Evolutions of Logifold Structures on Measure Spaces

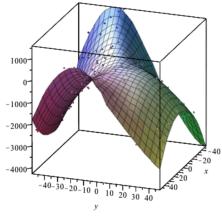
Inkee Jung Boston University

May 28 - 31

Based on Logifold structure on measure space joint work with Siu-Cheong Lau (arXiv:2405.05492) BU-Keio-Tsinghua Workshop 2024 on Differential Equation Dynamical System and Applied Mathematics

"Manifold" in Data Science

Interpolation

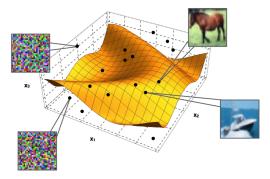


(Image from Maple16)

< ≣⇒

"Manifold" in Data Science

High-dimensional analogue of 2 dimensional surface in \mathbb{R}^N



(Image from Sebastian Goldt, Marc Mézard, Florent Krzakala, and Lenka Zdeborová)

Manifold : Local-to-Global Principle

Locally Euclidean Space (M, U) with collection of local data $U = \{(U_{\alpha}, \Phi_{\alpha})\}$

- Modeling Spacetime by Einstein's theory of relativity
- Local-to-Global principle

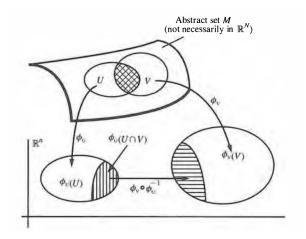
< 冊 > < Ξ

→

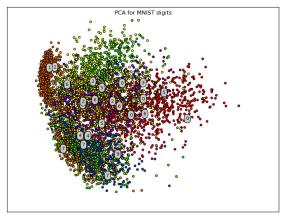
Manifold : Local-to-Global Principle

Locally Euclidean Space (M, U) with collection of local data $U = \{(U_{\alpha}, \Phi_{\alpha})\}$

- Modeling Spacetime by Einstein's theory of relativity
- Local-to-Global principle



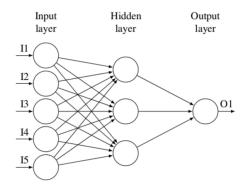
Is it really best formulation for dataset?



PCA for MNIST with 2 most important dimensions. (created by Vijayasaradhi Indurthi)

▲ □ ▶ ▲ □ ▶ ▲ □ ▶

Neural Network in Data Science



 $f = \sigma_2 \circ L_2 \circ \sigma_1 \circ L_1$

• Network models gain tremendous success in describing datasets

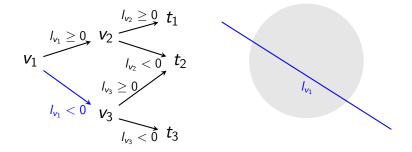
• In classification task, last layer is index-max function.

< /□ > < 三

→ ∃ →

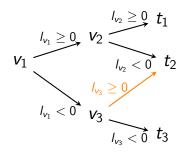
Motivated from Neural Network.

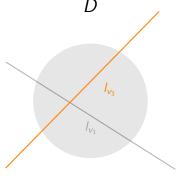
Example: Directed graph G & Set of affine maps $L = \{l_{v_1}, l_{v_2}, l_{v_3}\}$



Motivated from Neural Network.

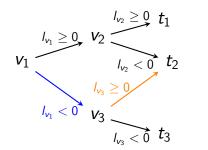
Example: Directed graph G & Set of affine maps $L = \{I_{v_1}, I_{v_2}, I_{v_3}\}$

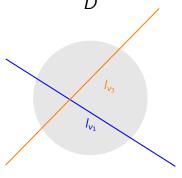




Motivated from Neural Network.

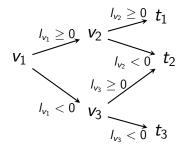
Example: Directed graph G & Set of affine maps $L = \{l_{v_1}, l_{v_2}, l_{v_3}\}$

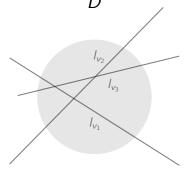




Motivated from Neural Network.

Example: Directed graph G & Set of affine maps $L = \{I_{v_1}, I_{v_2}, I_{v_3}\}$





- Measurable set $D \subset \mathbb{R}^n$, Finite set T.
- Directed finite graph G without cycle
- Affine maps

 $L = \{l_v : v \text{ is a vertex with more than one outgoing arrows}\}$

Definition

 $f_{G,L}: D \to T$ is a linear logical function of (G, L) if $I_v \in L$ are affine linear functions whose chambers in D are one-to-one corresponding to the outgoing arrows of v.

(G, L) is called a linear logical graph.

A (1) < A (2) < A (2) </p>

- Measurable set $D \subset \mathbb{R}^n$, Finite set T.
- Directed finite graph G without cycle
- Affine maps

 $L = \{l_v : v \text{ is a vertex with more than one outgoing arrows}\}$

Definition

 $f_{G,L}: D \to T$ is a linear logical function of (G, L) if $I_v \in L$ are affine linear functions whose chambers in D are one-to-one corresponding to the outgoing arrows of v.

(G, L) is called a linear logical graph.

Linear logical function as "local chart" of dataset.

・ 同 ト ・ ヨ ト ・ ヨ ト …

Definition (Lou van den Dries)

A structure S on the real line consists of a boolean algebra S_n of subsets of \mathbb{R}^n for each n = 0, 1, ..., such that

- $\{x \in \mathbb{R}^n : x_i = x_j\}, 1 \le i < j \le n \in S_n.$
- Closed under Cartesian product.
- Closed under projection $(A \in S_{n+1} \rightarrow \pi(A) \in S_n)$.
- $\{(x, y) \in \mathbb{R}^2 : x < y\} \in S_2.$

For instance:

$$\Phi := \{ (x, y) \in X \times Y : \phi(x, y) \}$$

$$\pi_Y(\Phi) = \{ y \in Y : \exists x \phi(x, y) \}$$

Definition (Lou van den Dries)

A structure S on the real line consists of a boolean algebra S_n of subsets of \mathbb{R}^n for each n = 0, 1, ..., such that

- $\{x \in \mathbb{R}^n : x_i = x_j\}, 1 \le i < j \le n \in S_n.$
- Closed under Cartesian product.
- Closed under projection $(A \in S_{n+1} \rightarrow \pi(A) \in S_n)$.
- $\{(x, y) \in \mathbb{R}^2 : x < y\} \in S_2.$
- Def(A) : The smallest structure on the real line contatining a collection A
- $f : A \rightarrow B$ is definable if its graph is definable.

くぼう くほう くほう

• A structure S : Geometric description of "definable sets" in mathematical logic.

47 ▶

- A structure S : Geometric description of "definable sets" in mathematical logic.
- A structure S is o-minimal if every *definable* subset is finite unions of intervals and points.

- A structure S : Geometric description of "definable sets" in mathematical logic.
- A structure S is o-minimal if every *definable* subset is finite unions of intervals and points.
- A semilinear set of \mathbb{R}^n : Finite unions of

$$\{x \in \mathbb{R}^n : f_1(x) = \cdots = f_k(x), g_1(x) > 0, \dots, g_l(x) > 0\}$$

with affines f_i and g_j .

- A structure S : Geometric description of "definable sets" in mathematical logic.
- A structure S is o-minimal if every *definable* subset is finite unions of intervals and points.
- A semilinear set of \mathbb{R}^n : Finite unions of

 $\{x \in \mathbb{R}^n : f_1(x) = \cdots = f_k(x), g_1(x) > 0, \dots, g_l(x) > 0\}$

with affines f_i and g_j .

• Semilinear set forms o-minimal structure.

- A structure S : Geometric description of "definable sets" in mathematical logic.
- A structure S is o-minimal if every *definable* subset is finite unions of intervals and points.
- A semilinear set of \mathbb{R}^n : Finite unions of

 $\{x \in \mathbb{R}^n : f_1(x) = \cdots = f_k(x), g_1(x) > 0, \ldots, g_l(x) > 0\}$

with affines f_i and g_j .

• Semilinear set forms o-minimal structure.

Theorem

A function $f : D \to T$ for a finite set T where $D \subset \mathbb{R}^n$ is semilinear if and only if it is a linear logical function.

Proof of idea : Systematically construct one-to-one correspondence between the two categories of functions.

Inkee Jung Boston University

Evolutions of Logifold Structures on Measure

May 28 - 31

Universality of Linear logical function

- $D \subset \mathbb{R}^N$ with $\mu(D) < \infty$, where μ is the Lebesgue measure.
- T is finite

Theorem

For any (Lebesgue) measurable function $f: D \to T$, we have a linear logical function that approximates to f.

Universality of Linear logical function

- $D \subset \mathbb{R}^N$ with $\mu(D) < \infty$, where μ is the Lebesgue measure.
- T is finite

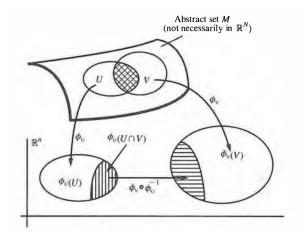
Theorem

For any (Lebesgue) measurable function $f: D \to T$, we have a linear logical function that approximates to f.

Corollary

There exists a family \mathcal{L} of linear logical functions $L_i : D_i \to T$, where $D_i \subset D$ and $L_i \equiv f|_{D_i}$, such that $D \setminus \bigcup_i D_i$ is measure zero set.

Logifold



2

イロト イヨト イヨト イヨト

Logifold

Definition

A linear logifold is a pair (X, U) such that

- X is a set equipped with a σ -algebra and a corresponding measure μ .
- \mathcal{U} is a collection of pairs (U_i, ϕ_i) .
- U_i are subsets of X such that $\mu(U_i) > 0$ and $\bigcup_i U_i = X$.
- ϕ_i are isomorphisms (of measure spaces) between U_i and the graphs of linear logical functions $f_i : D_i \to T_i$.
- $D_i \subset \mathbb{R}^{n_i}$ are a measurable subsets and T_i are finite sets.

・ 同 ト ・ ヨ ト ・ ヨ ト …

Example of logifolds

 $\mathcal{M} \subset \mathbb{R} \times \{0,1\}$

イロト イポト イヨト イヨト

э

Example of logifolds

 $\mathcal{M} \subset \mathbb{R} \times \{0,1\}$

Machine learning on {Logifolds}

э

10/14

イロト 不得 ト イヨト イヨト

Example of logifolds

 $\mathcal{M} \subset \mathbb{R} \times \{0,1\}$

Machine learning on {Logifolds}

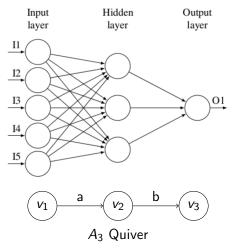
 $? \longrightarrow \{ \mathsf{Logifolds} \}$

Inkee Jung Boston University Evolutions of Logifold Structures on Measure May 28

イロト イヨト イヨト ・

э

- Q : Directed graph
- E(Q) : Arrows of Q
- V(Q) : Vertices of Q



▲ □ ▶ ▲ □ ▶ ▲ □ ▶

Theorem (Nakajima('96), Reineke('08))

Framed quiver moduli space is smooth compact variety.

→

< A > < E

Theorem (Nakajima('96), Reineke('08))

Framed quiver moduli space is smooth compact variety.

Theorem (Lau & Jefferys'21))

Framed quvier moduli space has the natural kähler metric.

A B < A B </p>

Theorem (Nakajima('96), Reineke('08))

Framed quiver moduli space is smooth compact variety.

Theorem (Lau & Jefferys'21))

Framed quvier moduli space has the natural kähler metric.

Framed A_3 moduli space \longrightarrow {Logifolds}.

直 ト イ ヨ ト イ ヨ ト

Theorem (Nakajima('96), Reineke('08))

Framed quiver moduli space is smooth compact variety.

Theorem (Lau & Jefferys'21))

Framed quvier moduli space has the natural kähler metric.

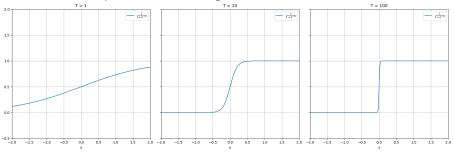
Framed A_3 moduli space \longrightarrow {Logifolds}.

Problem : Trivial gradient

通 ト イ ヨ ト イ ヨ ト

Motivation : Non-archimedean analysis

Introduce formal parameter T to logistic functions.



$$\lim_{T \to \infty} \frac{1}{1 + e^{-T_X}} = \begin{cases} 1 & (x > 0) \\ 0 & (x < 0) \end{cases}$$

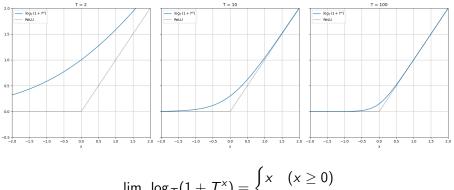
э

12/14

< □ > < □ > < □ > < □ > < □ > < □ >

Motivation : Non-archimedean analysis

Introduce formal parameter T to logistic functions.



$$\lim_{T \to \infty} \log_T (1 + T^x) = \begin{cases} x & (x \ge 0) \\ 0 & (x < 0) \end{cases}$$

3

12/14

イロト 不得 トイヨト イヨト

Motivation : Non-archimedean analysis

Introduce formal parameter T to logistic functions. For T > 1,

•
$$\sigma_T(x) := \frac{1}{1+e^{-Tx}}$$
.

•
$$\operatorname{ReLu}_T(x) := \log_T(1 + T^x).$$

• SoftMax_T(x₁,...,x_n) :=
$$\left(\frac{T^{x_j}}{\sum_i T^{x_i}}: j = 1,...,n\right)$$

• Smooth, non-trivial gradient in each T

$$\frac{\partial \sigma_{T}(x)}{\partial x} = \frac{Te^{Tx}}{(e^{Tx} + 1)^{2}}$$
$$\frac{\partial \text{ReLu}_{T}(x)}{\partial x} = \sigma_{T}(x)$$
$$D\left(\text{SoftMax}_{T}\right) = \left[\log T \cdot (\text{SoftMax}_{T})_{j} \cdot (\delta_{ij} - T^{x_{i}})\right]_{i,j}$$

< f³ ► <

Fuzzy linear logical function and fuzzy linear logifold

Definition

A fuzzy linear logifold is a tuple $(X, \mathcal{P}, \mathcal{U})$, where (X, \mathcal{U}) be a logifold and

- \mathcal{U} is a collection of tuples (ρ_i, ϕ_i, f_i)
- $ho_i: X
 ightarrow [0,1]$ describe fuzzy subsets of X with $\sum_i
 ho_i \leq 1_X$
- $U_i = \{x \in X : \rho_i(x) > 0\}$ be the support of ρ_i

A (1) < A (1) < A (1) </p>

Fuzzy linear logical function and fuzzy linear logifold

Definition

A fuzzy linear logifold is a tuple $(X, \mathcal{P}, \mathcal{U})$, where (X, \mathcal{U}) be a logifold and

- \mathcal{U} is a collection of tuples (ρ_i, ϕ_i, f_i)
- $ho_i: X
 ightarrow [0,1]$ describe fuzzy subsets of X with $\sum_i
 ho_i \leq 1_X$
- $U_i = \{x \in X : \rho_i(x) > 0\}$ be the support of ρ_i

In classification problems,

- $X = \mathbb{R}^n \times T$
- $\mathcal{P}: X \to [0,1]$ describes how likely an element of $\mathbb{R}^n \times \mathcal{T}$ is classified as 'yes'
- *ρ_i* be the 'weight' (or 'certainty') of the corresponding linear logical interpretation.

< ロ > < 同 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ >

Experimental Results : Evolution of fuzzy linear logifolds

Dataset : CIFAR10

Model structures : Version 1 and 2 of ResNet20 and ResNet56

Certainty Threshold	Accuracy	Coverage
0	0.8316 ± 0.0160	1
0.9526		0.6728 ± 0.0507
0.9975	0.8316 ± 0.0160	0.1130 ± 0.0484

Table: Logifold with single chart.

Certainty Threshold	Accuracy	Coverage
0	0.9304	1
0.9526	0.9334	1
0.9975	0.9290	0.6965

Table: Evolved Logifold.