

TRANSVERSE MODULATIONAL DYNAMICS OF QUENCHED PATTERNS

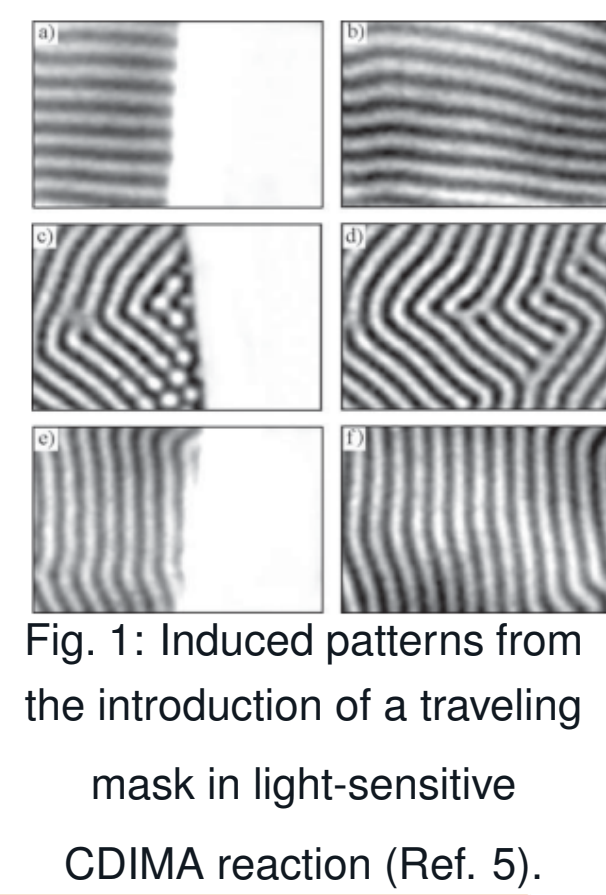
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Abstract and Motivation

We study transverse modulational dynamics of striped pattern formation in the wake of a directional quenching mechanism.

Such mechanisms have been proposed to control pattern-forming systems and suppress defect formation in many different physical settings, such as light-sensing reaction-diffusion equations, solidification of alloys, and eutectic lamellar crystal growth. In the context of two prototypical pattern forming PDEs, the complex Ginzburg-Landau and Swift-Hohenberg equations, we show that long-wavelength and slowly varying modulations of striped patterns are governed by a one-dimensional viscous Burgers' equation, with viscous and nonlinear coefficients determined by the quenched stripe selection mechanism.



Complex Ginzburg-Landau Equation

- Quenched Complex Ginzburg-Landau (CGL) equation with $\xi = x - ct$

$$A_t = (1 + i\alpha)(\partial_\xi^2 + \partial_y^2)A + cA_\xi + \chi(\xi)A - (1 + i\gamma)A|A|^2$$

$$A \in \mathbb{C}, \quad (x, y) \in \mathbb{R}^2, \quad \alpha, \gamma \in \mathbb{R}$$

- Quenching mechanism $\chi(\xi) = -\text{sign}(\xi)$, controls stability of $A \equiv 0$.

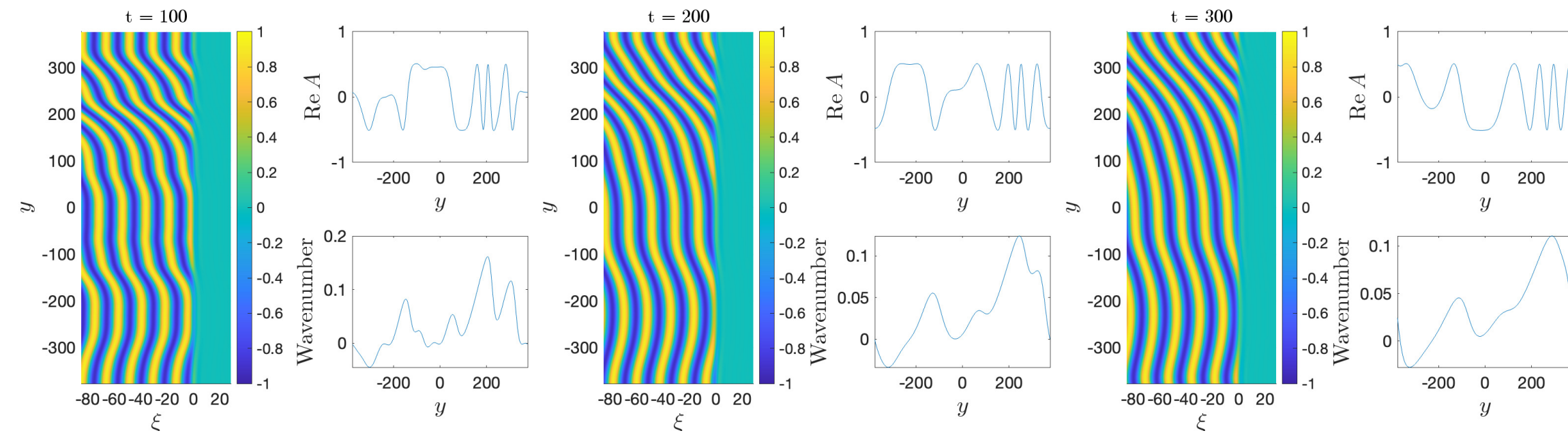


Fig. 2: Evolution of 2D quenched pattern in (ξ, y) variables with $\alpha = 3, \gamma = 1, c = 2.5$, from small random initial data.

- Pure stripes $re^{i(k_x\xi + k_y y - \omega t)}$, have nonlinear dispersion relation

$$r^2 = 1 - (k_x^2 + k_y^2), \quad \omega(k_x, k_y) = (\alpha - \gamma)(k_x^2 + k_y^2) - ck_x + \gamma$$

- Stripe-forming front solutions

$$A(\xi, y, t) = e^{i(k_y y - \omega t)} A_f(\xi; c, k_y)$$

- Travelling wave eqn. with asymptotic boundary conditions

$$0 = (1 + i\alpha)(\partial_\xi^2 - k_y^2)A_f + cA_{f,\xi} + (\chi(\xi) + i\omega)A_f - (1 + i\gamma)A_f|A_f|^2$$

$$0 = \lim_{\xi \rightarrow -\infty} \left| A_f(\xi) - re^{ik_x \xi} \right|, \quad 0 = \lim_{\xi \rightarrow +\infty} A_f(\xi)$$

- Fronts with $k_y = 0$ exist (Ref. 3) for $c \lesssim 2\sqrt{1 + \alpha^2}$.

- $k_y \neq 0$ is a regular perturbation, so fronts generically persist. ω and k_x are selected by c and k_y .

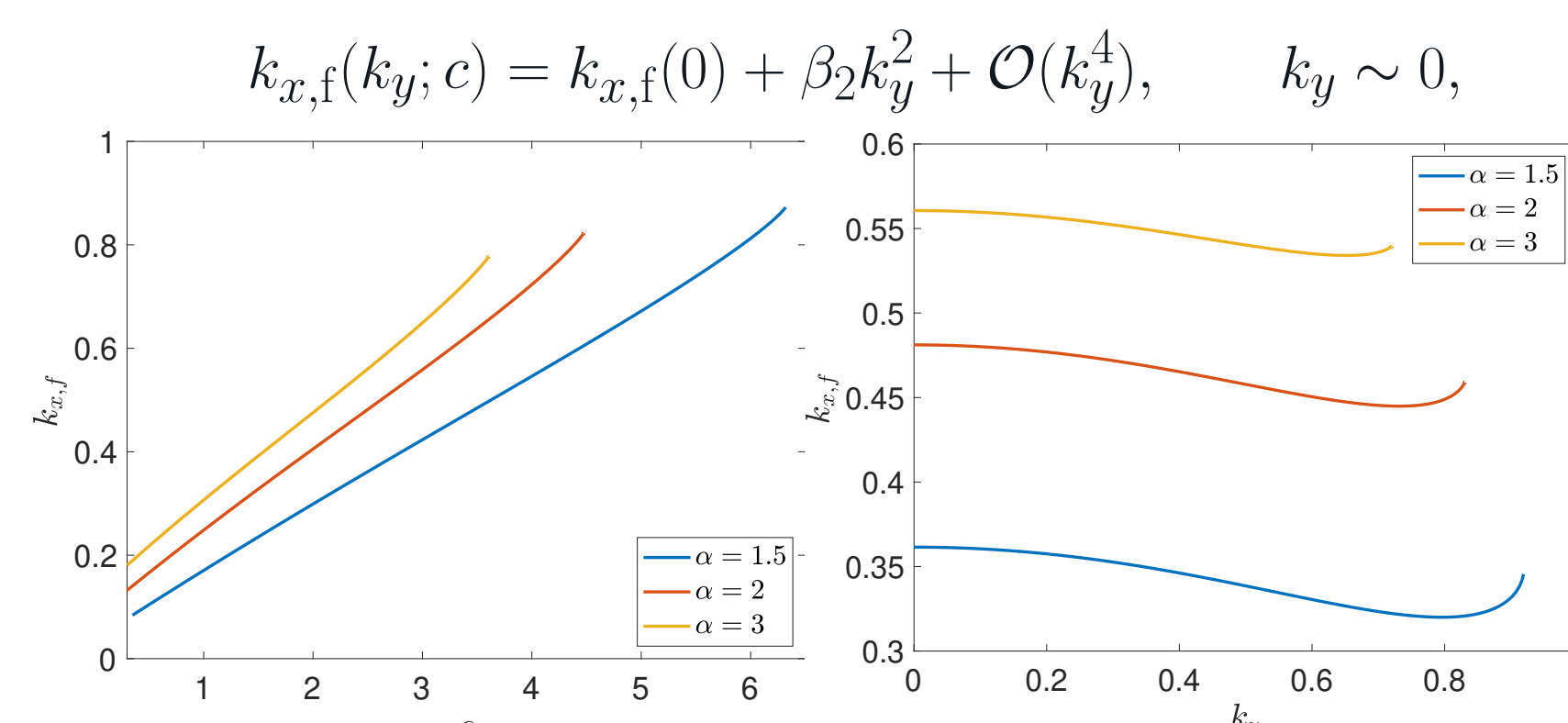


Fig. 3: Wave number selection curves with $\gamma = 1$ and $\alpha = 1.5, 2, 3$.

Slow Transverse Modulations

- Slowly-varying transverse phase modulation function $\Phi(Y, T)$ with slow variables $Y = \delta y, T = \delta^2 t$ for some small parameter $0 < \delta \ll 1$.

$$A(\xi, y, t) = e^{i(\Phi(Y, T) - \omega_f t)} \left[A_f(\xi; \delta\Phi_Y(Y, T)) + \delta^2 w_1(\xi, Y, T; \delta) \right].$$

- Fix $\xi = \xi_0$ directly behind quench with $-1 \leq \xi_0 < 0$.

- Expand and collect $\mathcal{O}(\delta^2)$ terms. Solvability condition gives a viscous Burgers' equation for slowly-varying transverse wave number modulation $\Psi := \partial_Y \Phi$

$$\Psi_T = \frac{\lambda_{\text{lin}}''(0)}{2} \Psi_Y Y + \frac{\omega_f''(0)}{2} (\Psi^2)_Y$$

- $\lambda_{\text{lin}}''(0) \approx 2(1 + \alpha\gamma)$ and $\omega_f''(0)$ given by

$$\partial_{k_y}^2 \omega_f(0) = 2(\alpha - \gamma) + \partial_{k_y}^2 k_{x,f}(0) (2(\alpha - \gamma)k_{x,f}(0) - c)$$

Example: Source-Sink Transverse Defect Pair

- Small transverse wave number $k_{y,+} = \delta q_+$ for $y > 0$ and $k_{y,-} = \delta q_-$ for $y < 0$, with $0 < \delta \ll 1$ and $q_\pm = \mathcal{O}(1)$.

$$A(\xi, y, 0) = h(-\xi) \left(h(y) r_- e^{i(k_x \xi - \xi + k_y y - y)} + h(-y) r_+ e^{i(k_x \xi + \xi + k_y y + y)} \right)$$

- Wave numbers $k_{x,\pm}$ chosen so that $k_{x,\pm} = k_x(k_{y,\pm}), r_\pm^2 = \sqrt{1 - (k_{x,\pm}^2 + k_{y,\pm}^2)}$.

- Defect speed determined by $c_{\text{dl}} = c_{g,0} + \delta c_* = \delta \frac{\omega_f''(0)}{2} (q_- + q_+)$

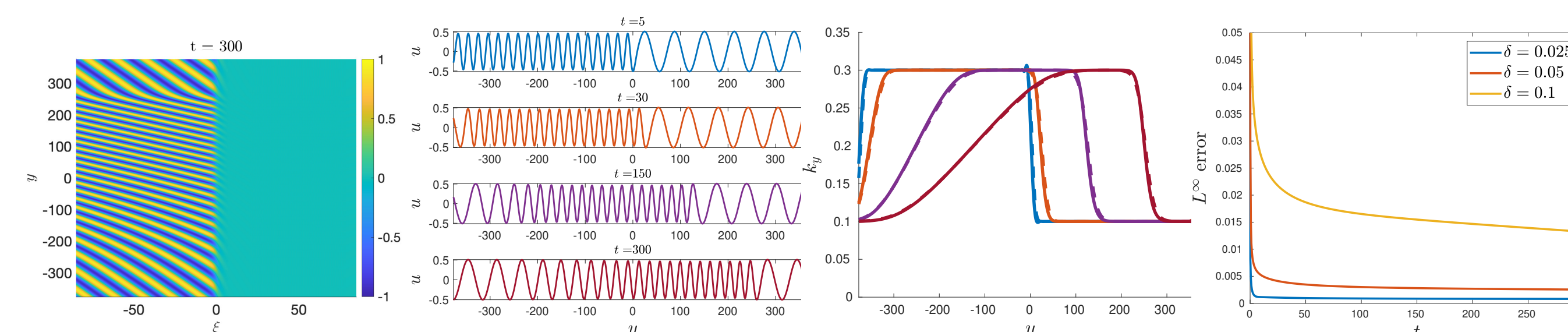


Fig. 4: Source-sink defect pair with $\alpha = 3, \gamma = 1, c = 2.5$ obtained from initial condition which connects stripes solutions with transverse wave numbers $k_{y,-} = 0.3, k_{y,+} = 0.1$ and $\delta = 0.1$; Local wave number measured as $\psi(y, t) = \text{Im} A_y(\xi_0, y, t) / A(\xi_0, y, t)$.

Example: Phase-Slip Defect Modulation

- Localized defect with $\phi_0(Y) = \pi \text{erf}(Y)$ and $\text{erf}(Y) = 2\pi^{-1/2} \int_0^Y e^{-t^2} dt$

$$A(\xi, y, 0) = h(-\xi) \sqrt{1 - k^2} \exp[i(k_x \xi + \delta y + \phi_0(\delta y))]$$

- Choose transverse wave number $k_y = \delta$ so that

$$\Psi(Y) = 1 + 4\pi^{1/2} e^{-Y^2}$$

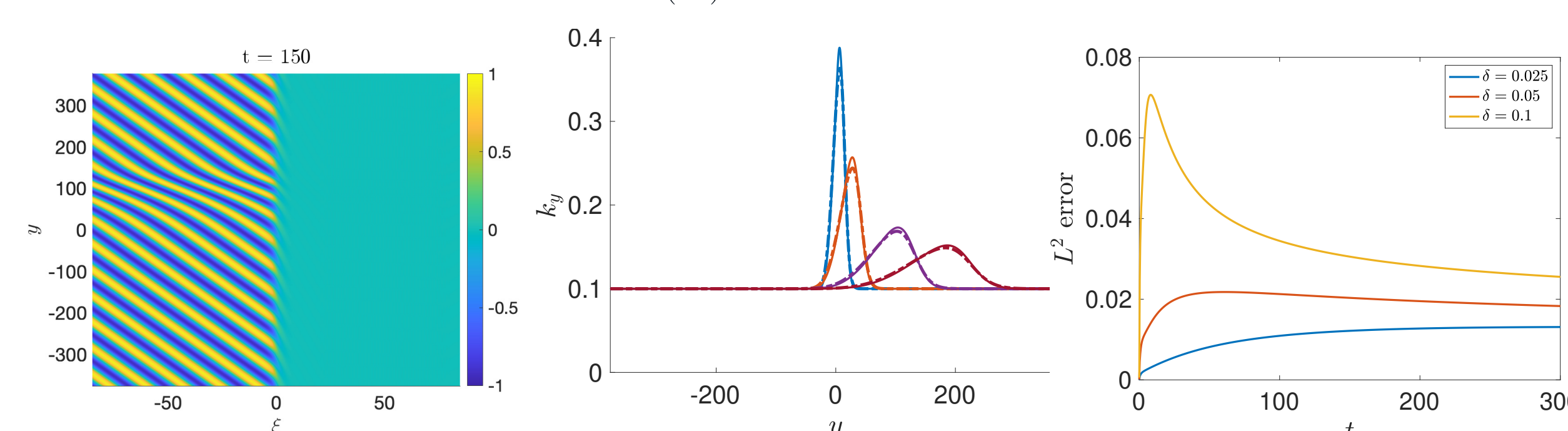


Fig. 5: Top row: Localized phase-slip defect solution of with $c = 2.5, \alpha = 3, \gamma = 1$ and $\delta = 0.1$ as well as L^2 error.

Swift-Hohenberg Equation

- Swift-Hohenberg Equation in co-moving frame

$$u_t = -(1 + \partial_\xi^2 + \partial_y^2)u + c\partial_\xi u + \mu\chi(\xi)u - u^3, \quad \mu > 0$$

- Front solutions $u_f(\xi, k_y y + \omega t)$, periodic in $\zeta := k_y y + \omega t$ exist (Ref. 4), solve

$$0 = -(1 + \partial_\xi^2 + k_y^2 \partial_\zeta^2)u_f + (c\partial_\xi - \omega\partial_\zeta)u_f + \mu\chi(\xi)u_f - u_f^3$$

- Striped fronts perturb smoothly for $k_y \sim 0$ and

$$k_{x,f}(k_y) = k_{x,f}(0) + \beta_2 k_y^2 + \mathcal{O}(k_y^4), \quad \beta_2 = \frac{1}{c} \langle 2\partial_\xi^2 (1 + \partial_\xi^2) u_f(\cdot, \cdot; 0), e_* \rangle_{L^2_\eta}$$

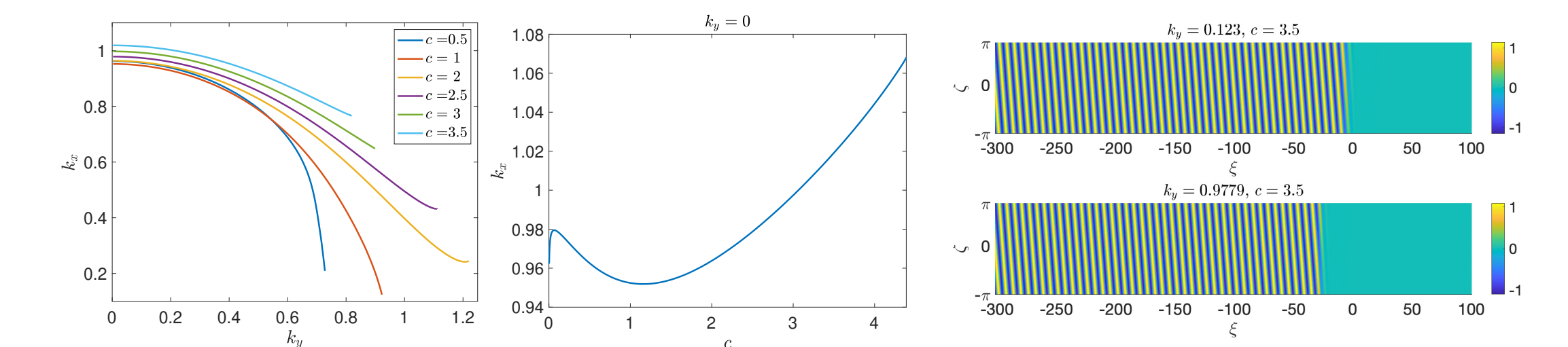


Fig. 6: Swift-Hohenberg wave number selection curves for $\mu = 1$, depicting $k_x(c, k_y)$ for c fixed, and k_y varied, then $k_y = 0$ fixed and c varied; Example front profiles $u_f(\xi, \zeta; k_y)$ with $c = 3.5$ and $k_y = 0.123, 0.9779$; $\mu = 1$.

- Bloch wave theory and concavity of k_y in k_x imply

$$\lambda_{\text{lin}}''(0) = \langle 4(1 + (k_x \partial_z)^2) \partial_z u_f, b_* \rangle_{L^2(\mathbb{T}_{2\pi})}, \quad \omega_f''(0) = 2\beta_2 c$$

- Phase-slip initial condition $u(\xi, y, 0) = \sqrt{4\mu/3} \cos(k_x x + k_y y + \phi_0(\delta y)) h(-\xi)$

- Numerical wave number measurements from Iterative Hilbert Transform; Gibbs-type oscillations in shocks

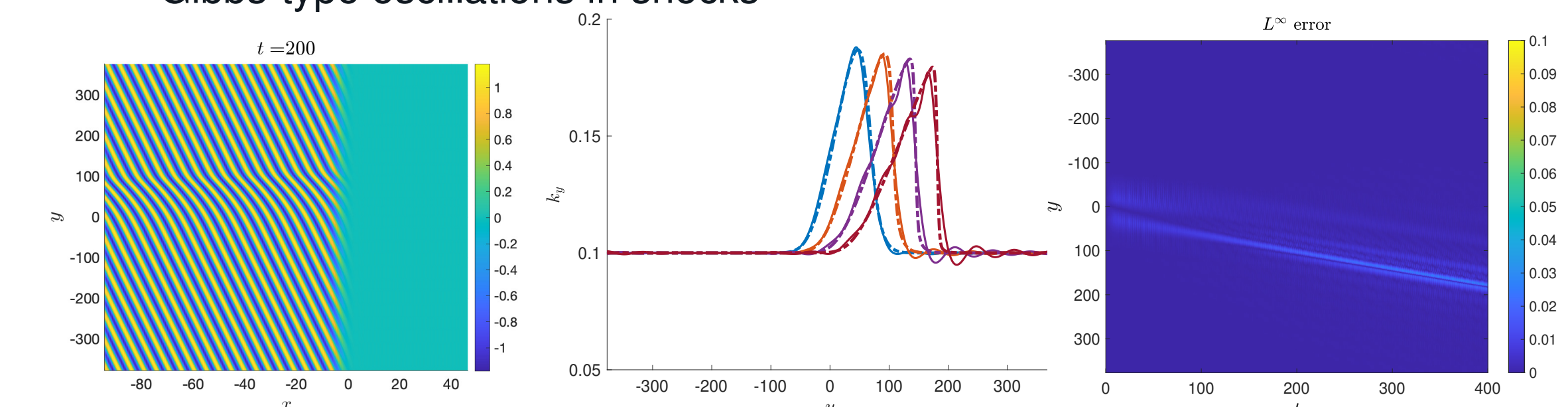


Fig. 7: Localized phase perturbation of striped front with $(k_x, k_y) = (0.993, 0.1)$; $c = 3, \mu = 1$; Transverse wave number dynamics at $\xi = \xi_0 = -1$ fixed (solid) plotted against rescaled viscous Burgers' solution at times $t = 100$ (blue), 200 (orange), 300 (purple), 400 (red); plot of absolute error.

Future Work

- Far-field dynamics and behavior
- Rigorous approximation arguments
- Effect of domain geometry on pattern growth

References & Acknowledgements

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