

Subspaces of vector spaces

Definition. A nonempty subset S of a vector space V is a *subspace* of V if

1. the zero vector $\mathbf{0}$ is in S ,
2. (closure under vector addition) for each \mathbf{v}_1 and \mathbf{v}_2 in S , the vector sum $\mathbf{v}_1 + \mathbf{v}_2$ is in S , and
3. (closure under scalar multiplication) for each r in \mathbb{R} and each \mathbf{v} in S , the scalar multiple $r\mathbf{v}$ is in S .

Note. A subspace S of a vector space V is a vector space in its own right.

Example. Consider the line $x_2 = 3x_1$ in the vector space \mathbb{R}^2 .

Example. Consider the line $x_2 = x_1 + 1$ in the vector space \mathbb{R}^2 .

Example. Let \mathbb{P} represent the vector space of all polynomial functions as discussed last class. Is \mathbb{P} a subspace of the vector space of all functions $f : \mathbb{R} \rightarrow \mathbb{R}$?

Example. Consider the subset $S = \text{Span}\{x, x^2\}$ within \mathbb{P} . Is S a subspace of \mathbb{P} ?

Theorem. If $\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_p$ are vectors in a vector space V , then $\text{Span}\{\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_p\}$ is a subspace of V .

Subspaces associated to a matrix

There are three important subspaces associated to an $m \times n$ matrix \mathbf{A} .

The null space of \mathbf{A} . The null space of \mathbf{A} is the set of all vectors \mathbf{x} in \mathbb{R}^n such that

$$\mathbf{Ax} = \mathbf{0}.$$

The null space of \mathbf{A} is denoted by $\text{Nul } \mathbf{A}$.

Theorem. The null space of an $m \times n$ matrix \mathbf{A} is a subspace of \mathbb{R}^n .

Application. Any plane through the origin in \mathbb{R}^3 is a subspace of \mathbb{R}^3 .

Example. Consider the matrix

$$\mathbf{A} = \begin{bmatrix} 1 & -2 & 0 & 4 & 0 \\ 0 & 0 & 1 & -9 & 0 \\ 2 & -4 & 0 & 8 & 1 \end{bmatrix}.$$

Express the null space of \mathbf{A} as the span of as few vectors as possible.