

Classical Adjoint and Cramer's Rule

Today we study two computationally oriented applications of the determinant which are sometimes theoretically useful.

Recall the definitions of cofactors and the determinant.

Definition. Given an $n \times n$ matrix \mathbf{A} , the ij th minor \mathbf{A}_{ij} of \mathbf{A} is the $(n-1) \times (n-1)$ matrix obtained from \mathbf{A} by eliminating the i th row and j th column. The ij th cofactor of \mathbf{A} is

$$C_{ij} = (-1)^{i+j} \det \mathbf{A}_{ij}.$$

Definition/Theorem. If \mathbf{A} is an $n \times n$ matrix, the determinant of \mathbf{A} can be computed using cofactor expansion along the i th row by

$$\det \mathbf{A} = a_{i1}C_{i1} + a_{i2}C_{i2} + \dots + a_{in}C_{in}$$

or by cofactor expansion along the j th column by

$$\det \mathbf{A} = a_{1j}C_{1j} + a_{2j}C_{2j} + \dots + a_{nj}C_{nj}.$$

Any row or any column yields the same result.

Both of these formulas are reminiscent of matrix multiplication except for the fact that the indexes are not quite right.

Given an $n \times n$ matrix \mathbf{A} , there is a cofactor C_{ij} for each entry of the matrix. Hence, we can make another $n \times n$ matrix \mathbf{C} using the cofactors of \mathbf{A} .

Example. Let

$$\mathbf{A} = \begin{bmatrix} 2 & 1 & 1 \\ 1 & 1 & 0 \\ 0 & 0 & 3 \end{bmatrix}.$$

Its matrix of cofactors is

$$\mathbf{C} = \begin{bmatrix} 3 & -3 & 0 \\ -3 & 6 & 0 \\ -1 & 1 & 1 \end{bmatrix}.$$

Why are the diagonal terms the way that they are?

What about the off diagonal terms? For example, consider the 1,2-term of the product $\mathbf{A}\mathbf{C}^T$.

Definition. The *classical adjoint* $\text{adj } \mathbf{A}$ of an $n \times n$ matrix \mathbf{A} is the transpose of its matrix of cofactors. It is also called the adjugate of \mathbf{A} .

Theorem. For any $n \times n$ matrix \mathbf{A} ,

$$\mathbf{A}(\text{adj } \mathbf{A}) = (\det \mathbf{A}) \mathbf{I}.$$

If $\det \mathbf{A} \neq 0$, then

$$\mathbf{A}^{-1} = \frac{1}{\det \mathbf{A}} \text{adj } \mathbf{A}.$$

Cramer's Rule

As we have seen, the linear system

$$\mathbf{Ax} = \mathbf{b}$$

has the unique solution $\mathbf{x} = \mathbf{A}^{-1}\mathbf{b}$. Using the formula above for \mathbf{A}^{-1} , we can derive an appealing formula for $\mathbf{A}^{-1}\mathbf{b}$.

Summary. The k th component x_k of the vector $\mathbf{x} = \mathbf{A}^{-1}\mathbf{b}$ is given by

$$x_k = \frac{\det \mathbf{B}_k}{\det \mathbf{A}},$$

where the matrix \mathbf{B}_k is the obtained from the matrix \mathbf{A} by replacing the k th column of \mathbf{A} with \mathbf{b} .

Example. Solve the system

$$3x_1 - x_2 + x_3 = 4$$

$$x_1 + x_2 + x_3 = 2$$

$$x_1 - x_2 - x_3 = -1.$$

Warning. Using the classical adjoint or Cramer's Rule usually involves a lot more work than the row reduction techniques that we have already discussed.