} du d\theta$$
.
Note that this integral does not depend
on R. We get
volume = $\int_{0}^{2\pi} \left[\frac{2}{3} u^{\frac{3}{2}}\right]_{0}^{9} d\theta$
 $= \int_{0}^{2\pi} 18 d\theta = 36\pi$.

2. (20 points) Suppose the D is an elementary region in \mathbb{R}^3 that is symmetric with respect to the yz-plane. In other words, a point (x, y, z) is in D if and only if the point (-x, y, z) is in D. Using the Change of Variables Theorem, show that

$$\iiint_D f(x, y, z) \, dV = 0$$

if f(x, y, z) is an odd function in x. (A function $f : \mathbb{R}^3 \to \mathbb{R}$ is odd in x if f(-x, y, z) = -f(x, y, z) for all $(x, y, z) \in \mathbb{R}^3$.)

Subdivide D into two regions
$$D_1$$
 and D_2
such that
 $D_1 = \{(x,y,z) \mid (x,y,z) \in D \text{ and } x \ge 0\}$
 $D_2 = \{(x,y,z) \mid (x,y,z) \in D \text{ and } x \le 0\}$

Then
$$\iiint \neq dV = \iiint \neq dV + \iint \neq dV$$
.
D D₁ D₂

Consider the mapping
$$T: D_1 \rightarrow D_2$$

given by $T(x, y, z) = (-x, y, z)$.
The Jacobian of T is
 $\left(\det \begin{bmatrix} -1 & 0 & 0\\ 0 & 1 & 0\\ 0 & 0 & 1 \end{bmatrix} \right) = 1$.
By the Change of Variables Therew,
we have
 $\iiint f(x, y, z) dV = \iiint f(T(x, y, z)) - 1/dV$
 D_2
 $= \iiint f(-x, y, z) dV$

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 $= -1 \iiint f(x,y,z) = T$

Since
$$\iiint \neq AV = - \iiint \neq dV$$

 D_2 D_4

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- 3. (20 points) The method of least squares approximation is described on page 246 of our text. In this problem, we use notation that is discussed there.
 - (a) Consider the three data points $(x_1, y_1) = (1, 1)$, $(x_2, y_2) = (2, 3)$, and $(x_3, y_3) = (3, 2)$. Find the equation of the best straight-line fit according to the method of least squares. Calculate the equation for the line directly. (In other words, don't use the result of Exercise 32 on page 247.) Give a rigorous justification of why this line minimizes s.
 - (b) Solve Exercise 32 on page 247, and use the result to give explicit formulas for m and b.
 - (c) Solve Exercise 34 on page 247.
 - (d) Use the method of least squares to find the line that best fits the points (0, 2), (1, 4), (1, 3), (2, 6), and (3, 6). Plot the points and the line.

(a) We want to minimize $S(m,b) = (m+b+1)^2 + (2m+b-3)^2 + (3m+b-2)^2$ 1 data point data point data point (11) (2,3) (3,2) After some algebra, we obtain $S = 14m^2 + 12mb - 26m + 3b^2 - 12b + 14$ and $\frac{2s}{2m} = 28m + 12b - 26$ $\frac{2s}{2!} = 12m + 6b - 12$. To determine the critical points, we solve $\int \frac{37}{52} = 0$ We obtain one critical point, $(m,b) = (\pm 1)$ Applying the second partials test, we compute

25 = 6 $\frac{\partial^2 S}{\partial x^2} = 28$ $\frac{\partial^2 s}{\partial m \partial h} = 12$ Note that 325 >0 and $\left(\frac{\partial^2 S}{\partial m^2}\right)\left(\frac{\partial^2 S}{\partial h^2}\right) - \left(\frac{\partial^2 S}{\partial m \partial h}\right)^2 > 0$ and we have a local minimum at the critical point There are functions R2 -> R that have exactly one critical point which is a local minimum but not a global minimum! We can show that s(m, b) is not one of these functions using some analytic gemetry.

 $S(m,b) = \sum (y_i - mx_i - b)^2$ (b)Then $2s_m = -2 \sum (y_i - mx_i - b)(x_i)$ $\frac{\partial S}{\partial L} = -2\Sigma (y_i - M X_i - b).$ The critical points satisfy $\Sigma(x_iy_i - mx_i^2 - bx_i) = 0$ $\Sigma(y_i - m \times i - b) = 0$. The second equation implies mZxi+nb = Zyi In terms in sum The first equation implies

MZXi + bZK: = ZXiyi.

If we let Sx denote Exi Sy denote Z yi Sx2 denote ZX2 Sxy denote Zxifi, then we have the system of two equations in two unknowns (mand b) $(S_{X}) m + nb = S_{Y}$ $(S_{x^2})m + (S_x)b = S_{xy}.$ We can write this system as a matrix equation $\begin{bmatrix} S_{X} & n \end{bmatrix} \begin{bmatrix} m \\ S_{X^{2}} & S_{X} \end{bmatrix} \begin{bmatrix} m \\ b \end{bmatrix} = \begin{bmatrix} s_{y} \\ S_{Xy} \end{bmatrix}$ Solving we obtain $\begin{bmatrix} m \\ m \end{bmatrix} = \begin{bmatrix} S_{X} & n \\ S_{X^{2}} & S_{X} \end{bmatrix} \begin{bmatrix} S_{Y} \\ S_{X} \\ S_{Y} \end{bmatrix} = \frac{1}{(r_{X})^{2} - nS_{X^{2}}} \begin{bmatrix} (S_{X})(S_{Y}) - n \\ (S_{X})(S_{Y}) - nS_{X^{2}} \end{bmatrix}$

(c) Using the formulas for
$$\frac{25}{5m}$$
 and
 $\frac{25}{5b}$ in part(b), we have
 $\frac{25}{5m^2} = 2 \sum x_i^2$
 $\frac{25}{5m^2} = 2n$
 $\frac{225}{5m^2} = 2 \sum x_i$

It is clear that
$$\frac{\partial^2 S}{\partial m^2} > 0$$
. We need only compute $\left(\frac{\partial^2 S}{\partial m^2}\right)\left(\frac{\partial^2 S}{\partial b^2}\right) - \left(\frac{\partial^2 S}{\partial m\partial b}\right)^2$.

Both terms have a factor of 4 that we ignore The rect is $n \sum x_i^2 - (\sum x_i)^2$. To see that this expression is positive, we eliminate all terms of the form Xi² from the second sum and obtain

$$(n-1) \mathbb{Z} \times t^2 - 2(\mathbb{Z} \times t \times t)$$

 $\mathbb{I} \leq t \leq n$

Note that the second sum involves 1+2+3+ + n-1 terms. Summing we set that three are

terms. For each such term

Since there are (n-1)n such terms in this sum, we have enough terms to write $(n-1) \sum x_i^2 - 2(\sum x_i x_j) =$ $\sum (x_i - x_j)^2$ $1 \le i \le j \le n$ Since this sum is clearly positive, the second derivative test implies that we have a local minimum.

(d) Using the formulas in part (b)
we obtain

$$m = \frac{19}{13} \approx 1.46$$

 $b = \frac{28}{13} \approx 2.15$.

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4. (20 points) Rewrite the integral

$$\int_0^1 \int_0^{1-x^2} \int_0^{1-x} f(x, y, z) \, dz \, dy \, dx$$

as an equivalent iterated integral in the five other orders.

First we skitch the solid region
of integration.
The solid has
five "sides."
Three of the sides
lie in the
coordinate planes.
The original integral
$$\int_{0}^{1} \int_{0}^{1-\chi^{2}} \int_{0}^{1-\chi} f(x,y,z) dz dy dx$$

involves projecting the region into
the xy-plane. The corresponding
side is
 $\int_{0}^{1} \int_{0}^{1-\chi} \int_{0}^{1-\chi} f(x,y,z) dz dy dx$
Involves projecting the region into
the xy-plane. The corresponding
side is
 $\int_{0}^{1} \int_{0}^{1-\chi} f(x,y,z) dz dy dy$

The projection of the region into the $x \ge -\beta$ lane is the triangle $1 \xrightarrow{7} = 1 - x$ or x = 1 - 2Using this triangle as our "base", we obtain the two integrals 1 1 1-x 1-x² f(x,y,z) by de dx and ∫¹∫¹⁻²∫^{1-x²} f(x,y,z) dydx d2



Unfortunately we need to subdivide the square into two sub regions based on the 15 projection of the boundary curve common to the plane x+z=1 and the surface y=1-x2. Since and X + 2 = 1y=1-x2 we have $y = 1 - (1 - 2)^2$ = 22-22. 2 1 1= - y=22-22 over this 04×41-5 over this 0=x= VI-y The last two orders of integration must be expressed as the sum of two separate integrals: For dx dy de, we have [1] 22-22 (1-2 f(x,y,2) dx by dz + $\int_{1}^{1} \int_{1}^{1} \int_{1}^{1-y} f(x,y,z) dx dy dz$

For dx dz dy, we must solve for z in the equation $y = 2z - z^2$, we apply the quadratic formula to $z^2 - 2z + y = 0$, and we obtain $z = 1 \pm \sqrt{1-y}$. In our case, $z = 1 - \sqrt{1-y}$. The last integral is $\int_{0}^{1} \int_{0}^{1-\sqrt{1-y}} \int_{0}^{\sqrt{1-y}} f(x,y,z) dx dz dy +$ $\int_{0}^{1} \int_{0}^{1} \int_{0}^{1} \int_{0}^{1-2} f(x,y,z) dx dz dy +$ 5. (20 points) Suppose 0 < a < b. Let

 $\Phi(u, v) = (b\cos u + a\cos v\cos u, b\sin u + a\cos v\sin u, a\sin v).$

- (a) Show that $\Phi(u, v)$ parametrizes the torus that is obtained by rotating about the *z*-axis the circle in the *xz*-plane with center (b, 0, 0) and radius a < b.
- (b) Calculate the surface area of this torus.

(a) Consider the slice of the torus
by the half-plane described
in cylindrical coordinates as

$$\Theta_0$$
 fixed and $r > 0$.
This slice is a circle of
radius a centered at
 $(r, \Theta, Z) = (b, \Theta_0, 0)$.
 $Z = \left(\begin{array}{c} z \\ z \\ z \end{array}\right)$

We can parametrize this circle using sine and cosine $r = b + a \cos x$ $z = a \sin x$ The or-interval $0 \le x \le 2\pi$

Converting this description of the torus to rectangular coordinates yields the parametrization $\chi = \gamma \cos u = (b + \alpha \cos u) \cos u$ y = r sin u = (b + a corv) sin u 7 = Q SINNS The variable is identical to the coordinate O in cylindrical coordinates. (6) $\overline{\Phi}_{u} = \left[-(b + a \cos v) \sin u \right] T +$ (btacrew) corult Fur = [- a crow sin of] + [-a sin u sin u]] + [a con or] Te

Then + [acb+acosv)(sinv)(cosv)]] + [a(b+acorv)(simv)]te. and $\| \overline{\phi}_{1} \times \overline{\phi}_{1} \|^{2} = a^{2} (b + a \cos^{2})^{2}.$ Since dS = II Dux Du II dA R uv-plane surface area = {] a (b + a coto) dudu $= \int_{-\infty}^{2\pi} \int (ab + a^2 \cos w) dw dw$ = [2Th (2Th (ab) du dus = 452 ab